

MA 401
114



Ref: (i) linear algebra: Hoffman & Kunze
(ii) linear algebra: S. Lang
(iii) linear algebra: P. Lax

Eval: 2 quizzes (cup)
midsem
endsem

29th July: vector spaces
 $M_{n \times n}(\mathbb{C})$ - Algebra

examples where: ① Markov's matrix ② $n \times n(\mathbb{C})$ group
 lin alg. pop up: ② adjacent matrix $\rightarrow$ see my mb

* gaussian method:

$Ax = b$ we have to solve for x . $\left. \begin{matrix} \text{3 planes} \\ \downarrow \\ \text{intersection point} \end{matrix} \right\} \mathbb{R}^3$

$$\begin{cases} x_1 + 3x_2 + x_3 = 2 \\ x_1 + 8x_2 + x_3 = 12 \\ 4x_2 + x_3 = 2 \end{cases}$$

coeff. matrix $A = \begin{bmatrix} 1 & 3 & 1 \\ 1 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix}_{3 \times 3}$ $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}_{3 \times 1}$ $b = \begin{bmatrix} 2 \\ 12 \\ 2 \end{bmatrix}_{3 \times 1}$

$Ax = \{x_1 c_1 + x_2 c_2 + x_3 c_3; \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3\}$
 column vector if $b \in Ax$ then there is a soln.
 column space (thrust)

Elementary Row operations:

1. Multiply non-zero scalar to row.
2. Multiply non-zero scalar to a row and add/mult row.
3. Interchange rows.

pivot $\begin{bmatrix} 1 & 3 & 1 \\ 1 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix} \xrightarrow{R'_2 = R_2 - R_1} \begin{bmatrix} 1 & 3 & 1 \\ 0 & 5 & 0 \\ 0 & 4 & 1 \end{bmatrix} \xrightarrow{R'_3 = R_3 - \frac{4}{5}R_2} \begin{bmatrix} 1 & 3 & 1 \\ 0 & 5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$\begin{bmatrix} 1 & 3 & 1 & | & 2 \\ 1 & 8 & 1 & | & 12 \\ 0 & 4 & 1 & | & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 1 & | & 2 \\ 0 & 5 & 0 & | & 10 \\ 0 & 4 & 1 & | & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 1 & | & 2 \\ 0 & 5 & 0 & | & 10 \\ 0 & 0 & 1 & | & -6 \end{bmatrix}$$

note: $\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix}_{1 \times 3} \begin{bmatrix} R_1 \\ R_2 \\ R_3 \end{bmatrix}_{3 \times 3} = x_1 R_1 + x_2 R_2 + x_3 R_3$
 $u x = b'$ $x_3 = -6$
 $5x_2 = 10 \Rightarrow x_2 = 2$
 $x_1 + 3x_2 + x_3 = 2 \Rightarrow x_1 = 2$

$\begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{bmatrix} \begin{bmatrix} R_1 \\ R_2 \\ R_3 \end{bmatrix}$ we, $\begin{bmatrix} 1 & 3 & 1 \\ 0 & 5 & 0 \\ 0 & 4 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 1 \\ 0 & 5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
 by $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$\begin{bmatrix} 1 & 3 & 1 \\ 0 & 5 & 0 \\ 0 & 4 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 1 \\ 0 & 5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ by:

$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -4/5 & 1 \end{bmatrix}$ and then $\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
 see E_{ij} matrices

* invertible: $AB = BA = I$ (Def'n) $\rightarrow$ see

$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I$ if $Ax = b$
 $\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I$
 P_{12} P_{12}
 see perm. matrix
 not solvable as $x_3 \cdot 0 = c_3$
 x_3 can be anything

now $Ax = b$
 $\dots E_2 E_1 A = u$
 $EA = u$

so $\underbrace{EA}_{u} x = u \quad x = Eb = b'$

Note: $Ax = b$
 $u x = b'$
 $\Leftrightarrow EAx = Eb$
 $\Leftrightarrow Ax = b$
 so, $u x = b'$
 $\Leftrightarrow Ax = b$

1st Aug:

$$A \in M_{n \times n}(\mathbb{C})$$

$$EA = U \leftarrow \text{upper triangular matrix}$$

$\hookrightarrow$ we left multiply by

$E_{ij}(\lambda)$ matrices or P_{ij} matrices.

$\} \rightarrow$ see notes (all linear algebra till midsem)

$$\begin{bmatrix} 1 & 0 & 0 \\ -\alpha & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2' = R_2 - \alpha R_1} E_{21}(-\alpha) = \begin{bmatrix} 1 & 0 & 0 \\ -\alpha & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_1 \leftrightarrow R_2 \\ P_{12} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = E^{-1}U \\ L \ U \text{ where } E^{-1} = L$$

Remark: If there is no row exchange in elimination process for A then we can write $A = LU$

$$\text{as } (E_{21}(\lambda))^{-1} = (E_{21}(-\lambda)) \\ \text{Always } L$$

$$\text{Now: } A \in M_{m \times n}(\mathbb{C}), m < n$$

$$\text{eg: } m=3 \ n=4$$

$$U = \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad Ux = 0$$

2 pivots

$$m \begin{bmatrix} n \\ n \end{bmatrix}$$

also $Ax = 0$ (Homogeneous equation)

$$\begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = 0$$

$$x = \begin{pmatrix} -2x_2 - 2x_4 \\ x_2 \\ -3x_4 \\ x_4 \end{pmatrix} = x_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 0 \\ -3 \\ 1 \end{pmatrix}$$

Note: In such a case we will always get a non-trivial solution.

$$\begin{cases} x_1 = -2x_2 - 2x_4 \\ x_3 = 0x_2 - 3x_4 \end{cases} \quad \left. \begin{matrix} x_1, x_3 \text{ are linear comb of} \\ x_2, x_4 \end{matrix} \right\} \rightarrow \text{soln is linear comb of } x_2 \text{ and } x_4$$

(max 3 pivots
4 variables)

Theorem: Let A be a $n \times n$ matrix.

Then A is invertible iff $Ax = 0$ has a unique soln.

Proof: $\Leftarrow$ Let U be the row-reduced Echlon form of A . Then the system $UX = 0$, also has a unique solution.

If r is the number of pivots (or number of non-zero rows) in U , then

$$r = n \\ \text{i.e. } \underbrace{\text{no. of pivots}}_{\text{no. of non-zero rows}} = \text{no. of rows}$$

Since every row of U has non-zero element,

$$U = I \Rightarrow A = E^{-1}U \\ \Rightarrow A \text{ is invertible}$$

$(\Rightarrow)$ A is nullible

$$\begin{aligned} Ax &= 0 \\ \Rightarrow x &= A^{-1} \cdot 0 \\ \Rightarrow x &= 0 \text{ (unique soln)} \end{aligned}$$

Defⁿ: A vector space V over a field F is a set equipped with the operations:

- (i) $\alpha + \beta \in V, \alpha, \beta \in V$
- (ii) $c\alpha \in V, c \in F, \alpha \in V$

s.t

- (i) $(V, +)$ is commutative group
- (ii) $1 \cdot \alpha = \alpha, \forall \alpha \in V$
- (iii) $c_1(c_2\alpha) = (c_1c_2)\alpha, \forall c_1, c_2 \in F, \alpha \in V$
- (iv) $(c_1 + c_2)\alpha = c_1\alpha + c_2\alpha, \forall c_1, c_2 \in F, \alpha \in V$
- (v) $c(\alpha + \beta) = c\alpha + c\beta, \alpha, \beta \in V, c \in F$

$\} \rightarrow$ See this properties carefully

Ex^{mp}: U, W are vector spaces over F , then $U \times W = \{(u, w) \mid u \in U, w \in W\}$ is a vector space.

Example of vector spaces:

③ $Ax=b$
 $b \neq 0$
 solution space
 (Non Example)

- (i) $\mathbb{R}^2$
- (ii) $\mathbb{R}^n$
- (iii) $M_{m \times m}(\mathbb{C})$
- (iv) $\{f: \mathcal{L} \rightarrow F\}$

Non-Example: $\mathbb{Q}$ over $\mathbb{R}$

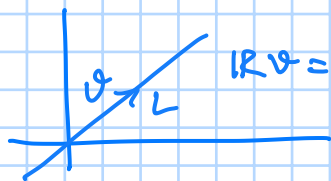
as $\alpha \notin \mathbb{Q}$ when $\zeta \in \mathbb{R}$
 and $\alpha \in \mathbb{Q}$
 ② $x=2, y \in \mathbb{R}$ $(2, y)$ not a vector space.

is a vector space over F .
 $(f+g)(s) = f(s) + g(s) \quad \forall s \in \mathcal{L}$
 $(\alpha f)(s) = \alpha \cdot f(s), \quad \forall s \in \mathcal{L}, \alpha \in F$

(v) $P_n(x) = \{a_0 + a_1x + \dots + a_nx^n \mid a_i \in F\}$ is also a vector space.

(vi) $\{x \in \mathbb{C}^n \mid Ax=0\} = N(A) = \text{null space}$

Defⁿ: Let V be a vector space over F . A subset W of V is a subspace of V if W is a vector space with respect to the operations borrowed from V .



$$\mathbb{R}^2 = \{xv \mid x \in \mathbb{R}\}$$

- ① $c_1v + c_2v \in \mathbb{R}v$
- ② $0 \in \mathbb{R}v$
- ③ if $0 \in \mathbb{R}v$
 $-v \in \mathbb{R}v$

Theorem: Let W be non-empty subset of a vector space V over F , then W is a subspace iff

$$c\alpha + \beta \in W, \quad \forall c \in F \text{ and } \alpha, \beta \in W$$

($\Rightarrow$) Trivial (as W is a subspace $c\alpha + \beta \in F$ is true)

($\Leftarrow$) since $0 = (-\alpha) + (\alpha)$, then $0 \in W$

for $\alpha \in W$, $-\alpha = (-1)(\alpha) + 0 \in W$

so $-\alpha \in W$

also for $\alpha, \beta \in W$,

for $c=1$

$$\alpha + \beta \in W$$

and for $\forall c \in F, \beta = 0 \in W$

$$c\alpha \in W$$

Thus W is a vector space.

for $v_1, v_2, \dots, v_n \in V$ over F , we say $\beta \in V$ is a linear combination of $v_1, v_2, \dots, v_n$ if $\exists c_1, c_2, \dots, c_n \in F$ s.t. $\beta = c_1v_1 + \dots + c_nv_n = \sum_{i=1}^n c_iv_i$

ex¹:

V, W are vector spaces over F , then $V \times W = \{(v, w) \mid v \in V, w \in W\}$ is a vector space.

given V, W are vector spaces.

$$\text{then } V \times W = \{(v, w) \mid v \in V, w \in W\}$$

now for $(\alpha v, \alpha w) \in V \times W$

and $(\beta v, \beta w) \in V \times W$

$$(\alpha v + \beta v, \alpha w + \beta w) \in V \times W$$

as both $\alpha v + \beta v \in V$
 & $\alpha w + \beta w \in W$

also $c(\alpha_v, \alpha_w) = (c\alpha_v, c\alpha_w) \in V \times W$

as $c\alpha_v \in V$
and $c\alpha_w \in W$

8th Aug:

Defn: Let S be a set of vectors in V . Then the span of S is the intersection of all subspaces of V which contains S .

Theorem: Let S be a set of vectors in V , Then $\text{Span } S = \left\{ \sum_{i=1}^n c_i v_i \mid n \in \mathbb{N}, c_i \in F, v_i \in S \right\}$
ex proof of $\text{Span}\{x_1, x_2, \dots, x_n\} = \left\{ \sum_{i=1}^n c_i x_i \mid n \in \mathbb{N}, c_i \in F \right\}$

Defn: A collection of vectors $x_1, x_2, \dots, x_n$ is linearly dependent if $\sum_{i=1}^n \alpha_i x_i = 0$

Defn: The collection is linearly independent if it is not dependent for some choices of α_i 's s.t. not all zero.
 $\sum_{i=1}^n \alpha_i x_i = 0 \iff \alpha_1 = \alpha_2 = \dots = \alpha_n = 0$

Examples: (i) $\{x_1 = 0, x_2, \dots, x_n\}$ dependent as $\nexists \alpha_i \neq 0$ and $\alpha_i = 0, i \geq 2$
 $\alpha_1(x_1) + 0 = 0$
as $x_1 = 0$

NOTE: A set of vectors S is independent if any finite (non-empty) subset of S is independt.

(ii) Two vectors are dependent x_1, x_2

$\iff x_1 = \lambda x_2$ for some $\lambda \in F$
or
 $x_2 = \beta x_1$ for some $\beta \in F$

proof: ($\Rightarrow$) if x_1, x_2 are dependent, then $\exists \alpha_1, \alpha_2 \in F$ s.t. not both zero.
 $\alpha_1 x_1 + \alpha_2 x_2 = 0$

if $\alpha_1 \neq 0$ then $x_1 = -\frac{\alpha_2}{\alpha_1} x_2$

if $\alpha_2 \neq 0$ then $x_2 = -\frac{\alpha_1}{\alpha_2} x_1$

eg: $F(x) = \{f: \mathbb{R} \rightarrow \mathbb{R}\}$

$\{1, x, \dots, x^n\}$ lin ind.

($\Leftarrow$) if $x_1 - \lambda x_2 = 0$
then $\exists \alpha_1, \alpha_2 \in F$ not both zero s.t.
 $\alpha_1 x_1 + \alpha_2 x_2 = 0$

(iii) Any finite superset of a dependent collection of vectors is dependent.

proof: $\{x_1, x_2, \dots, x_n\}$ $\sum_{i=1}^n \alpha_i x_i = 0$
 $\{x_1, x_2, \dots, x_n, y_n, y_{n+1}, \dots\}$
 $\sum_{i=1}^n \alpha_i x_i + \underbrace{\sum 0 \cdot y_{n+1}}_0 = 0$
 $\therefore$ dependent.

(iv) Subset of a finite collection of independent vectors is independent again.

proof: $\neg(\text{finite superset of dep} \Rightarrow \text{fin sub dep})$

$\neg(\text{fin sub dep}) \Rightarrow \neg(\text{fin superset dep})$
 $\text{fin set independent} \Rightarrow \text{fin subset independent}$

Defⁿ: A set of vector S in a vector space X is a basis if

(i) $\text{span } S = X$

(ii) S is linearly independent

$$\text{span } S = \left\{ \sum_{i=1}^n \alpha_i x_i \mid x_i \in S, \alpha_i \in F \right\}$$

$$S = \{x_1, x_2, \dots, x_n\}$$

$$x = \sum_{i=1}^n \alpha_i x_i = \sum_{i=1}^n \beta_i x_i$$

$$\Rightarrow \alpha_i = \beta_i \quad (\text{as lin independent})$$



we can choose any other u then v
 then: $\{u, v\}$ is a basis

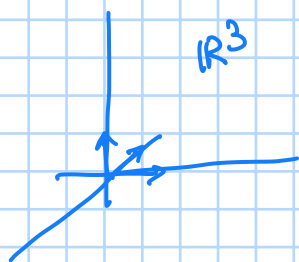
- ① $\text{span } \{u, v\} = \mathbb{R}^2$
- ② $\{u, v\}$ are lin ind.

as $\alpha v + \beta u$ will give any vector in $\mathbb{R}^2$.

$\{(1,0), (0,1)\}$ is a basis of $\mathbb{R}^2$

$\{u, v, w\}$ is not a basis of $\mathbb{R}^2$: as w can be expressed

$$\text{as } \alpha u + \beta v \\ w - \alpha u - \beta v = 0 \\ \therefore \text{dependent}$$



$$\{(x_1, x_2), (x_3)\}$$

Plane if x_3 is a line on plane then $\text{span} \neq \mathbb{R}^3$

lemma: If $\text{span } \{x_1, \dots, x_n\} = X$ and if $\{y_1, \dots, y_m\}$ is linearly independent in X then $m \leq n$.

proof: $y_1 = \sum_{i=1}^n \alpha_i x_i, \alpha_i \in F$

one of the $\alpha_i \neq 0$ as $y_1 \neq 0$.
 without any loss of generality let $\alpha_1 \neq 0$

$$x_1 = \frac{y_1}{\alpha_1} - \sum_{i=2}^n \alpha_i x_i$$

claim $\{y_1, x_2, \dots, x_n\} = X$

any $x \in X$

$$x = \sum_{i=1}^n \beta_i x_i \quad x_1 = \frac{1}{\alpha_1} y_1 - \sum_{i=2}^n \alpha_i x_i$$

so x can be expressed as l.c of $\{y_1, x_2, x_3, \dots, x_n\}$

repeat again to get:

$$y_2 = y_1 + \sum_{i=2}^n \beta_i x_i$$

$\text{span}\{y_1, y_2, x_3, \dots, x_n\} = X$
again to get:

$$\text{span}\{y_1, y_2, y_3, \dots, y_n\} = X$$

some of $\beta_i \neq 0$
as if all zero
 $y_2 = \beta_1 y_1$ (not possible)

now if $m > n$,

then some n in $\{y_1, y_2, \dots, y_m\}$

let it be $\{y_1, y_2, \dots, y_n\}$ also lin ind.

$$\text{as } \text{span}\{y_1, y_2, \dots, y_n\} = X$$

One more element here should still make the span lin ind.

But it would be lin dep. $\therefore$
 $m \leq n$

12th Aug:

Lemma: let $\{a_1, \dots, a_n\}$ be a spanning set of vector space X . Then any l.i. set of vectors $\leq$ to n -elements.

proof: let $\{x_1, x_2, \dots, x_m\}$ be l.i. in X , suppose $m > n$.

as $x_i \in X \forall i=1, 2, \dots, m$
and $\{a_1, a_2, \dots, a_n\}$ span X

$$x_i = \sum_{j=1}^n \alpha_{ij} a_j, \forall i=1, 2, \dots, m$$

$$\text{Take } \sum_{i=1}^m \beta_i x_i = \sum_{i=1}^m \beta_i \sum_{j=1}^n \alpha_{ij} a_j = \sum_{j=1}^n \left(\sum_{i=1}^m \alpha_{ij} \beta_i \right) a_j \quad \rightarrow \text{see}$$

$$\sum_{i=1}^m \alpha_{ij} \beta_i = 0, \forall j=1, 2, \dots, n$$

$$\sum_{i=1}^m \alpha_{ij} x_i = 0 \text{ as } n < m$$

(*) can be made 0 by non-trivial choice of β_i 's.

this implies $\{x_1, \dots, x_m\}$ is l.i. $\neq$

Defⁿ: A vector space is finite dimensional if it has a basis consist of finitely many vectors.

Theorem: In a finite dimensional vector space any basis has same number of elements.

proof: let A, B be two basis of X with $\#A, \#B$ cardinality from prev lemma

$$\begin{aligned} \#A &\leq \#B \text{ as } B \text{ is spanning set} \\ \#B &\leq \#A \text{ as } A \text{ is spanning set.} \end{aligned}$$

$$\Rightarrow \#A = \#B$$

$$\begin{aligned} \therefore \text{cardinality of } A &= \text{cardinality of } B \\ \dim X &= \text{cardinality} \\ &= \#A \\ &\hookrightarrow A \text{ is a basis} \end{aligned}$$

Theorem: (i) Any subspace of a finite dimensional vector space is finite dimensional

(ii) There exist a subspace Z of X s.t. $Y \cap Z = \{0\}$
and

$$X = Y + Z = \{y+z \mid y \in Y, z \in Z\}$$

$$\Rightarrow \dim(X) = \dim(Y) + \dim(Z)$$

proof (i) if $\{y_1, y_2, \dots, y_n\}$ l.i. ind in Y . Then by "the lemma"
 $\leq \dim X$

also by tutorial problem (2.4), $\dim Y \leq \dim X \rightarrow \text{see}$

(ii) let $\{y_1, y_2, \dots, y_m, z_1, z_2, \dots, z_n\}$ be a basis of X .

vectors added to Y to make a basis of X .

$$\text{let } Z = \text{span} \{z_1, z_2, \dots, z_n\}$$

$$Y = \text{span} \{y_1, y_2, \dots, y_m\}$$

$$X = \text{span} \{y_1, y_2, \dots, y_m, z_1, z_2, \dots, z_n\}$$

$$Z \cap Y = \{ \cdot \}$$
 as if $x \in Z \cap Y$

$$\Rightarrow x \in Z \text{ and } x \in Y$$

but since $\text{span}(Y) = \sum_{i=1}^m c_i y_i = x$

$$\text{span}(Z) = \sum_{i=1}^n c'_i z_i = x$$

$$\text{so } x \in \text{span}(Y)$$

$$\text{and } x \in \text{span}(Z)$$

$$\sum_{i=1}^m \alpha_i y_i - \sum_{j=1}^n \beta_j z_j = 0$$

$$\text{as } \sum_{j=1}^n \beta_j z_j = \sum_{i=1}^m \alpha_i y_i \quad *$$

$$\Rightarrow \alpha_i = \beta_j = 0 \quad \forall i, j$$

$$\therefore Z \cap Y = \{ \cdot \}$$

$$\text{for any } \alpha \in X, \alpha = \text{span} \{y_1, y_2, \dots, y_m, z_1, z_2, \dots, z_n\}$$

$$= \sum c_i y_i + \sum c'_j z_j$$

$$\alpha = y' + z'$$

$$\Rightarrow X = Y + Z$$

$$\text{also } \dim X = \# \{y_1, y_2, \dots, y_m, z_1, z_2, \dots, z_n\}$$

$$\# X = m + n = \# Y + \# Z$$

$$\dim X = \dim Y + \dim Z$$

If $X_1, X_2, \dots, X_n$ are subspaces of X

then

$$X_1 + X_2 + \dots + X_n = \left\{ x_1 + x_2 + \dots + x_n \mid x_i \in X_i \right\}$$

if pairwise disjoint:

$$\dim(X_1 + X_2 + \dots + X_n) = \sum_{i=1}^n \dim(X_i)$$

Note: Y - subspace of X

$$\text{defn: } x_1 \equiv x_2 \pmod{Y} \Leftrightarrow x_1 - x_2 \in Y$$

Ex: Show that congruence modulo Y defines an equivalence relation in X . $\rightarrow$ do

Claim: $[x] = x + Y = \{x + y \mid y \in Y\}$

equivalence class

all elements equivalent to x

as for

$$\begin{aligned} x' &\in [x] \\ x' &= x + y \text{ for some } y \in Y \\ x' - x &= y \in Y \\ \therefore x' &\equiv x \pmod{Y} \end{aligned}$$

also if $z \equiv x \pmod{Y}$

$$\Rightarrow z - x \in Y$$

$$\Rightarrow z - x = y, \text{ for some } y \in Y$$

$$\Rightarrow z = x + y$$

$$\Rightarrow z \in [x]$$

Define: (i) $(x_1 + Y) + (x_2 + Y) = (x_1 + x_2) + Y$

(ii) $\alpha(x + Y) = \alpha x + Y$

$$X/Y = \{x + Y \mid x \in X\} \text{ becomes a vector space}$$

Theorem: let Y be a subspace of finite dimensional space X .

then $\dim(X/Y) = \dim(X) - \dim(Y)$

proof: let $\{y_1, y_2, \dots, y_m\}$ be basis of Y .
and let

$\{x_1, x_2, \dots, x_n, y_1, y_2, \dots, y_m\}$ be basis of X .

now

$\{x_i + Y \mid i = 1, 2, \dots, n\}$ forms a basis for X/Y
then we are done

① spans X/Y

② lin ind

lin ind: if we take linear combination then

$$\sum_{i=1}^n \alpha_i (x_i + Y) = 0 + Y$$

$$\Rightarrow \sum_{i=1}^n (\alpha_i x_i + Y) = 0 + Y$$

$$\Rightarrow \sum_{i=1}^n \alpha_i x_i + Y = 0 + Y$$

$$\Rightarrow \sum_{i=1}^n \alpha_i x_i - 0 \in Y$$

$$\Rightarrow \sum_{i=1}^n \alpha_i x_i \in Y$$

then $\sum_{i=1}^n \alpha_i x_i = \sum_{j=1}^m \beta_j y_j = y$

if non-zero then they don't form basis of X

$$\Rightarrow y = 0$$

$$\Rightarrow \sum_{i=1}^n \alpha_i x_i = 0 \Rightarrow \alpha_i = 0, \forall i \in 1, 2, \dots, n$$

(subset of lin ind set)

$\therefore$ lin ind

$$\text{spans } X/Y : \{x_i + y \mid i=1, 2, \dots, n\}$$

for any $x \in X$,

$$x = \sum_{i=1}^n \alpha_i x_i + \sum_{j=1}^n \beta_j y_j$$

$$x + y = \sum_{i=1}^n \alpha_i x_i + y$$

$$x + y = \sum \alpha_i (x_i + y)$$

any $x + y$ can
be written as
lin comb of $x_i + y$

$\therefore$ spans X/Y

$$\therefore \dim(X/Y) = \dim X - \dim Y$$

19th Aug: correction: X -vector space
 $x_1, x_2, \dots, x_n \in X$

subspaces of X

$$\dim(x_1 \oplus x_2 \oplus \dots) = \sum_{i=1}^n \dim(x_i)$$

if every vector in $x \in X$
can be written uniquely
as $x = x_1 + x_2 + \dots + x_n$,
 $x_i \in X_i$


counter
example
of why
not correct
(original)
as $\sum \dim(x_i) = 3$
but $\dim X = 2$

morphisms:

Defn: (linear map) let X and Y be vector spaces over F . A map $T: X \rightarrow Y$ is a linear map / linear transformation / linear operator if

$$(i) T(x_1 + x_2) = T(x_1) + T(x_2), \forall x_1, x_2 \in X$$

$$(ii) T(\alpha x) = \alpha T(x), \alpha \in F, x \in X.$$

Note: If $Y = F$, then T is said to be a linear functional.

$$T(\alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_n x_n) = \alpha_1 T(x_1) + \alpha_2 T(x_2) + \dots + \alpha_n T(x_n)$$

and so on... to get the this.

Examples: (i) $X = C([0,1]) = \{f: [0,1] \rightarrow \mathbb{R}, f \text{ is cont}\}$

$$\text{Fix } \lambda \in [0,1] \quad T: C([0,1]) \rightarrow \mathbb{R}$$
$$T(f) = f(\lambda), \forall f \in C([0,1])$$

$$\leadsto f, g \in C([0,1])$$

$$\begin{aligned} T(f+g) &= (f+g)(\lambda) \\ &= f(\lambda) + g(\lambda) \\ &= T(f) + T(g) \end{aligned}$$

$$\text{for } \alpha \in \mathbb{R} \text{ and } f \in C([0,1]), T(\alpha f) = (\alpha f)(\lambda) = \alpha f(\lambda) = \alpha T(f)$$

(ii) let $X = \text{set of polynomials of degree } \leq n$

$$\begin{aligned} \frac{d}{dx}: X &\rightarrow X \\ f &\rightarrow \frac{df}{dx} \end{aligned}$$

Null space / kernel: $T: X \rightarrow Y$
 $\ker(T) = N_T = \{x \in X \mid T(x) = 0\} = \text{Null space}$

$\ker(T)$ is a subspace:

$$\text{for } x, y \in \ker(T)$$

$$T(\lambda x + y) = T(\lambda x) + T(y) = 0$$

$$\therefore \lambda x + y \in N_T$$

$\therefore \ker(T)$ is a subspace of X .

Range of T: $\text{Ran } T = R_T = \{T(x) \mid \forall x \in X\}$

$\text{Ran } T$ is a subspace:

$$\alpha \in F, T(x_1) \in R_T, T(x_2) \in R_T$$

$$\begin{aligned} \text{now } \alpha T(x_1) + T(x_2) \\ &= T(\alpha x_1) + T(x_2) \\ &= T(\alpha x_1 + x_2) \end{aligned}$$

as $T(\alpha x_1 + x_2) \in R_T$
 $\text{Ran } T = R_T$ is a subspace of Y .

Isomorphism: let X and Y be vector spaces over F .

A linear map $T: X \rightarrow Y$ is an isomorphism if T is a bijective map.

Lemma: A linear map $T: X \rightarrow Y$ is injective $\Leftrightarrow \ker T = N_T = \{0\}$

Proof: $(\Rightarrow)$ Trivial

$$\begin{aligned} (\Leftarrow) \text{ for } x_1 \neq x_2 \in X \text{ suppose} \\ T(x_1) - T(x_2) = T(x_1 - x_2) = 0 \\ \Rightarrow x_1 - x_2 \in N_T = \{0\} \\ \Rightarrow x_1 = x_2 \quad \text{---} \end{aligned}$$

Defn: two vector spaces are isomorphic, $\exists$ linear map that is isomorphism.

Theorem: let X and Y be finite dimensional vector spaces over F .
Then X is isomorphic to $Y \Leftrightarrow \dim X = \dim Y$.

Note: F^m is m -th degree subspace of F (as $\dim F^m = m$)

Proof: $(\Leftarrow)$ let $\{x_1, x_2, \dots, x_m\}$ be basis for X and $\{y_1, \dots, y_m\}$ be a basis for Y .

Define $T: X \rightarrow Y$
$$T\left(\sum_{i=1}^m \alpha_i x_i\right) = \sum_{i=1}^m \alpha_i y_i, \quad \forall \alpha_i \in F, x_i \in X.$$

① well defined:

$$\sum_{i=1}^m \alpha_i x_i \text{ is unique then}$$

$\sum \alpha_i y_i$ is also unique.

② linear map: Trivial (as $T(\sum \alpha_i x_i + \sum \beta_i x_i) = T(\sum (\alpha_i + \beta_i) x_i)$)

③ one-one: now $N_T = \{x \in X \mid T(x) = 0\}$

$$\text{if } T\left(\sum_{i=1}^m \alpha_i x_i\right) = 0, \text{ then}$$

$$\begin{aligned} \sum \alpha_i y_i &= 0 \\ \Rightarrow \alpha_i &= 0 \quad \forall i \in \{1, 2, \dots, n\} \end{aligned}$$

$$\therefore T(0) = 0 \quad \text{only } T(0) = 0$$

$$\therefore \{0\} = N_T$$

as $N_T = \{0\} \Rightarrow T$ is one-one.

④ onto: $R_T = Y$ (follows from fact, $y_i \in R_T$)

$\therefore X$ is isomorphic to Y .

($\Rightarrow$) let $T: X \rightarrow Y$ be an isomorphism

Suppose $\{x_1, x_2, \dots, x_n\}$ is a basis for X .

claim: $T(x_1), \dots, T(x_n)$ is a basis for Y .

$$\begin{aligned} \text{Suppose } \sum_{i=1}^n \alpha_i T(x_i) &= 0 \\ \Rightarrow T\left(\sum_{i=1}^n \alpha_i x_i\right) &= 0 \end{aligned}$$

$$\text{as } N_T = \{0\}$$

$$\Rightarrow \sum_{i=1}^n \alpha_i x_i = 0$$

$$\Rightarrow \alpha_i = 0, \forall i = 1, 2, \dots, n$$

$\therefore \{T(x_1), \dots, T(x_n)\}$ is lin ind.

$\rightarrow$ as $\text{Ran } T = Y$

Take $y \in Y$. Then $\exists x \in X$ s.t. $T(x) = y$. since $\{x_1, \dots, x_n\}$ is a basis for X ,

$$x = \sum_{i=1}^n \beta_i x_i$$

$$T\left(\sum_{i=1}^n \beta_i x_i\right) = y$$

$$\Rightarrow \sum_{i=1}^n \beta_i T(x_i) = y$$

$$\forall y \in Y$$

$$\therefore \text{span}\{T(x_1), T(x_2), \dots, T(x_n)\} = Y$$

$\therefore \{T(x_1), T(x_2), \dots, T(x_n)\}$ is a basis of Y .

$$\therefore \dim X = \dim Y$$

Exercise: let X be an n -dimensional vector space over F . Find an isomorphism, between X^m and F^m . $\rightarrow$ done (see down)

Example: (iii) $\begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix}_{1 \times n}$ $c_i \in \mathbb{R}^m$ this is a linear map from

$$\begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix}: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\text{as } \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n \mapsto \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}_{n \times 1}$$

$$\begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix}_{1 \times n} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}_{n \times 1} = x_1 c_1 + x_2 c_2 + \dots + x_n c_n \in \mathbb{R}^m$$

Exercise: matrix multiplication defines a linear map $\rightarrow$ done (see down)

Theorem: Let X, Y be finite dimensional vector spaces over F . If $T: X \rightarrow Y$ is a linear map, then

$$\dim X = \underbrace{\dim(N_T)}_{\text{nullity}} + \underbrace{\dim(R_T)}_{\text{rank}}$$

proof: $\tilde{T}: X/N_T \rightarrow Y$

$$\tilde{T}(x + N_T) = T(x)$$

$$x_1 + N_T = x_2 + N_T \Leftrightarrow x_1 - x_2 \in N_T$$

this means map is well defined.

$$T(x_1 - x_2) = 0$$
$$\Rightarrow T(x_1) = T(x_2)$$

$$\tilde{T}(x_1 + N_T) = \tilde{T}(x_2 + N_T)$$

$\therefore \tilde{T}$ is well defined.

$$\begin{aligned}\tilde{T}((x_1 + N_T) + (x_2 + N_T)) &= \tilde{T}(x_1 + x_2 + N_T) \\ &= T(x_1 + x_2) \\ &= T(x_1) + T(x_2) \\ &= \tilde{T}(x_1 + N_T) + \tilde{T}(x_2 + N_T)\end{aligned}$$

$$\text{and } \lambda \tilde{T}(x_1 + N_T) = \lambda T(x_1) = T(\lambda x_1) = \tilde{T}(\lambda x_1 + N_T)$$

$\therefore \tilde{T}$ is a linear map.

$$\begin{aligned}\tilde{T}(x + N_T) &= 0 \\ \Rightarrow T(x) &= 0 \\ \Rightarrow x &\in N_T \\ \Rightarrow x + N_T &= N_T \\ \therefore \ker(\tilde{T}) &= \{0\} \quad \tilde{T} \text{ is one-one}\end{aligned}$$

$$\tilde{T}: X/N_T \rightarrow R_{\tilde{T}} \subseteq Y$$

$\parallel$
 R_T

$\tilde{T}: X/N_T \rightarrow R_T$ is also one-one and surjective to R_T

$$\dim(X/N_T) = \dim(R_T)$$

$$\Rightarrow \dim(X) - \dim(N_T) = \dim(R_T)$$

$$\Rightarrow \dim(X) = \dim(N_T) + \dim(R_T)$$

Exercise: let X be an n -dimensional vector space over F . Find an isomorphism, between X^m and F^m .

let Basis of X be $\{x_1, x_2, \dots, x_n\}$ as it is n -dimensional now,

X^m is m th degree subspace of X and F^m is m th degree subspace of F .

let Basis of $X^m = \{x_1, x_2, \dots, x_m\}$

$$\text{let } x_m \in X^m = \sum_{i=1}^m \alpha_i x_i$$

$$\text{and let } T: X^m \rightarrow F^m \\ x_m \rightarrow \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_m \end{pmatrix} \in F^m$$

$$\text{now, } \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_m \end{pmatrix} = \alpha_1 \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}_{m \times 1} + \alpha_2 \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}_{m \times 1} + \dots + \alpha_m \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix}_{m \times 1}$$

$$\text{Basis of } F^m = \left\{ \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix} \right\}$$

as it ① spans F^m

$\therefore$ as $\deg F^m = \deg X^m$
 $\Rightarrow F^m$ is isomorphic to X^m .

$$T: X^m \rightarrow F^m \\ \sum_{i=1}^m \alpha_i x_i \mapsto \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_m \end{pmatrix}$$

T is a linear map
as

$$\begin{aligned} \textcircled{1} T(x_{m1} + x_{m2}) &= \begin{pmatrix} \alpha_1 + \beta_1 \\ \vdots \\ \alpha_m + \beta_m \end{pmatrix} \\ &= T(x_{m1}) + T(x_{m2}) \end{aligned}$$

$$\textcircled{2} T(\alpha x_m) = \alpha T(x_m)$$

① well defined:

$$\begin{aligned} \text{as for } \sum \alpha_i x_i = \sum \beta_i x_i \\ \Rightarrow \alpha_i = \beta_i \\ \therefore T(\sum \alpha_i x_i) &= T(\sum \beta_i x_i) \end{aligned}$$

② one-one:

$$\begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_m \end{pmatrix} = \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_m \end{pmatrix}$$

$$\begin{aligned} \Rightarrow \alpha_i &= \beta_i \\ \Rightarrow \sum \alpha_i x_i &= \sum \beta_i x_i \end{aligned}$$

③ onto:

$$\text{for any set } \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_m \end{pmatrix} \in F, \exists \sum \alpha_i x_i = x_m \therefore \text{onto}$$

$\therefore T: X^m \rightarrow F^m$ is an isomorphism

Exercise: matrix multiplication defines a linear map

$$\begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix}_{m \times n} : \mathbb{R}^n \rightarrow \mathbb{R}^m \text{ defined as:}$$

$$\begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix}_{m \times n} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}_{n \times 1} = x_1 c_1 + x_2 c_2 + \dots + x_n c_n$$

linear map:

$$\begin{aligned} \textcircled{1} \begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix} \begin{bmatrix} x_1 + y_1 \\ \vdots \\ x_n + y_n \end{bmatrix} &= (x_1 + y_1) c_1 + \dots + (x_n + y_n) c_n \\ &= \begin{bmatrix} c \end{bmatrix} x + \begin{bmatrix} c \end{bmatrix} y \end{aligned}$$

$$\begin{aligned} \textcircled{2} \begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix} \begin{bmatrix} \alpha x_1 \\ \vdots \\ \alpha x_n \end{bmatrix} &= \alpha x_1 c_1 + \dots + \alpha x_n c_n \\ &= \alpha (x_1 c_1 + \dots + x_n c_n) \\ &= \alpha \begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \end{aligned}$$

22nd Aug:

Theorem : (Rank nullity theorem) let X be a finite dimensional vector space, and V be a vector space over F . If $T: X \rightarrow V$ is a linear map then $\dim X = \dim(N_T) + \dim(R_T)$

group theory eq:

$$\begin{aligned} T: X &\rightarrow V \\ \bar{T}: X/N_T &\rightarrow V \\ X/N_T &\cong R_T^\perp = R_T \end{aligned}$$

$$\therefore \dim(X) - \dim(N_T) = \dim(R_T)$$

→ finite vector space

Cor: let $T: X \rightarrow V$ be a linear map (I) If $\dim(V) < \dim(X)$ then $\exists$ a non-zero vector x s.t. $T(x) = 0$.

as $T(0) = 0$
 $T(\lambda x) = \lambda T(x), \forall \lambda \in F$
and if $\lambda = 0$
 $T(0) = 0$ (always)

$$m < n \quad \sum_{j=1}^n a_{ij} x_j = 0 \quad x_j \in \mathbb{R}^m$$
$$A = \begin{pmatrix} & \end{pmatrix}_{m \times n} : \mathbb{C}^n \rightarrow \mathbb{C}^m$$

(II) If $\dim(V) = \dim(X)$ and if $N_T = \{0\}$, then $R_T = V$
injective $\Rightarrow$ surjective $\Rightarrow$ bijective

(III) If $\dim(V) = \dim(X)$ and $R_T = V$, then $N_T = \{0\}$
surjective $\Rightarrow$ injective $\Rightarrow$ bijective

proof: (I) $\dim(N_T) = \dim(X) - \dim(R_T)$
 $\geq \dim(X) - \dim(V) > 0$
 $\Rightarrow \dim(N_T) > 0$

(II) $\dim(N_T) = 0$
 $\dim(X) = \dim(R_T) = \dim(V)$
 $\Rightarrow R_T = V$
as $R_T \subseteq V$

(III) $\dim(V) = \dim(X)$
and $R_T = V \Rightarrow \dim(R_T) = \dim(X)$
 $\Rightarrow \dim(N_T) = 0$
 $\Rightarrow N_T = \{0\}$

Note:

now,

$Ax = b, A \in M_{n \times n}$
if $Ax = 0$ has only the trivial soln then $N_A = \{0\}$ then it means $\dim(N_A) = 0$ then $Ax = b$ will have a unique solution.

as $Ax = b$

→ linear map

$$A: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

and as $b \in \mathbb{R}^n$ is in RA

$$RA = \mathbb{R}^n$$

$\therefore Ax = b$ will have a unique sol (one-one, onto)

Note: $\mathcal{L}(X, V) = \{T: X \rightarrow V \mid T \text{ is linear}\}$
 $\swarrow$
 vector space

* $\mathcal{L}(X, V)$ is a vector space

proof: $T_1 + T_2: X \rightarrow V$
 $(T_1 + T_2)(x) = T_1(x) + T_2(x)$

$$\lambda T: X \rightarrow V$$

$$(\lambda T)(x) = \lambda T(x), \forall x \in X$$

Theorem: let $\{x_1, x_2, \dots, x_n\}$ be a basis for X . There is an isomorphism

$$\Pi: \mathcal{L}(X, V) \rightarrow V \times V \times \dots \times V$$

$$T \mapsto (T(x_1), T(x_2), \dots, T(x_n))$$

proof: ① well-defined
 ② linear
 ③ injective
 ④ surjective

} Needed for isomorphism

well-defined: $T_1 = T_2$
 $T_1(x_1) = T_2(x_1)$
 $T_1(x_i) = T_2(x_i)$
 $\therefore \Pi$ is a well-defined map.

linear: $\Pi(\lambda T_1 + T_2) = ((\lambda T_1 + T_2)(x_1), \dots, (\lambda T_1 + T_2)(x_n))$
 $= (\lambda T_1(x_1) + T_2(x_1), \dots, \lambda T_1(x_n) + T_2(x_n))$
 $= \lambda (T_1(x_1), T_1(x_2), \dots, T_1(x_n)) + (T_2(x_1), \dots, T_2(x_n))$
 $= \lambda \Pi(T_1) + \Pi(T_2)$

injective: If $T \in \mathcal{L}(X, V)$, show that $T(x_i) = 0, \forall i = 1, 2, \dots, n$

$$\text{then } T(x) = T\left(\sum_{i=1}^n \lambda_i x_i\right)$$

$$= \sum_{i=1}^n \lambda_i T(x_i)$$

$$= 0, \forall x \in X$$

$\therefore T \equiv 0$
 so if $T(x_i) = 0 \forall i$
 then $T \equiv 0$ (it is a zero map)

$$\therefore N_\Pi = \{0\}$$

$\hookrightarrow$ all linear zero maps.

surjective: let $(v_1, \dots, v_n) \in V \times V \times \dots \times V$
 define $T_v: X \rightarrow V$ by

$$T_v\left(\sum_{i=1}^n \alpha_i x_i\right) = \sum_{i=1}^n \alpha_i v_i \quad \text{where } v_i = T(x_i)$$

① T_v is well defined
 ② T_v is linear map

$$\text{as } T_v(\alpha x + y) = \alpha T_v(x) + T_v(y)$$

$$\text{now, } (T v(x_1), T v(x_2), \dots, T v(x_n)) = (v_1, v_2, \dots, v_n) \\ \alpha_1 = 1 \quad \alpha_2 = 1 \\ \alpha_i = 0 \quad \alpha_i = 0 \\ \text{for } i \neq 1 \quad \text{for } i \neq 2$$

$\therefore$ isomorphism

cor: let $T \in \mathcal{L}(X, V)$ and $\{x_1, x_2, \dots, x_n\}$ is basis then (I) T is injective $\Leftrightarrow \{T(x_1), \dots, T(x_n)\}$ is lin ind set of vector in V .

(II) T is surjective $\Leftrightarrow \text{span}\{T(x_1), T(x_2), \dots, T(x_n)\} = V$

so here see T is bijective $\Leftrightarrow$ Basis $V = \{T(x_1), \dots, T(x_n)\}$

sketch of proof: (I) $T(\sum \alpha_i x_i) = 0 \Leftrightarrow \sum \alpha_i T(x_i) = 0$
as $N_T = \{0\}$
only if $\sum \alpha_i x_i = 0$
 $\Rightarrow \alpha_i = 0$

proof:

($\Rightarrow$) T is injective
then any $v \in V$
 $v = T(x)$
 $v = T(\sum \alpha_i x_i)$
 $\Rightarrow v = \sum \alpha_i T(x_i)$
 $\therefore$ span.

(II) T is surjective,
 $R_T = V$ any $v \in V$

$v = T(x)$
 $\Rightarrow v = T(\sum \beta_i x_i)$
 $\Rightarrow v = \sum \beta_i T(x_i)$

proof: ($\Rightarrow$) T is one-one
if $T(\sum \alpha_i x_i) = 0$ $\alpha_i = 0$
 $\Rightarrow \sum \alpha_i T(x_i) = 0$
 $\Rightarrow \alpha_i = 0 \therefore$ lin ind

($\Leftarrow$) if $\sum \beta_i T(x_i)$ is lin ind
 $\sum \beta_i T(x_i) = 0$
 $\Rightarrow \beta_i = 0$
also $\sum \beta_i T(x_i) = T(\sum \beta_i x_i)$
 $0 = T(0)$

($\Leftarrow$) if $T(x_i)$ span or span has to be whole space.
then $\sum \beta_i T(x_i) = T(\sum \beta_i x_i)$, $\forall x \in X$
 $= T(x) \therefore V = R_T$

defⁿ: X - n dimensional vector space

$X' = \mathcal{L}(X, F)$ - dual space

Note: $X' \cong F^n$, $\dim(X') = \dim(F^n) = n$

basis of F^n :

$$e_i = (0, \dots, 0, 1, 0, \dots, 0)$$

$\uparrow$
ith place

basis for F^n .

defⁿ: let $Y \subseteq X$ be a subspace of X

$Y^\perp = \{\gamma \in \mathcal{L}(X, F) \mid \gamma(y) = 0, \forall y \in Y\} \rightarrow$ Annihilator of Y

$Y^\perp \subseteq X^\perp$

$$(\alpha \gamma_1 + \gamma_2)(y) = \alpha \gamma_1(y) + \gamma_2(y) \\ = \alpha \cdot 0 + 0 \\ = 0, \forall y \in Y$$

$\therefore Y^\perp \subseteq X^\perp$

Theorem: let Y be a subspace of a finite dimensional vector space X . Then
 $Y^\perp \cong (X/Y)' \rightarrow$ dual space

$$(X/Y)' = \alpha(X/Y, f)$$

and $\dim(X) = \dim(Y) + \dim(Y^\perp)$

$$Y^\perp \rightarrow (0, 0, 0, \dots, * * \dots) \in \mathbb{F}^n$$

for $\alpha(x, v) \rightarrow (\underbrace{\tau(x_1), \tau(x_2), \dots, \tau(x_n)}_{\text{Basis of } Y^\perp})$

$$(X/Y)' \cong \frac{\dim(X) - \dim(Y)}{\dim(X) - \dim(Y)}$$

$$\text{then } (0, 0, \dots, \underbrace{\tau(x_1), \tau(x_2)}_m, \dots, \tau(x_{n-m})) \in \mathbb{F}^m$$

$$\dim(X) = \dim(Y^\perp) + \dim(Y)$$

proof: Define a map

$$\Gamma: Y^\perp \rightarrow (X/Y)'$$

$$\gamma \mapsto \sigma$$

s.t. $\sigma(x+Y) = \gamma(x)$

$$x_1 + Y = x_2 + Y$$

$$\Leftrightarrow x_1 - x_2 \in Y$$

$$\Leftrightarrow \gamma(x_1 - x_2) = 0$$

$$\Leftrightarrow \gamma(x_1) = \gamma(x_2)$$

well defined and one-one

26th Aug: Quiz - Wednesday - Kill last laws (not this)

Theorem: Let X be a finite dimensional vector space and $Y \subseteq X$ be a subspace. Then

$$\dim(Y^\perp) = \dim(X/Y)'$$

proof: claim: there is an isomorphism b/w $Y^\perp$ and $(X/Y)'$

$$\begin{aligned} \Gamma: Y^\perp &\rightarrow (X/Y)' \\ \gamma &\rightarrow \Gamma(\gamma) \quad \text{where} \\ \Gamma(\gamma): X/Y &\rightarrow F \quad (F \text{ is a field, wlog}) \\ \text{linear map} & \\ \text{defined by} & \\ \Gamma(\gamma)(x+Y) &= \gamma(x) \quad \forall x \in X \end{aligned}$$

① well-defined ——— trivial

② linear: $\Gamma(\gamma_1 + \gamma_2)(x+Y) = (\gamma_1 + \gamma_2)(x) = \gamma_1(x) + \gamma_2(x)$
 $= \Gamma(\gamma_1)(x+Y) + \Gamma(\gamma_2)(x+Y)$

$$\Rightarrow \Gamma(\gamma_1 + \gamma_2) = \Gamma(\gamma_1) + \Gamma(\gamma_2)$$

$$\Gamma(\lambda \gamma)(x+Y) = (\lambda \gamma)(x+Y) = \lambda \gamma(x+Y) = \lambda \Gamma(\gamma)(x+Y)$$

③ one-one: if $\Gamma(\gamma) = 0$, then $\Gamma(\gamma)(x+Y) = 0, \forall x \in X$
 $\Rightarrow \gamma(x) = 0, \forall x \in X$
 $\Rightarrow \gamma = 0$
 $\therefore N_\Gamma = \{0\}$
 $\Rightarrow \Gamma$ is one-one

④ onto: $X \xrightarrow{\pi} X/Y \xrightarrow{\Theta} F$
 $x \mapsto x+Y$
vanishes on Y ——— vanishes on Y
 π : linear surjection $\rightarrow$ trivial ($\pi(x) = x+Y$)

$$\begin{aligned} Q \circ \pi: X &\rightarrow F \rightarrow \text{composition of linear} \\ Q \circ \pi(x_1 + x_2) &= Q(\pi(x_1 + x_2)) \text{ maps to linear} \\ &= Q(\pi(x_1) + \pi(x_2)) \\ &= Q \circ \pi(x_1) + Q \circ \pi(x_2) \end{aligned}$$

$$\text{also } Q \circ \pi(\lambda x) = Q(\pi(\lambda x)) = \lambda Q \circ \pi(x)$$

Also vanishes at Y , as π kills $Y \in Y$.

$$\Rightarrow Q \circ \pi \in Y^\perp$$

need to show $\Gamma(Q \circ \pi) = Q$ then done
as $Q \in (X/Y)'$

$$\begin{aligned} \Gamma(Q \circ \pi)(x+Y) &= Q \circ \pi(x) \\ &= Q(\pi(x)) \\ &= Q(x+Y), \forall x \in X \end{aligned}$$

$\therefore$ onto

Transpose: $T: X \rightarrow Y$
 $\leadsto T': Y' \rightarrow X'$ (Transpose of T)

$$T'(Q)(x) = Q(T(x)), \quad Q \in Y', \quad x \in X$$

$$\begin{aligned} x &\xrightarrow{T} y \xrightarrow{Q} F \\ &\quad \quad \quad T: X \rightarrow Y \\ &\quad \quad \quad Q: Y \rightarrow F \\ \text{then } Q \circ T &: X \rightarrow F \end{aligned}$$

Note: $T'(Q)(x) = Q(T(x))$, $Q \in Y'$, $x \in X$
 composing linear maps
 (see prev onto proof)

$\gamma \nearrow$ wnt map
 $[a, b] \xrightarrow{\gamma} [c, d]$
 $\leadsto T: C([c, d]) \rightarrow C([a, b])$
 $f \mapsto f \circ \gamma$
Exercise: show that if γ is surjective then T is injective. here $T: f \mapsto f \circ \gamma$
 γ is surjective $R_T' = X'$ but $\dim(X') = \dim(R_T') + \dim(N_T')$
 $\Rightarrow N_T' = \{0\}$
 this theorem $\Rightarrow$ dual-
 can be used one

Theorem: let $T: X \rightarrow Y$ be a linear map, show that X and Y are finite dimensional vector spaces, then $R_T^\perp = N_{T'}$

proof: For $Q \in R_T^\perp$
 $\Leftrightarrow Q(y) = 0, \forall y \in R_T$
 $\Leftrightarrow Q(T(x)) = 0, \forall x \in X$
 $\Leftrightarrow (T'(Q))(x) = 0, \forall x \in X$
 $\Leftrightarrow T'(Q) \equiv 0$
 $\Leftrightarrow Q \in N_{T'}$

for $T'(Q)(x) = Q \circ T = 0$
 Q has to vanish on range of T
 $T: X \rightarrow Y$
 so $Q \in R_T^\perp$

Theorem: let X and Y be f.d vector spaces and $T: X \rightarrow Y$ is a linear map then $\dim(R_T) = \dim(R_{T'})$

proof:
 $\dim(Y') = \dim(R_{T'}) + \dim(N_{T'})$ — By Rank-nullity theorem
 $\dim(Y) = \dim(R_T) + \dim(R_T^\perp)$ — By theorem we proved today
 as $\dim(Y) = \dim(Y')$ $\rightarrow$ see
 $\dim(R_T^\perp) = \dim(N_{T'})$
 then $\dim(R_T) = \dim(R_{T'})$

Example:

$$\begin{aligned} X &\xrightarrow{\text{dual space}} X' \xrightarrow{\text{dual space}} X'' \\ \dim(X) &= \dim(X') = \dim(X'') \\ X'' &\cong X \quad (\text{as } X \cong X' \cong X'') \end{aligned}$$

Dual space of $\mathbb{R}^n$:

$\mathbb{R}^n$ and $(\mathbb{R}^n)'$

$$(\mathbb{R}^n)' = \{ T: \mathbb{R}^n \rightarrow \mathbb{R} \mid T \text{ is linear} \}$$

$$e_i = (\underbrace{0, 0, \dots, 1}_{i\text{th}}, \underbrace{0, 0, \dots, 0}_{n-i}) \text{ basis of } \mathbb{R}^n$$

$$\begin{aligned} Q &\in (\mathbb{R}^n)' \\ Q &\leftrightarrow (Q(e_1), Q(e_2), \dots, Q(e_n)) \\ Q(\sum \alpha_i e_i) &= \sum \alpha_i Q(e_i) \\ (\alpha_1, \alpha_2, \dots, \alpha_n) &\mapsto \sum \alpha_i Q(e_i) \end{aligned}$$

$(Q(e_1), \dots, Q(e_n)) \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{bmatrix} = \sum_{i=1}^n \alpha_i Q(e_i)$
 new vector uniquely determines

$$T = [T_{ij}] : \mathbb{R}^m \rightarrow \mathbb{R}^n$$

$$T' : (\mathbb{R}^n)' \rightarrow (\mathbb{R}^m)'$$

$$T'(Q)(x) = Q(T(x)), \forall Q \in (\mathbb{R}^n)', x \in \mathbb{R}^m$$

where $T'(Q)(x) = Q(T(x)), \forall Q \in (\mathbb{R}^n)', x \in \mathbb{R}^m$

For $Q = (Q_1, \dots, Q_n) \in (\mathbb{R}^n)'$ and

$$x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix} \in \mathbb{R}^m$$

$$Q\left(T\begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix}\right) = (Q_1 \ Q_2 \ \dots \ Q_n) \begin{pmatrix} \sum_{j=1}^m T_{1j} x_j \\ \vdots \\ \sum_{j=1}^m T_{nj} x_j \end{pmatrix}$$

$$= \sum_{\ell=1}^n Q_\ell \sum_{j=1}^m T_{\ell j} x_j = \sum_{j=1}^m \left(\sum_{\ell=1}^n T_{\ell j} Q_\ell \right) x_j$$

$$= \sum_{j=1}^m \left(\sum_{\ell=1}^n T_{j\ell}^t Q_\ell \right) x_j$$

$$= \left(\sum_1^n T_{1\ell}^t Q_\ell, \sum_1^n T_{2\ell}^t Q_\ell, \dots, \sum_1^n T_{m\ell}^t Q_\ell \right) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix}$$

Note:

$$(T^t)_{ij} = T_{ji}$$

$$\text{see } \rightarrow = T^t(Q) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix}$$

$$\text{see } \Rightarrow \Rightarrow T' : (\mathbb{R}^n)' \rightarrow (\mathbb{R}^m)'$$

$$\underline{T' = T^t}$$

29th Aug : recap:

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

Proved: $T': \mathbb{R}^m \rightarrow \mathbb{R}^n$ if T' is a transpose map then $T' = T^t$ metric transpose

Defn: The column rank of a matrix $T \in M_{n \times n}(F)$ is the dimension of the span $\{c_1, \dots, c_n\}$ then $T = [c_1, c_2, \dots, c_n]$.

The row rank of T is dimension of the span $\{r_1, r_2, \dots, r_m\}$, then

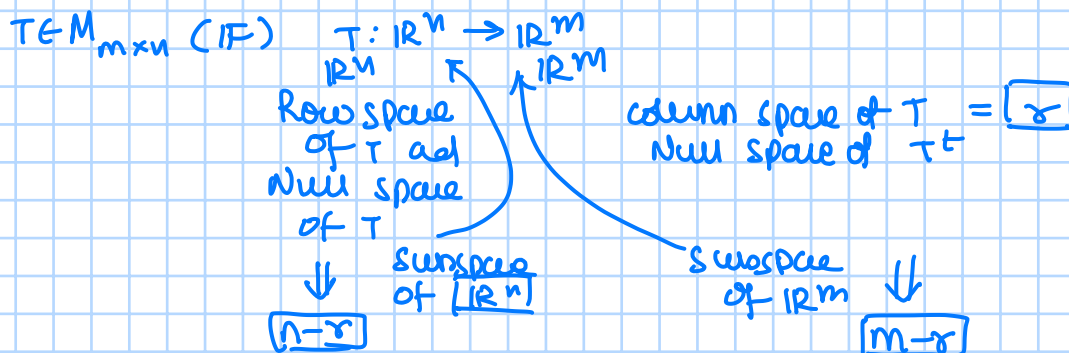
$$T = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_m \end{bmatrix}$$

• column rank of $T = \dim(R_T)$
 $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$\begin{bmatrix} c_1, c_2, \dots, c_n \end{bmatrix}_{m \times n} \quad R_T = \left\{ [c_1, c_2, \dots, c_n] \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \mid x_i \in F \right\} \\ = \left\{ \sum_{i=1}^n x_i c_i \mid x_i \in F \right\} = \text{span}\{c_1, c_2, \dots, c_n\}$$

$$\text{row rank of } T = \text{column rank of } T^t = \dim(R_{T^t})$$

Theorem: For $T \in M_{m \times n}(F)$, column rank of $T = \text{row rank of } T$.



$$\begin{bmatrix} 1 & * & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{T^t} \begin{bmatrix} 1 & 0 & 0 \\ * & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$\uparrow$ T Why is rank of T and T^t same?
 $ET = R$

Span $\{r_1, r_2, \dots, r_m\}$
 Span $\{\lambda r_1, \lambda r_2, \dots, \lambda r_m\}$ } same span T and T'

$$N(T^t) = \{y \in \mathbb{R}^m \mid T^t y = 0\}$$

$$= \{y \in \mathbb{R}^m \mid y^t T = 0\}$$

$$(y_1, \dots) \begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$N(T) = \{x \in \mathbb{R}^n \mid T x = 0\}$$

$$T \leftrightarrow \begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix} \\ T x = E^t R x = 0$$

$$\begin{aligned}
 &V \cong \mathbb{F}^n \\
 &\text{let } \{v_1, \dots, v_n\} \text{ be dual basis} \\
 &\text{then } \tau: V \rightarrow \mathbb{F}^n \\
 &b) \tau(v_i) = e_i, \forall i = 1, 2, \dots, n \\
 &\quad e_i = (0, \dots, 1, \dots) \\
 &\quad \tau\left(\sum_{i=1}^n a_i v_i\right) = (a_1, a_2, \dots, a_n)
 \end{aligned}$$

$$\mathbb{R}^n \leftarrow V \xrightarrow{W} \mathbb{R}^m$$

Define $\pi: \mathcal{L}(V, W) \rightarrow M_{m \times n}(\mathbb{F})$
 $T \mapsto B_W \circ T \circ B_V^{-1}$
 then π is an isomorphism

$$\begin{aligned}
 \alpha S + T &\xrightarrow{B_W \circ (\alpha S + T) \circ B_V^{-1}} \\
 &B_W \circ (\alpha S) \circ B_V^{-1} + B_W \circ T \circ B_V^{-1}
 \end{aligned}$$

$\sim \pi$ is linear

Injectivity: If $B_W \circ T \circ B_V^{-1} = 0$
 then for any $x \in V$, $B_W \circ T \circ B_V^{-1}(B_V x) = 0$
 $\Rightarrow B_W(\tau(x)) = 0$
 $\Rightarrow \tau(x) = 0$

Surjectivity: For any $M \in M_{m \times n}(\mathbb{F})$
 define $T: B_W \circ M \circ B_V^{-1}: V \rightarrow W$
 and $\pi(T) = B_W \circ (B_V^{-1} \circ M \circ B_V) \circ B_V^{-1} = M$

$$\begin{array}{c}
 \begin{matrix} 1 & 2 & \dots & n \end{matrix} \\
 \left[\begin{array}{ccc|c} 1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{array} \right]_{m \times n} \quad T(e_i)
 \end{array}$$

$$B_W \circ T \circ B_V^{-1}(e_i) = B_W \circ T(v_i) = B_W\left(\sum_{j=1}^m A_{ji} w_j\right) = (A_{1i}, A_{2i}, \dots, A_{mi})$$

} Deepest (ask prof)

Also for this theorem
 see above class proof
 for $\dim(R_T)$
 $= \dim(R_{T'})$
 as $R_{T'} = R_T^t$
 column rank
 $=$ row rank

2nd sept:

$$T: X \rightarrow X$$

The matrix rep of T w.r.t a basis $\alpha = \{\alpha_1, \dots, \alpha_n\}$ is $A \in M_{n \times n}(\mathbb{C})$

$$T(\alpha_i) = \sum_{j=1}^n A_{ji} \alpha_j$$

as linear combinations of α_j 's

$$A = \begin{bmatrix} A_{11} \\ A_{21} \\ \vdots \\ A_{n1} \end{bmatrix}$$

matrix rep of T (1st column)

Tricks: $\begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix}$ $T: V \rightarrow V = \{v_1, \dots, v_m\}$ $\hookrightarrow$ Basis $\hookrightarrow$ Basis $= \{v_1, \dots, v_m\}$

If B is a matrix representation of T w.r.t another matrix then

$$\mathbb{F}^n \xleftarrow{B_x^{-1}} X \xrightarrow{T} X \xrightarrow{B_y} \mathbb{F}^n$$

$y = \{y_1, y_2, \dots, y_n\}$

$B_y(y_i) = e_i \leftarrow$ standard basis

$$B = B_y \circ T \circ B_x^{-1}$$

composition of linear map from $\mathbb{F}^n \rightarrow \mathbb{F}^n$

see why

$$A = B_x \circ T \circ B_x^{-1}$$

$$B = B_y \circ T \circ B_y^{-1} = B_y \circ B_x^{-1} \circ B_x \circ T \circ B_x^{-1} \circ B_x \circ B_y^{-1}$$

$$B = B_y \circ B_x^{-1} \circ A \circ B_x \circ B_y^{-1} = B_y \circ B_x^{-1} \circ A \circ (B_y \circ B_x^{-1})^{-1} = S A S^{-1}$$

$$\mathbb{F}^n \xrightarrow{B_x^{-1}} X \xrightarrow{B_y} \mathbb{F}^n$$

Isomorphism $\therefore$ invertible

$$S \in M_{n \times n}(\mathbb{F})$$

Note: $B = S A S^{-1}$
then they are called similar

Exercise: Let T be a linear map from X to X and A be a matrix representation of T w.r.t a basis of $\{\alpha_1, \dots, \alpha_n\}$. Let $B = S A S^{-1}$, $\exists S \in M_{n \times n}(\mathbb{F})$.

Then find a basis $\gamma = \{\gamma_1, \gamma_2, \dots, \gamma_n\}$ of X s.t B is the matrix rep of T w.r.t γ .

done see down

now

$$\mathbb{F}^n \xrightarrow{B_x^{-1}} X \xrightarrow{B_y} \mathbb{F}^n$$

$$B_y \circ B_x^{-1} = S \rightarrow A \text{ as } B_x(\alpha_i) = e_i$$

$$B_y \circ B_x^{-1}(e_i) = B_y(\alpha_i) = B_y\left(\sum_{j=1}^n A_{ji} \gamma_j\right) = \sum_{j=1}^n A_{ji} e_j$$

$$S = \begin{bmatrix} A_{11} \\ A_{21} \\ \vdots \\ A_{n1} \end{bmatrix}$$

1st column

Determinants:

Let $D: \underbrace{\mathbb{F}^n \times \dots \times \mathbb{F}^n}_{n \text{ times}} \rightarrow \mathbb{F}$ be a map such that it satisfies the below prop:

P1: $D(x_1, x_2, \dots, x_n) = 0$ if $x_i = x_j$ for some $i \neq j$

P2: Multilinear:

$$D(x_1, x_2, \dots, x_{i-1}, \alpha x + y, x_{i+1}, \dots, x_n) \\ \uparrow \\ \text{All fixed but} = \alpha D(x_1, x_2, \dots, x_{i-1}, x, x_{i+1}, \dots, x_n) \\ \text{one is } \alpha x + y \quad + D(x_1, x_2, \dots, x_{i-1}, y, x_{i+1}, \dots, x_n) \\ \text{then with} \\ \text{to that column it is} \\ \text{linear (At any column) (Multilinearity)}$$

P3: Normalisation:

$$D(e_1, e_2, \dots, e_n) = 1$$

Lemma: Let $D: \mathbb{F}^n \times \dots \times \mathbb{F}^n \rightarrow \mathbb{F}$ be s.t it satisfies P1, P2 and P3. Then

$$D(x_1, x_2, \dots, x_n) = -D(y_1, y_2, \dots, y_n) \\ \text{where } y_i = \begin{cases} x_i, & \forall i \neq p, q \\ x_p, & i = q \\ x_q, & i = p \end{cases}$$

~~proof~~: Set $D(x_p, x_q) = D(x_1, x_2, \dots, x_{p-1}, x_p, x_{p+1}, \dots, x_q, \dots, x_n)$
to prove: $D(x_p, x_q) = -D(x_q, x_p)$

$$\begin{aligned} D(x_p, x_q) &= D(x_p, x_q) + D(x_q, x_q) \\ &= D(x_p + x_q, x_q) \\ &= D(x_p + x_q, x_q) - D(x_p + x_q, x_p + x_q) \\ &= D(x_p + x_q, -x_p) \\ &= -D(x_p + x_q, x_p) \\ &= -D(x_q, x_p) - D(x_p, x_p) \\ &= -D(x_q, x_p) \end{aligned}$$

Lemma: Let D be as above, if $\{x_1, \dots, x_n\}$ is a dependent set of vectors in $\mathbb{F}^n$ then $D(x_1, x_2, \dots, x_n) = 0$.

proof:

$$\begin{aligned} \text{Suppose } x_1 &= \sum_{i=2}^n \alpha_i x_i \text{ then } D(x_1, x_2, \dots, x_n) = D\left(\sum_{i=2}^n \alpha_i x_i, x_2, x_3, \dots, x_n\right) \\ &= \sum_{i=2}^n \alpha_i D(x_i, x_2, \dots, x_n) \\ &= 0 \text{ By Property 1.} \end{aligned}$$

Defn: (Signature of Permutation)

$$\sigma: (1, 2, \dots, n) \rightarrow (1, 2, \dots, n) \\ \sigma \in S_n \leftarrow \text{permutation}$$

$$\text{define } P(x_1, x_2, \dots, x_n) = \prod_{i < j} (x_i - x_j)$$

$$P(x_{\sigma(1)}, \dots, x_{\sigma(n)}) = \prod_{i < j} (x_{\sigma(i)} - x_{\sigma(j)})$$

$\text{sgn}(\sigma)$ is s.t

$$P(x_1, x_2, \dots, x_n) = \text{sgn}(\sigma) P(x_{\sigma(1)}, \dots, x_{\sigma(n)})$$

$$\begin{aligned}
 \text{Now, } D(x_1, x_2, \dots, x_n) &= D\left(\sum_{i=1}^n a_{i1} e_i, x_2, \dots, x_n\right) \\
 &= \sum_{i=1}^n a_{i1} D(e_i, x_2, \dots, x_n) \\
 &\vdots \\
 &= \sum a_{1f(1)} \dots a_{nf(n)} D(e_{f(1)}, \dots, e_{f(n)})
 \end{aligned}$$

where the sum $f: \{1, \dots, n\} \rightarrow \{1, \dots, n\}$
is over all functions

see if

$$\begin{aligned}
 D(x_1, x_2) &= D(a_{11}e_1 + a_{12}e_2, x_2) \\
 &= a_{11}D(e_1, x_2) + a_{12}D(e_2, x_2) \\
 &= a_{11}a_{21}D(e_1, e_1) + a_{11}a_{22}D(e_1, e_2) \\
 &\quad + a_{12}a_{21}D(e_2, e_1) + a_{12}a_{22}D(e_2, e_2)
 \end{aligned}$$

$$\begin{aligned}
 &= \sum a_{1f(1)} \dots a_{nf(n)} D(e_{f(1)}, \dots, e_{f(n)}) \\
 \text{Reduces to} \\
 &\rightsquigarrow = \sum_{\sigma \in S_n} a_{1\sigma(1)} \dots a_{n\sigma(n)} D(e_{\sigma(1)}, \dots, e_{\sigma(n)}) \\
 &= \sum_{\sigma \in S_n} \text{sgn}(\sigma) a_{1\sigma(1)} \dots a_{n\sigma(n)}
 \end{aligned}$$

Exercise: Let T be a linear map from X to X and A be a matrix representation of T w.r.t a basis of $\{x_1, \dots, x_n\}$. Let $B = SAS^{-1}$, $\exists S \in M_{n \times n}(\mathbb{F})$. Then find a basis $y = \{y_1, y_2, \dots, y_n\}$ of X s.t B is the matrix rep of T w.r.t y .

Here as $B = SAS^{-1}$

$$\text{and } A = Bx \circ T \circ Bx^{-1}$$

where $Bx(x_i) = e_i$ ↖ Standard basis

now

$$\begin{aligned}
 B &= S(Bx \circ T \circ Bx^{-1})S^{-1} \\
 &= (SBx)T(SBx)^{-1}
 \end{aligned}$$

$$\text{now for } SBx = By$$

then

$$SBx(y_i) = e_i$$

as SBx will be a linear map from X to $\mathbb{F}^n$

and will be invertible

we have

$$\begin{aligned}
 y_i^0 &= (SBx)^{-1}(e_i) \\
 y_i^0 &= Bx^{-1}S^{-1}(e_i)
 \end{aligned}$$

$$\therefore \text{Basis will be } Bx^{-1}S^{-1}(e_i)$$

$$\begin{aligned}
 \text{where } A &= Bx \circ T \circ Bx^{-1} \\
 A(e_i) &= Bx \circ T \circ Bx^{-1}(e_i)
 \end{aligned}$$

5th sept:

S_n and σ notations:

S_n -group of permutations on n -symbols

also called
symmetric group

$$\sigma: \{1, \dots, n\} \xrightarrow{\text{bijection}} \{1, \dots, n\}$$

$$\sigma = \begin{pmatrix} 1 & 2 & 3 & \dots & n \\ \sigma(1) & \sigma(2) & \sigma(3) & \dots & \sigma(n) \end{pmatrix}$$

$$\sigma^{-1} = \begin{pmatrix} \sigma(1) & \sigma(2) & \dots & \sigma(n) \\ 1 & 2 & \dots & n \end{pmatrix}$$

$$\sigma \circ \sigma^{-1}(\sigma(1)) = \sigma(1)$$

$$\sigma \circ \sigma^{-1}(\sigma(r)) = \sigma(r)$$

$$\begin{aligned} \sigma \circ \sigma^{-1}(i) &= \sigma \circ \sigma^{-1}(\sigma(k)) = \sigma(k) = i \\ &\Rightarrow i = \sigma(k) \\ &\Rightarrow \sigma \circ \sigma^{-1}(i) = i \end{aligned}$$

Defn: cycle:

let S_n be the permutation group of $\{x_1, \dots, x_n\}$ then $(x_1, \dots, x_k)$ is a cycle where

$$(x_1, x_2, \dots, x_k)(x_i) = \begin{cases} x_i & \text{if } x_i \notin \{x_1, \dots, x_k\} \\ x_{i+1} & \text{if } i \neq k \\ x_1 & \text{if } i = k \end{cases}$$

Note: $(x_1, x_2, \dots, x_k) = (x_2, x_3, \dots, x_k, x_1)$

Defn: length of cycle $(x_1, x_2, \dots, x_k) - k\text{-cycle}$ (length)

eg: (x, y) 2-cycle is called transposition.
transposition, just changes x and y position.

product of k -cycles:

we take an example:

every σ can be written as multiplication of product of cycles

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 3 & 4 & 2 & 1 & 5 \end{pmatrix}$$

$$\text{Note } 1 \rightarrow 3 \rightarrow 2 \rightarrow 4 \rightarrow 1 \rightarrow 3$$

$$\text{so } (1324)$$

product of cycles

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 5 & 4 & 3 & 1 \end{pmatrix}$$

$$1 \rightarrow 2 \rightarrow 5 \rightarrow 1 \rightarrow 2 \rightarrow 5$$

cycle 1

$$3 \rightarrow 4 \rightarrow 3$$

cycle 2

$$(125)(34) = (34)(125)$$

Note: k -cycle

$$(123) = (13)(12)$$

$$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$$

similarly

$$(x_1, x_2, \dots, x_k) = (x_1, x_k)(x_1, x_{k-1}) \dots (x_1, x_2)$$

proof: if $x_i \notin \{x_1, \dots, x_k\}$ then

$$(x_1, x_2, \dots, x_k)(x_i) = x_i$$

$$\text{and same for } (x_1, x_k) \dots (x_1, x_2)(x_i) = x_i$$

$$\begin{aligned} &\text{if } x_i \in \{x_1, \dots, x_k\} \text{ and } x_i \neq x_k \\ &\text{then } (x_1, \dots, x_k)(x_i) = x_{i+1} \\ &\text{and } (x_1, x_k)(x_1, x_{k-1}) \dots (x_1, x_2)(x_i) \end{aligned}$$

$$= \begin{cases} x_2 & i=1 \\ x_{i+1} & i \neq 1 \end{cases}$$

This is not unique
 $(123) = (13)(12) = (45)(45)(13)(12)$

σ as two sum representations

similarly for $i=k$ we see both sides equal.

$\therefore$ every cycle of length > 2 can be converted into multiplication of cycles of size 2

Every permutation can be written as product of 2 cycles. they are both 2 cycles

Theorem: (Parity theorem) let $\sigma \in S_n$. let $\sigma = \gamma_1 \dots \gamma_n$ and let $\sigma = \gamma'_1 \dots \gamma'_n$ be factorisation of σ as product of 2-cycles
Then $1n - m_1 = 2i, p \in \mathbb{N} \cup \{0\}$

Defn: let $\sigma \in S_n$ and $\sigma = \gamma_1 \dots \gamma_n$ be a factorisation of σ as product of two cycles, Then
 $\text{sgn}(\sigma) = (-1)^n$ Because of Parity theorem this will be unique

Note: $\sigma = \gamma_1 \gamma_2 \dots \gamma_n$

as $(\gamma_i^{-1})^1 = \gamma_i$ we have
 $\sigma^{-1} = (\gamma_1 \gamma_2 \dots \gamma_n)^{-1} = \gamma_n \gamma_{n-1} \dots \gamma_1$

$$\sigma \sigma^{-1} = \gamma_1 \gamma_2 \dots \gamma_n \gamma_n \gamma_{n-1} \dots \gamma_1 = \gamma_1 \gamma_1$$

determinants again:

$$D: \underbrace{\mathbb{F}^n \times \mathbb{F}^n \times \dots \times \mathbb{F}^n}_{n \text{ times}} \rightarrow \mathbb{F}$$

① $D(a_1, \dots, a_n) = 0$ if $a_i = a_j, i \neq j$

② multilinearity i.e.

$$D(a_1, \dots, \lambda a + b, \dots, a_n) = \lambda D(a_1, \dots, a, \dots, a_n) + D(a_1, \dots, b, \dots, a_n)$$

$\therefore$ a linear map $\forall i=1, 2, \dots, n$

③ $D(e_1, \dots, e_n) = 1$

Note: $D(a_1, \dots, a_n)$

where

$$a_j = \begin{pmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{nj} \end{pmatrix} = a_{1j} e_1 + a_{2j} e_2 + a_{3j} e_3 + \dots = \sum_{i=1}^n a_{ij} e_i$$

(last time we did the row method, this one we follow now)

then $D(a_1, a_2, \dots, a_n)$

$$\begin{aligned} &= D\left(\sum_{i=1}^n a_{i1} e_i, \sum_{i=1}^n a_{i2} e_i, \dots, \sum_{i=1}^n a_{in} e_i\right) \\ &= \sum_f a_{f(1)} \dots a_{f(n)} D(e_{f(1)}, e_{f(2)}, \dots, e_{f(n)}) \\ &= \sum_{\sigma \in S_n} a_{\sigma(1)} \dots a_{\sigma(n)} D(e_{\sigma(1)}, \dots, e_{\sigma(n)}) \end{aligned}$$

To prove: $\sum_{\sigma \in S_n} a_{\sigma(1)} \dots a_{\sigma(n)} D(e_{\sigma(1)}, \dots, e_{\sigma(n)})$

proof: $D(e_{\sigma(1)}, \dots, e_{\sigma(n)}) \xrightarrow{1 \rightarrow \sigma(1)} = D(\sigma(e_1), \dots, \sigma(e_n)) \xrightarrow{e_i \rightarrow e_{\sigma(i)}} = \sum_{\sigma \in S_n} \text{sgn}(\sigma) a_{\sigma(1)} \dots a_{\sigma(n)}$

$$D(e_1, \dots, e_n) = D(\sigma^{-1} \circ \sigma(e_1, \dots, e_n)) = D(\sigma^{-1} \circ (e_{\sigma(1)}, \dots, e_{\sigma(n)}))$$

Because of the alternative prop now $\sigma = \gamma_1 \dots \gamma_k$ then $\text{sgn}(\sigma) = (-1)^k$ that we proved already $D(a, b) = -D(b, a)$
 $\Rightarrow \text{sgn}(\sigma) = (-1)^k$
 $\therefore D(e_{\sigma(1)}, \dots, e_{\sigma(n)}) = \text{sgn}(\sigma)$ as $D(e_1, \dots, e_n) = 1$

Defn: Let A be a $n \times n$ matrix over $\mathbb{F}$. If $A = (a_1, \dots, a_n)$, where $a_i \in \mathbb{F}^n$
then $\det A = D(a_1, \dots, a_n)$

Wok: $\det(AB) = \det(A) \det(B)$

9th sept: recap:

$$A = (a_1, \dots, a_n)$$
$$\det(A) = D(a_1, \dots, a_n)$$
$$= \sum_{\sigma \in S_n} \text{sgn}(\sigma) a_{\sigma(1)1} a_{\sigma(2)2} \dots a_{\sigma(n)n}$$

where $a_i = \begin{pmatrix} a_{i1} \\ \vdots \\ a_{ni} \end{pmatrix}, \forall i=1,2,\dots,n$

Theorem: for $A, B \in M_{n \times n}(F)$,

$$\det(AB) = \det(A)\det(B)$$

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & & & \\ \vdots & & & \\ a_{n1} & & & \end{bmatrix} \begin{bmatrix} b_{11} & \dots & b_{1n} \\ \vdots & & \vdots \\ b_{n1} & \dots & b_{nn} \end{bmatrix}$$

proof:

we know $\det(AB) = D(AB(e_1), AB(e_2), \dots, AB(e_n))$
where $\{e_1, e_2, \dots, e_n\}$ are standard basis of F^n .

$$\Rightarrow \det(AB) = D(AB^*1, AB^*2, \dots, AB^*n)$$

case I:

$$\det(A) \neq 0 \quad C: F^n \times F^n \times \dots \times F^n \rightarrow F$$

$$\text{define a map } C(x_1, x_2, \dots, x_n) = \frac{D(A(x_1), A(x_2), \dots, A(x_n))}{\det(A)}$$

Note: $x_i \in F^n$
(Not necessarily B^*i)

now, we want to see if C satisfies P_1, P_2, P_3

① let $x_i = x_j$ for $i \neq j$

$$\text{then } C(x_1, x_2, \dots, x_n) = \frac{D(A(x_1), \dots, A(x_i), \dots, A(x_i), \dots, A(x_n))}{\det(A)}$$

$$= \frac{0}{\det(A)} = 0$$

$$\text{as } A(x_i) = A(x_j)$$

② let $x_2, \dots, x_n \in F^n$ be fixed then

$$C(\alpha x + \beta y, x_2, \dots, x_n) = \frac{D(A(\alpha x + \beta y), A(x_2), \dots, A(x_n))}{\det(A)}$$

$$\alpha C(x) + \beta C(y) = \frac{\alpha D(A(x), A(x_2), \dots, A(x_n)) + \beta D(A(y), A(x_2), \dots, A(x_n))}{\det(A)}$$

$\therefore$ linear column wise
(multilinear)

$$\text{③ } C(e_1, e_2, \dots, e_n) = \frac{D(A^*1, A^*2, \dots, A^*n)}{\det(A)}$$

$$= 1 \quad \text{as } \det(A) = D(A^*1, \dots, A^*n)$$

By the uniqueness of D , we have

$$\det(B) = \frac{\det(AB)}{\det(A)}$$

$$\Rightarrow \det(AB) = \det(A)\det(B)$$

case II $\det(A) = 0$

consider $A(t) = A + tI$ for

$t \in [0, 1]$

$f: t \in [0, 1] \rightarrow \det(A(t))$

is a monic polynomial of degree n

$\therefore$ at most n zeroes (finitely many t 's)

$\therefore$ from 0 to the point where $\det(A(t)) = 0$
we can find many points where $\det(A(t)) \neq 0$
 $t \in (0, t_0)$

then by case I, $\det(A(t)B) = \det(A(t)) \det(B)$, $\forall t \in (0, t_0)$

$$\begin{bmatrix} a_{11}+t & & & \\ & a_{22}+t & & \\ & & \ddots & \\ & & & a_{nn}+t \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \dots \\ b_{21} & & \end{bmatrix} \rightarrow \det(A(t)B)$$

(as $\begin{bmatrix} a+t & b \\ c & d+t \end{bmatrix} \rightarrow \deg 2$)
can have at most t .

Now $\det(A(t)B)$ is a polynomial of degree at most n
and $\det(A(t))$ is a polynomial of degree n (monic)

Therefore by taking limit as $t \rightarrow 0$ in $\det(A(t)) \det(B)$
we get $\det(A) \det(B) = \det(AB)$

Proposition: Let $A \in M_{n \times n}(\mathbb{C})$. Then A is invertible iff $\det(A) \neq 0$

proof: ($\Rightarrow$) If A is invertible then

$$\det(I) = \det(A) \det(A^{-1})$$

$$\Rightarrow 1 = \det(A) \det(A^{-1})$$

$$\Rightarrow \det(A) = \frac{1}{\det(A^{-1})} \quad \therefore \det(A) \neq 0.$$

($\Leftarrow$) $0 \neq \det(A) = D(A^*1, A^*2, \dots, A^*n)$

this implies $\{A^*1, A^*2, \dots, A^*n\}$ are linearly independent

($\because$ if lin dep then $D = 0$) (Here columns are lin ind,
rank = n , range = $\mathbb{F}^n$
 $\therefore R_T = \mathbb{F}^n$)

As $\{A^*1, \dots, A^*n\}$

Note, $\{A^*1, \dots, A^*n\}$ is lin ind follows from a lemma already proved.

$$\Rightarrow \text{rank} = n$$

$$\Rightarrow RA = \mathbb{F}^n$$

$$\Rightarrow \text{nullity} = 0$$

$\therefore A: \mathbb{F}^n \rightarrow \mathbb{F}^n$ is one-one and onto

$\therefore A$ is isomorphism

$\Rightarrow A$ is invertible

Exercise: Show that similar matrices have same determinant. $\leftarrow$ done

Theorem: for $A \in M_{n \times n}(\mathbb{C} \text{ or } \mathbb{R})$, $\det(A) = \det(A^T)$

proof: If $A = (a_1, a_2, \dots, a_n)$, then $\det(A) = \sum_{\sigma \in S_n} \text{sgn}(\sigma) a_{\sigma(1)} \dots a_{\sigma(n)}$

$$= \sum_{\sigma \in S_n} \text{sgn}(\sigma) a'_{1\sigma(1)} \dots a'_{n\sigma(n)}$$

where $A^T = (a'_1, a'_2, \dots, a'_n)$

Note: $a'_{1\sigma(1)} = a'_{\sigma^{-1}(1)1}$

$$\begin{aligned} \text{so } \sum_{\sigma \in S_n} \text{sgn}(\sigma) a'_{1\sigma(1)} \dots a'_{n\sigma(n)} &= \sum_{\sigma \in S_n} \text{sgn}(\sigma^{-1}) a'_{\sigma^{-1}(1)1} \dots a'_{\sigma^{-1}(n)n} \\ &\quad \text{as } \text{sgn}(\sigma) = \text{sgn}(\sigma^{-1}) \\ &= \sum_{\sigma^{-1} \in S_n} \text{sgn}(\sigma^{-1}) a'_{\sigma^{-1}(1)1} \dots a'_{\sigma^{-1}(n)n} \\ &\quad \text{(as } S_n \text{ is a group, } \sigma \in S_n \Rightarrow \sigma^{-1} \in S_n) \end{aligned}$$

$$= \det(A^T)$$

$$\therefore \det(A) = \det(A^T)$$

$\det(A) = \sum (-1)^{i+j} a_{ij} A_{ij}$ minor

$$\begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & & & & \\ \vdots & & A & & \\ 0 & & & & \end{bmatrix} = B$$

then $\det(A) = \det(B)$

as $\sum_{\sigma \in S_n} \text{sgn}(\sigma) a_{\sigma(1)1} a_{\sigma(2)2} \dots$

here $a_{\sigma(1)1} = a_{11}$

else it is zero

$$\therefore \sum_{\sigma \in S_n} \text{sgn}(\sigma) a_{\sigma(2)2} \dots$$

this is $\det(A)$

$$= \sum_{\sigma \in S_{n-1}} \text{sgn}(\sigma) a_{\sigma(2)2} \dots$$

$$\det(B) = \det(A)$$

Exercise: Show that similar matrices have same determinant.

as $\exists S$ s.t.

$$B = SAS^{-1}$$

$$\det(B) = \det(A) \det(S) \det(S^{-1})$$

$$= \det(A) \det(I)$$

$$\det(B) = \det(A)$$

12th sept -

$$\det(A) = \sum_i (-1)^{i+j} (a_{ij}) A_{ij}$$



lemma: $D(a_1, a_2, \dots, a_{i-1}, e_j, a_{i+1}, \dots, a_n) = D(a_1 - a_{1j}e_j, a_2 - a_{2j}e_j, \dots, a_{i-1} - a_{(i-1)j}e_j, e_j, a_{i+1} - a_{(i+1)j}e_j, \dots, a_n - a_{nj}e_j)$

$$a_1 = a_{1j}e_j = \begin{pmatrix} a_{11} \\ a_{21} \\ \vdots \\ 0 \\ \vdots \\ a_{in} \end{pmatrix} \leftarrow j^{\text{th}} \text{ place}$$

$$\leftarrow a_1 = \begin{pmatrix} a_{11} \\ a_{12} \\ \vdots \\ a_{in} \end{pmatrix}$$

$\forall a_i \in \mathbb{F}^n, e_j = (0, 0, \dots, 1, 0, 0, \dots)$
 $\dots a_n - a_{nj}e_j$
 $j^{\text{th}} \text{ place}$

$$\det \begin{bmatrix} a_{11} & \dots & a_{1n} \\ a_{21} & \dots & a_{2n} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} = \det \begin{bmatrix} a_{11} & \dots & 0 & \dots & a_{1j} \\ \vdots & & 0 & \dots & 0 \\ \vdots & & 0 & \dots & 0 \\ a_{n1} & \dots & 0 & \dots & a_{nn} \end{bmatrix}$$

proof: $D(a_1, a_2, \dots, a_n) = D(a_1 + \lambda a_2, a_2, a_3, \dots, a_n)$
as $D(\lambda a_2, a_2, \dots, a_n) = 0$

$$\Rightarrow D(a_1, a_2, \dots, e_j, \dots, a_n) = D(a_1 + \lambda_1 e_j, a_2 + \lambda_2 e_j, \dots, a_n)$$

$$\Rightarrow D(a_1, a_2, \dots, e_j, \dots, a_n) = D(a_1 - a_{1j}e_j, a_2 - a_{2j}e_j, \dots, e_j, \dots, a_n - a_{nj}e_j)$$

$\lambda_i = a_{ij} \text{ other than } i=j$

lemma: $\det \begin{pmatrix} 1 & x & x & \dots & x \\ \vdots & & & & \\ 0 & & A & & \end{pmatrix}_{n \times n} = \det(A)$

proof: $\det \begin{pmatrix} 1 & x & x & \dots & x \\ \vdots & & & & \\ 0 & & A & & \end{pmatrix}_{n \times n} = \det \begin{pmatrix} 1 & 0 & \dots & 0 \\ \vdots & & & \\ 0 & & A & \end{pmatrix}_{n \times n}$
from the previous lemma

$$\sigma = \begin{pmatrix} 1 & 2 & \dots & n \\ 1 & \sigma(2) & \dots & \sigma(n) \end{pmatrix}$$

$\text{sgn}(\sigma) = \text{sgn}(\sigma')$
 $\sigma' = \begin{pmatrix} 2 & 3 & \dots & n \\ \sigma(2) & \sigma(3) & \dots & \sigma(n) \end{pmatrix}$

Define $c: \mathbb{F}^{n-1} \times \mathbb{F}^{n-1} \times \dots \times \mathbb{F}^{n-1} \rightarrow \mathbb{F}$

$$c(a_1, a_2, \dots, a_{n-1}) = D(e_1, \hat{a}_1, \hat{a}_2, \dots, \hat{a}_{n-1})$$

where $\hat{a}_i = \begin{pmatrix} 0 \\ a_{1i} \\ a_{2i} \\ \vdots \\ a_{n-1,i} \end{pmatrix}, \forall i = \{1, 2, \dots, n-1\}$

$$\begin{aligned} \textcircled{1} c(a_1, a_1, a_3, \dots, a_{n-1}) &= D(e_1, \hat{a}_1, \hat{a}_1, \dots, \hat{a}_{n-1}) = 0 \\ \textcircled{2} c(a_1, a_2, \dots, \lambda a + b, \dots, a_{n-1}) &= D(e_1, \hat{a}_1, \dots, \lambda \hat{a} + \hat{b}, \dots, \hat{a}_{n-1}) \\ &= \lambda D(e_1, \hat{a}_1, \dots, \hat{a}, \dots, \hat{a}_{n-1}) + D(e_1, \hat{a}_1, \dots, \hat{b}, \dots, \hat{a}_{n-1}) \end{aligned}$$

$$\begin{aligned} \textcircled{3} c(e_1, e_2, \dots, e_{n-1}) &= D(e_1, \hat{e}_1, \hat{e}_2, \dots, \hat{e}_{n-1}) \\ &= D(e_1, e_2, e_3, \dots, e_n) \\ &= 1 \end{aligned}$$

as c satisfies all these properties,

$$c(a_1, a_2, \dots, a_{n-1}) = \det(A)$$

$$\therefore \det \begin{pmatrix} 1 & 0 & \dots & 0 \\ \vdots & & & \\ 0 & & A & \end{pmatrix} = \det(A)$$

Lemma: If j^{th} column of a matrix A is e_i , then $\det(A) = (-1)^{i+j} A_{ij}$, where A_{ij} is the matrix obtained from A by striking i^{th} row and j^{th} column.

$$\begin{aligned} \det \begin{pmatrix} a_{11} & a_{12} & \dots & 0 & \dots \\ \vdots & \vdots & \ddots & \vdots & \ddots \\ a_{ji} & \dots & \dots & 0 & \dots \\ \vdots & \vdots & \ddots & \vdots & \ddots \\ 0 & \dots & \dots & 0 & \dots \end{pmatrix}_{n \times n} &= (-1)^{i-1} \det \begin{pmatrix} 0 & a_{11} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{pmatrix}_{n \times n} \\ \text{we swap } i-1 \text{ times} &= (-1)^{i-1} \det \begin{pmatrix} 0 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 1 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & \dots \end{pmatrix}_{n \times n}^T \\ &= (-1)^{i-1+j-1} \det \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & \dots & \dots & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & \dots & 0 & A_{ij}^T \end{pmatrix}_{n \times n} \\ &= (-1)^{i+j} \det \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & \dots & \dots & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & \dots & 0 & A_{ij} \end{pmatrix}_{n \times n} \end{aligned}$$

proof: we define $C: \mathbb{F}^{n-1} \times \mathbb{F}^{n-1} \times \dots \times \mathbb{F}^{n-1} \rightarrow \mathbb{F}$

$$\det \begin{pmatrix} x & x & x & \vdots & x & x \\ & & & 1 & & \\ & & & & & \end{pmatrix}_{n \times n} = \det \begin{pmatrix} \vdots & & & 0 & \vdots \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ & & & 0 & & & \end{pmatrix}_{n \times n} = c(a_1, a_2, \dots, a_{n-1}) (-1)^{i+j}$$

$$C: \mathbb{F}^{n-1} \times \mathbb{F}^{n-1} \times \dots \times \mathbb{F}^{n-1} \rightarrow \mathbb{F} \text{ by}$$

$$C(a_1, a_2, \dots, a_{n-1}) = (H)^{i+j} (a_1, a_2, \dots, a_{j-1}, e_i, \dots, a_n)$$
 where $a_k = \begin{pmatrix} a_{1r} \\ a_{2r} \\ \vdots \\ a_{i-1r} \\ 0 \\ \vdots \\ a_{n-1r} \end{pmatrix}$

check that C has all these properties
done done

Theorem: Let $A \in M_{n \times n}(\mathbb{F})$, then $\det(A) = \sum_{j=1}^n (-1)^{i+j} a_{ij} \det(A_{ij})$

and $A_{ij} \in M_{(n-1) \times (n-1)}(\mathbb{F})$ obtained by taking out its row and j th column of A .

Proof: wlog

$$\begin{aligned} \det(A) &= D(a_1, \dots, a_n) \\ &= D(\sum a_{ii} e_i, \dots, a_n) \\ &= \sum a_{ii} D(e_i, \dots, a_n) \\ &= \sum a_{ii} (-1)^{i+1} D(A_{ii}) \end{aligned}$$

These calculation of a determinant $\leftarrow$ done down

Defn: $A \in M_{n \times n}(\mathbb{F})$, then $\text{tr}(A) = \sum_{i=1}^n a_{ii}$

Theorem: $\text{tr} : M_{n \times n}(\mathbb{F}) \rightarrow \mathbb{F}$ is a linear function. Moreover $\text{tr}(AB) = \text{tr}(BA)$

proof: if $\text{tr}(\alpha A + \beta B) = \alpha \text{tr}(A) + \beta \text{tr}(B)$
 $\forall A, B \in M_{n \times n}(\mathbb{F})$,
 $\alpha, \beta \in \mathbb{F}$

$$\begin{aligned}\text{tr}(\alpha A + \beta B) &= \sum (a_{ii} + \beta b_{ii}) \\ &= \alpha \sum a_{ii} + \beta \sum b_{ii} \\ &= \alpha \text{tr}(A) + \beta \text{tr}(B)\end{aligned}$$

$$\begin{aligned}\text{tr}(AB) &= \sum (AB)_{ii} = \sum_{i=1}^n \left(\sum_{k=1}^n a_{ik} b_{ki} \right) \\ &= \sum_{k=1}^n \left(\sum_{i=1}^n b_{ki} a_{ik} \right) \\ &= \sum_{k=1}^n (BA)_{kk} \\ &= \sum_{i=1}^n (BA)_{ii} = \text{tr}(BA)\end{aligned}$$

propn: If A, B are similar matrices then $\text{tr}(A) = \text{tr}(B)$

proof: $A = SBS^{-1}$
 $\text{tr}(A) = \text{tr}(SBS^{-1})$
 $= \text{tr}(S^{-1}SB)$
 $= \text{tr}(B)$

show $\det \begin{pmatrix} \vdots & 0 & \vdots \\ 0 & 0 & 0 \\ \vdots & 0 & \vdots \end{pmatrix} = C(a_1, a_2, \dots, a_{n-1}) (-1)^{i+j}$, C is a determinant

$$C : \underbrace{\mathbb{F}^{n-1} \times \mathbb{F}^{n-1} \times \dots \times \mathbb{F}^{n-1}}_{n-1 \text{ times}} \rightarrow \mathbb{F}$$

$$C(a_1, a_2, \dots, a_{n-1}) = D(\hat{a}_1, \hat{a}_2, \dots, \hat{a}_{i-1}, e_j, \hat{a}_{i+1}, \dots, \hat{a}_n)$$

$$\begin{aligned}\det(A_{ij}) &= (-1)^{i+j} D(e_1, \hat{a}_1, \hat{a}_2, \dots, \hat{a}_{i-1}) \\ &= (-1)^{i+j} \det(A)\end{aligned}$$

$$\Rightarrow \det(A) = (-1)^{i+j} \det(A_{ij})$$

Inverse calculation of a determinant

$$(-1)^{ij} A_{ij} = \text{cofactor} = C_{ij}(A)$$

$$\text{adj } A = [C_{ij}(A)]^T$$

$$A(\text{adj } A) = \det(A) I$$

$$\begin{aligned}\text{also } A(\text{adj } A) &= [a_{ij}] [C_{ij}(A)]^T \\ \Rightarrow A^{-1} &= \frac{\text{adj } A}{\det(A)}\end{aligned}$$

also

$$\begin{bmatrix} 1 & 2 & 6 \\ 2 & 3 & 4 \\ 3 & 4 & 2 \end{bmatrix}^T \times \frac{1}{\det A} = A^{-1}$$

23rd sept -

Defn: The eigenvalue of $A \in M_{n \times n}(\mathbb{C})$ is $\lambda \in \mathbb{C}$ s.t. $Ax = \lambda x$ for some non-zero vector $x \in \mathbb{C}^n$. In such a case the vector x is called the eigenvector corr. to the eigenvalue λ .

Given $A \in M_{n \times n}(\mathbb{C})$, we consider a non-zero vector $x \in \mathbb{C}^n$. Clearly $\forall u, Au, A^2u, A^3u, \dots, A^nu \in \mathbb{C}^n$

we know

$\{u, Au, \dots, A^nu\}$ is linearly dependent.

(as $\dim \mathbb{C}^n = n$, and $u, Au, \dots, A^nu$ is $n+1$)

$\exists c_i \in \mathbb{C}$, not zero s.t.

$$\sum_{i=0}^n c_i A^i u = 0 \quad c_i \neq 0 \quad \text{--- ①}$$

let $p(t) = \sum_{i=0}^n c_i t^i$ for $t \in \mathbb{C}$

our polynomial (degree n , n roots say $\lambda_1, \lambda_2, \dots, \lambda_n$)

$$p(t) = c_n \prod_{i=1}^n (t - \lambda_i) \quad \text{for some } \lambda_i \in \mathbb{C}$$

now

$$p(A)u = \left(\sum_{i=0}^n c_i A^i \right) u = 0$$

from ①

$$\Leftrightarrow \prod_{i=1}^n (A - \lambda_i I) u = 0 \quad (u \neq 0) \quad (\text{ker} \neq \{0\})$$

$$\Leftrightarrow \prod_{i=1}^n (A - \lambda_i I) \text{ is non invertible (as ker contains a non-zero } \lambda_i)$$

$$\Leftrightarrow \det(A - \lambda_i I) = 0 \quad \text{for some } i$$

$$\Leftrightarrow (A - \lambda_i I)y = 0 \quad \text{for some } 0 \neq y \in \mathbb{C}^n$$

$$\Leftrightarrow Ay = \lambda_i y \quad \text{for some } 0 \neq y \in \mathbb{C}^n$$

Result: λ is an eigen-value of $A \Leftrightarrow \det(A - \lambda I) = 0$

Defn: The characteristic polynomial of A is:

$$\lambda \mapsto \det(A - \lambda I)$$

λ is an eigenvalue of A

$\Leftrightarrow \lambda$ is a root

for the char. polynomial

Note for $A \in M_{n \times n}(\mathbb{C})$, u_0

$$\text{where } Au_0 = \lambda' u_0$$

$$A \cdot Au_0 = A \lambda' u_0$$

$$= A u_0 \lambda'$$

$$= \lambda' u_0 \lambda'$$

$$A^2 u_0 = \lambda'^2 u_0$$

$$\text{or } A^n u_0 = \lambda'^n u_0$$

$$\forall n = 0, 1, 2, \dots, n$$

Defn: Markov matrix:

- ① entries of a markov matrix is always positive
- ② sum of entries in each column is 1

Note: if λ is an eigenvalue, then λ is also an eigenvalue of A^T as

$$(A - \lambda I)^T = A^T - \lambda I^T$$

$$= A^T - \lambda I$$

$$\text{as } \det(A - \lambda I)^T = \det(A - \lambda I) = \det(A^T - \lambda I)$$

$A \rightarrow$ markov matrix, then sum of columns =

$$A^T = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \rightarrow \text{sum of rows} = 1$$

$$A^T \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = (1) \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

so $x = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ is a eigenvector to A^T

$\Rightarrow \lambda = 1$ is eigenvalue to A^T
 $\Rightarrow \lambda = 1$ is eigenvalue to A

Properties of Markov matrices: ($A \in M_{n \times n}(\mathbb{C})$) (general case)

① All the remaining eigenvalues of A have modulus strictly less than 1.

② A has n no. of linearly independent eigenvectors.
 $\{x_1, x_2, \dots, x_n\}$ where
 $Ax_i = \lambda_i x_i$
 where $\lambda_1 = 1$
 so $Ax_1 = x_1$

Now $0 \neq u_0 \in \mathbb{C}^n$

by hypothesis,
 $u_0 = \sum_{i=1}^n c_i x_i$ for some $c_i \in \mathbb{C}$

$$Au_0 = \sum_{i=1}^n c_i \lambda_i x_i$$

$$A^m u_0 = \sum_{i=1}^n c_i \lambda_i^m x_i$$

$$= c_1 x_1 + \sum_{i=2}^n c_i \lambda_i^m x_i$$

as $|\lambda_i| < 1$
 at steady state

$$A^m u_0 = c_1 x_1$$

Fibonacci numbers -

0, 1, 1, 2, 3, 5, 8, ...

$$\left. \begin{array}{l} F_{n+2} = F_{n+1} + F_n \\ F_{n+1} = F_{n+1} \end{array} \right\} \rightarrow v_{n+2} = \begin{bmatrix} F_{n+2} \\ F_{n+1} \end{bmatrix} = \begin{bmatrix} F_{n+1} + F_n \\ F_{n+1} + 0 \cdot F_n \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}}_A \underbrace{\begin{bmatrix} F_{n+1} \\ F_n \end{bmatrix}}_{v_{n+1}}$$

$$\text{so } v_{n+2} = A v_{n+1}$$

$$v_{n+1} = A v_n$$

$$\vdots$$

$$v_{n+1} = A^n v_1$$

$$= A^n \begin{bmatrix} F_1 \\ F_0 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 1 \\ 1 & -\lambda \end{vmatrix} = (1-\lambda)(-\lambda) - (1) = 0$$

$$\begin{aligned}
 -\lambda + \lambda^2 - 1 &= 0 \\
 \lambda^2 - \lambda - 1 &= 0 \\
 \lambda &= \frac{1 \pm \sqrt{1+4}}{2} \\
 \lambda &= \frac{1 \pm \sqrt{5}}{2}
 \end{aligned}$$

or eigenvalues of $A = \lambda_1, \lambda_2$
 $= \frac{1+\sqrt{5}}{2}, \frac{1-\sqrt{5}}{2}$

now $Ax_1 = \lambda_1 x_1$
 for $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} x_1 = \left(\frac{1+\sqrt{5}}{2}\right) x_1$
 $x + y = \left(\frac{1+\sqrt{5}}{2}\right) x$

$$x = \left(\frac{1+\sqrt{5}}{2}\right) y$$

$$x_1 = \begin{pmatrix} \frac{1+\sqrt{5}}{2} \\ 1 \end{pmatrix}$$

$$x_2 = \begin{pmatrix} \frac{1-\sqrt{5}}{2} \\ 1 \end{pmatrix}$$

$$\begin{aligned}
 v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} &= \underbrace{\frac{1}{\sqrt{5}}}_{c_1} \underbrace{\begin{pmatrix} \frac{1+\sqrt{5}}{2} \\ 1 \end{pmatrix}}_{x_1} + \underbrace{\frac{-1}{\sqrt{5}}}_{c_2} \underbrace{\begin{pmatrix} \frac{1-\sqrt{5}}{2} \\ 1 \end{pmatrix}}_{x_2}
 \end{aligned}$$

$$\begin{aligned}
 v_1 &= c_1 x_1 + c_2 x_2 \\
 v_{n+1} &= A^n v_1 \\
 &= A^n c_1 x_1 + A^n c_2 x_2 \\
 &= c_1 \lambda_1^n x_1 + c_2 \lambda_2^n x_2 \\
 &= c_1 \left(\frac{1+\sqrt{5}}{2}\right)^n x_1 + c_2 \left(\frac{1-\sqrt{5}}{2}\right)^n x_2
 \end{aligned}$$

then $F_{n+1} = \frac{1}{\sqrt{5}} \left(\frac{1+\sqrt{5}}{2}\right)^n \left(\frac{1+\sqrt{5}}{2}\right) - \frac{1}{\sqrt{5}} \left(\frac{1-\sqrt{5}}{2}\right)^n \left(\frac{1-\sqrt{5}}{2}\right)$

$$\begin{aligned}
 &= \frac{1}{\sqrt{5}} \left(\frac{1+\sqrt{5}}{2}\right)^{n+1} - \underbrace{\frac{1}{\sqrt{5}} \left(\frac{1-\sqrt{5}}{2}\right)^{n+1}}_{< 1/2}
 \end{aligned}$$

$$= \text{nearest integer of } \frac{1}{\sqrt{5}} \left(\frac{1+\sqrt{5}}{2}\right)^{n+1}$$

(Keep the estimation in mind)

26th Sept -

Theorem: let $A \in M_{n \times n}(\mathbb{C})$. The eigenvectors corresponding to different eigenvalues are linearly independent.

proof: let v_i be an eigenvector corresponding to an eigenvalue $\lambda_i, i=1,2,\dots,m$ and they are all different. ($\lambda_i \neq \lambda_j$) $\forall i \neq j$

Suppose that $\sum_{i=1}^m c_i v_i = 0$ and $c_i \neq 0, \forall i=1,2,\dots,m$

$$\left(\text{Note: } f(t) = \sum_{n=0}^s a_n t^n \leftarrow \text{polynomial} \right)$$

$$f(A) = \sum_{n=0}^s a_n A^n \leftarrow A^0 = I$$

$$\begin{aligned} \text{now, } 0 &= f(A) \left(\sum_{i=1}^m c_i v_i \right) = \sum_{i=1}^m c_i f(A) v_i \\ &= \sum_{i=1}^m c_i f(\lambda_i) v_i \\ 0 &= \sum_{i=1}^m c_i f(\lambda_i) v_i \end{aligned}$$

$$0 = \sum_{i=1}^m (c_i f(\lambda_i)) v_i \quad \text{for any polynomial } f \in \mathbb{C}[z]$$

we choose polynomial in one variable, complex coefficients

taking a polynomial f_i s.t

(Lagrange polynomial) $f_i(\lambda_j) = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{otherwise} \end{cases}$

(example: $f_i = \frac{\prod_{j \neq i} (t - \lambda_j)}{\prod_{j \neq i} (\lambda_i - \lambda_j)}$)

Now, $f_i(\lambda_i) = 1$
else 0
so

putting $f = f_i$ we get

$$0 = \sum_{i=1}^m c_i f_i(\lambda_i) v_i$$

$$0 = \underbrace{c_i f_i(\lambda_i)}_1 v_i + 0 + 0 + \dots + 0$$

$$0 = c_i v_i$$

$$\text{as } c_i \neq 0$$

$$\Rightarrow v_i = 0$$

i.e. the eigenvector is 0, which is a contradiction.

so, if $\sum_{i=1}^m c_i v_i = 0$ then $c_1 = c_2 = \dots = c_m = 0$

Theorem: if $A \in M_{n \times n}(\mathbb{C})$ has distinct eigenvalues then there is a basis of $\mathbb{C}^n$ consist of eigenvectors of A .

proof: $A \in M_{n \times n}(\mathbb{C}), A v_i = \lambda_i v_i \quad \forall i=1,2,\dots,n$ (this is a special case)
 $\Leftrightarrow \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \lambda_n \end{bmatrix}$ or A is a diagonal matrix with diagonal entries λ_i 's (we have to show)

defn: Diagonalisable - If a matrix $A \in M_{n \times n}(\mathbb{C})$ is diagonalizable if $\exists$ an invertible matrix $P \in M_{n \times n}(\mathbb{C})$ s.t $P^{-1}AP$ is a diagonal matrix.

Now, $P^{-1}AP$ is diagonal $\Leftrightarrow (P^{-1}AP)(e_i) = \lambda_i(e_i), \forall i=1,2,\dots,n$
 $\Leftrightarrow A(P(e_i)) = P(\lambda_i(e_i))$
 $\Leftrightarrow AP(e_i) = \lambda_i P(e_i)$
 $\Leftrightarrow AP_i = \lambda_i P_i$

(This is a general case)

Note $\{P(e_i) \mid i=1,2,\dots,n\}$ forms a basis consisting of eigenvectors of A .

Note: A is diagonalisable $\Leftrightarrow A$ has n -distinct eigenvalues.

characteristic polynomial: $X_A(t) = \det(tI - A)$ of A .

Note: roots of X_A are eigenvalues of A .

Theorem: If $a_1, a_2, \dots, a_n$ are eigenvalues of $A \in M_{n \times n}(\mathbb{C})$, then
 $\text{tr}(A) = \sum_{i=1}^n a_i$
 $\det(A) = \prod_{i=1}^n a_i$
 and $X_A(t) = t^n - \text{tr}(A)t^{n-1} + \dots + (-1)^n \det A$
 (sum of roots and product of roots approach)

proof: $X_A(t) = \prod_{i=1}^n (t - a_i)$

$$= \det(tI - A)$$

$$= \det \begin{bmatrix} t-a_{11} & \dots & -a_{1n} \\ -a_{21} & t-a_{22} & \dots \\ \vdots & \ddots & \vdots \\ -a_{n1} & \dots & t-a_{nn} \end{bmatrix}$$

the coefficients of t^n, t^{n-1} appear from

$$\prod_{i=1}^n (t - a_i)$$

$\Rightarrow$ the coefficients of t^n is one and t^{n-1} is $-(\sum_{i=1}^n a_i)$

(Note, $\det(A) = \prod a_i$ follows from $t=0$) $= -\text{tr}(A)$

$$\text{thus } X_A(t) = t^n - \text{tr}(A)t^{n-1} + \dots + (-1)^n \det(A)$$

Since roots of the char. polynomial are the eigenvalues of A ,

$$X_A(t) = \prod_{i=1}^n (t - a_i) = t^n - (a_1 + \dots + a_n)t^{n-1} + \dots + (-1)^n \prod_{i=1}^n a_i$$

By comparing coefficients, $\text{tr}(A) = \sum_{i=1}^n a_i$

$$\det(A) = \prod_{i=1}^n a_i$$

Theorem: (Spectral mapping theorem) for any polynomial $P \in \mathbb{C}[Z]$ and $A \in M_{n \times n}(\mathbb{C})$, then $P(\sigma(A)) = \sigma(P(A))$

$(\sigma(A) = \text{spectrum of } A = \text{set of all eigenvalues of } A)$

Proof: It is trivial to see that if λ is an eigenvalue of A , then $P(\lambda)$ is an eigenvalue of $P(A)$.

$$\Rightarrow P(\sigma(A)) \subseteq \sigma(P(A))$$

Now, take $b \in \sigma(P(A))$ and consider

$$p(t) - b = c \prod_{i=1}^n (t - a_i)$$

(assuming $p(t)$ is not const
as const case is trivial)

as $b \in \sigma(P(A))$

$P(A) - bI$ is non-invertible

$$P(A) - bI = c \prod_{i=1}^n (A - a_i I)$$

as product is non-invertible
 $\Rightarrow$ at least one term
non-invertible.

since $P(A) - bI$ is non-invertible,

$(A - a_i I)$ is non-invertible for some $1 \leq i \leq n$
therefore a_i is an eigenvalue

or $a_i \in \sigma(A)$ and

$$p(t) - b = c \prod_{i=1}^n (t - a_i) \text{ vanishes at } a_i$$

$$\Rightarrow p(a_i) = b$$

or $b \in \sigma(P(A))$

then $b \in P(\sigma(A))$

as $a_i \in \sigma(A)$

and $p(a_i) = b$

$$\therefore \sigma(P(A)) \subseteq P(\sigma(A))$$

$$\therefore \sigma(P(A)) = P(\sigma(A))$$

Note: for $P = \chi_A(t)$

$$\sigma(\chi_A(A)) = \chi_A(\sigma(A)) = \{0\}$$

χ_A has roots as eigenvalues of A

30th sept:

$T \in M_{n \times n}(\mathbb{C})$

Basis of $M_{n \times n}(\mathbb{C}) = n^2$

(for $M_{n \times m}(\mathbb{C})$ should be $\dim = mn$)

$I, T, T^2, T^3, \dots, T^{n^2}$

as $n^2 + 1$ elements, and $\dim$ of $M_{n \times n}(\mathbb{C}) = n^2$,
 $\{I, T, T^2, \dots, T^{n^2}\}$ is lin dep.

$$\sum_{i=0}^{n^2} \alpha_i T^i = 0 \text{ for some } \alpha_i \neq 0.$$

$$\Leftrightarrow P(T) = 0, \text{ where } P(t) = \sum_{i=0}^{n^2} \alpha_i t^i$$

Note: $P(T) = \sum_{i=0}^{n^2} \alpha_i T^i$
so $\exists T \in M_{n \times n}(\mathbb{C})$ s.t. $P(T) = 0$

$\therefore$ given any square matrix, $\exists$ a non-zero polynomial which annihilates the matrix.

$\tau = \{P \in \mathbb{C}[Z] \mid P(T) = 0\}$ is an ideal because if $P \in \tau$
and $Q \in \mathbb{C}[Z]$ then $PQ(T) = P(T)Q(T) = 0 \cdot Q(T) = 0$
 $\Rightarrow PQ \in \tau$

Defn I is a principle ideal if

$$I = \langle P \rangle \text{ for some } P \in \mathbb{C}[Z]$$

Note: P is unique monic polynomial

(if P is smallest degree P in I , or $\deg P \leq \deg \chi$ $\forall \chi \in I$)

$$\left(\begin{array}{l} q \in I, q = pf + h \\ \in I \quad \in I \quad \deg(h) < \deg(P) \end{array} \right)$$

$\deg(h) = 0$
 $\therefore$ every q is of form of $g = pf \Rightarrow g \in \langle P \rangle$

such P is called a minimal polynomial of T .

Defn: P is a minimal polynomial of T if

① $P(T) = 0$

② if $Q(T) = 0$ then $q(x) = P(x)\sigma(x)$ for some $\sigma(x) \in \mathbb{C}[X]$
or $q \in \langle P \rangle$
or $P \mid q$

Note: How do we find minimal polynomial of T :

we know that $P'(T) = \sum \alpha_i T^i$
so $\deg(P) \leq n^2$

Theorem: The roots of minimal polynomial of T and characteristic polynomial of a matrix (T) are same.

roots of $\chi_T =$ roots of P (minimal polynomial)

proof: Enough to show that root of $P \Leftrightarrow$ root of χ_T
 i.e. if λ is the root of minimal polynomial of T
 iff λ is the eigenvalue of T .

let P be the minimal polynomial of T .

Suppose $P(\lambda) = 0$

then

$$P(t) = (t - \lambda)q(t)$$

$$\text{then } P(T) = (T - \lambda I)q(T)$$

$$= 0$$

$$(T - \lambda I)q(T) = 0$$

$$\text{as } \deg(q) < \deg(P)$$

$$q(T) \neq 0$$

as P is the minimum deg polynomial with

$$P(T) = 0$$

$\therefore q(T)$ is a non-zero matrix

as $q(T)$ is a non-zero matrix

take a non-zero $h \in \mathbb{C}^n$ s.t

$$q(T)h = x \text{ is non-zero}$$

so

$$(T - \lambda I)q(T)h = 0 \cdot h = 0$$

$$\Rightarrow (T - \lambda I)x = 0 \text{ for some } x \neq 0$$

$$\ker(T - \lambda I) \neq \{0\}$$

$$\therefore \det(T - \lambda I) = 0$$

$$\Rightarrow \lambda \text{ is a root of } \chi_T$$

$\therefore \lambda$ is an eigenvalue

conversely let λ be an eigenvalue of T

$$\text{as } \sigma(P(T)) = P(\sigma(T))$$

$$\lambda \in \sigma(T)$$

Note: $P(T) = 0$ (0 matrix)

$$\longrightarrow \sigma(0) = 0 \text{ (0 matrix spectrum)}$$

$$\{0\} = \sigma(P(T)) = P(\sigma(T))$$

this means that

$$P(\lambda) = 0$$

$$\text{as } \lambda \in \sigma(T)$$

$\therefore \lambda$ is a root of P .

$\left(\begin{array}{l} \sigma(0) = 0 \text{ as} \\ \text{eigenvalues of} \\ 0 \text{ matrix s.t} \\ 0x = \lambda x \\ 0 = \lambda x \Rightarrow \lambda = 0 \\ \text{for } x \neq 0 \end{array} \right)$

Note: If T has n distinct eigenvalues $\lambda_1, \dots, \lambda_n$ then

$\in M_{n \times n}(\mathbb{C})$

$$P(t) = (t - \lambda_1) \cdots (t - \lambda_n)q(t) \leftarrow \text{will have a root but}$$

$$P(t) = (t - \lambda_1) \cdots q(t) \quad \therefore \text{const} \leftarrow \text{not a polynomial}$$

$$p(t) = q_0 \chi_T(t)$$

but

$q_0 = 1$ for p to be monic

$$\therefore p(t) = (t - \lambda_1)(t - \lambda_2) \cdots (t - \lambda_n)$$

↑
monic polynomial (minimal for T)

Note: If all λ_i are distinct, then T is a diagonalisable matrix

$\therefore$ If T is diagonalisable then $p(t) = (t - \lambda_1)(t - \lambda_2) \cdots (t - \lambda_n)$

prop: minimal polynomial of T = minimal polynomial of R
if $T = SRS^{-1}$ where $S \in M_{n \times n}(\mathbb{C})$
 T is similar to R ($T \sim R$)

proof: Suppose $P^{-1}TP = T'$
(i.e. $T \sim T'$)

if $f(T') = 0$
→ Anniates T'

then $f(P^{-1}TP) = f(T') = 0$
 $= P^{-1}f(T)P$
as P is invertible, so is P^{-1} .

$$\left(\begin{array}{l} (P^{-1}TP)^n = P^{-1}T^nP \\ \text{eg. } \forall n \in \mathbb{N} \\ P^{-1}TP P^{-1}TP = P^{-1}T^2P \end{array} \right)$$

$$\text{now } f(T') = 0 \quad \forall f \in \mathbb{C}[Z] \\ \Rightarrow f(T) = 0$$

$$\therefore \text{ if } P_{T'}(T') = 0 \\ \text{ then } P(T) = 0 \\ \text{ or } \langle P_{T'} \rangle \subseteq \langle P_T \rangle$$

$$\text{Similarly } \langle P_T \rangle \subseteq \langle P_{T'} \rangle \\ \text{ or } \langle P_T \rangle = \langle P_{T'} \rangle$$

as P 's are unique

$$\Rightarrow P_T = P_{T'} \text{ say } P$$

or minimal polynomial of T = minimal polynomial of T'

Note: If T is diagonalisable, then $p(t) = (t - \lambda_1)(t - \lambda_2) \cdots (t - \lambda_n)$
where $\lambda_1, \lambda_2, \dots, \lambda_n$ are distinct eigenvalues

As similar matrices have same minimal polynomial.

$$T \sim \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

as T is diagonalisable, it is similar to $\begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$

minimal polynomial of $\begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} = (t-\lambda_1)(t-\lambda_2)\dots(t-\lambda_n) = P(t)$ → distinct ones that appear
 = minimal polynomial of T

∴ minimal polynomial of $T = (t-\lambda_1)(t-\lambda_2)\dots(t-\lambda_n)$

Note: No need to take power, if we only take diff eigenvalues we find minimal polynomial.

Theorem: (Caley-Hamilton theorem)
 $\chi_T(T) = 0$ for any $T \in M_{n \times n}(\mathbb{C})$

(χ_T annihilates T or $\chi_T \in \langle P \rangle$ where $P = \text{minimal polynomial of } T$)

Note: $\phi(t) = \sum_{n=0}^m A_n t^n$ → matrix valued polynomials
 where A_n are matrices of fixed size

$$\phi(T) = \sum_{n=0}^m A_n T^n \text{ where } T^0 = I$$

→ same order as coefficients

$$q(t) = \sum_{n=0}^k B_n t^n \text{ another sum matrix valued polynomial}$$

$$pq(t) = \sum_{n=0}^{m+k} C_n t^n \text{ where } C_n = \sum_{r+s=n} A_r B_s$$

$$pq(T) = \sum_{n=0}^{m+k} C_n T^n = P(T)q(T)$$

if T commutes with B_n 's

$$\phi(t) = \begin{bmatrix} p_{11}(t) & p_{12}(t) & \dots & \dots \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

because all polynomials, collect all w.r.t t

↓
gives us matrix

$$\text{so } \phi(t) = \sum_{n=0}^m A_n t^n$$

proof: Take $\phi(s) = (T - sI)$
 → matrix valued polynomial

let $q(s)$ be the Adj $P(t)$

$\uparrow$
is also a matrix valued polynomial

$q(s)P(s) = X_T(s)I \leftarrow$ roots of X_T are
const of $P(s)$ is either in T or in $T-s^-$ roots of minimal polynomial

$$\Rightarrow q(T)P(T) = X_T(T) \cdot I$$

$\uparrow$
maximal polynomial

$$\Rightarrow X_T(T) = 0$$

or
minimal polynomial
 $\text{pol } X_T(s) = q(s) \times p(s)$

$$q(T)P(T) = 0$$

or $X_T(T) = 0$

Note: if $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$

$$\text{then } C_{31} = (-1)^{3+1} A_{31}$$

$$C_{ij} = (-1)^{i+j} A_{ij}$$

$$\text{Adj}(A) = \begin{bmatrix} C_{11} & C_{12} & C_{13} \\ C_{21} & C_{22} & C_{23} \\ C_{31} & C_{32} & C_{33} \end{bmatrix}^T$$

$$\text{and } A \text{Adj}(A) = |A|I$$

$$\text{or } \frac{1}{|A|} \text{Adj}(A) = A^{-1}$$

3rd Oct:

finite dimensional vector space:

let V be a finite dimensional vector space, and let W_i be subspaces of V . Then $W = W_1 + \dots + W_n$

$\uparrow$
this is a subspace of V . (satisfies $u \in W, v \in W$
then $u + \alpha v \in W$)

(direct sum : every vector in W , can be expressed uniquely
if as sum of $W_1, W_2, \dots, W_n$)

defn: (Equivalent to direct sum)

we say $\{W_i\}$ are independent if $x_i \in W_i$ and

$$x_1 + x_2 + \dots + x_n = 0 \Rightarrow x_i = 0 \quad \forall i$$

prop: $\{W_1, \dots, W_n\}$ is independent iff $W = W_1 \oplus W_2 \oplus \dots \oplus W_n$

proof:

$$(\Rightarrow) x_1 + x_2 + \dots + x_n = y_1 + y_2 + \dots + y_n$$

then

$$(x_1 - y_1) + \dots + (x_n - y_n) = 0$$

$\in W_1$

$\in W_n$

$$\Rightarrow x_1 = y_1, \dots, x_n = y_n$$

or $x_i = y_i \quad \forall i$

$\therefore$ unique combination

$$\therefore W = W_1 \oplus W_2 \oplus \dots \oplus W_n$$

($\Leftarrow$) if direct sum, every vector uniquely, then it is trivial that

if

$$x_i \in W_i$$

then

$$x_1 + x_2 + \dots + x_n = 0$$

$$\Rightarrow x_1 = 0$$

$$x_2 = 0$$

.

$$x_n = 0$$

or $\{W_i\}$ is independent

lemma: let V be a f.d vector space and W_i 's are subspaces of V ,
and $W = W_1 + \dots + W_n$

TFAE:

(i) $W = W_1 \oplus W_2 \oplus \dots \oplus W_n$

(ii) for all $2 \leq j \leq n$,

$$(W_1 + \dots + W_{j-1}) \cap W_j = \{0\}$$

(iii) if $B_1, \dots, B_n$ are basis of $W_1, \dots, W_n$ respectively then

$\bigcup_{i=1}^n B_i$ is a basis for W .

(iv) $\dim(W) = \sum_{i=1}^n \dim(W_i)$

proof: (i) $\Rightarrow$ (ii):

suppose that there is a non-zero vector

$$0 \neq x \in W_j \cap (W_1 + W_2 + \dots + W_{j-1})$$

$$\Rightarrow \underbrace{0+0+\dots+0}_{j^{\text{th}} \text{ place}} + \overset{+a_j}{x} + 0 = y_1 + y_2 + \dots + y_{j-1} + 0 + 0 + \dots + 0$$

$$\Rightarrow 0+0+\dots+0+x+0+0+\dots+0 = y_1 + y_2 + \dots + y_{j-1} + 0+0+\dots+0$$

$$\Rightarrow x = 0$$

$$\text{as } W = W_1 \oplus W_2 \oplus \dots \oplus W_n$$

$\downarrow$ W_i is unique

$$\text{or } y_1 + y_2 + \dots + y_{j-1} - x_j = 0$$

$$\Rightarrow$$

$$y_1 = y_2 = \dots = y_{j-1} = 0$$

$$\therefore x \in \{0\}$$

$$\text{or } \{0\} = W_j \cap (W_1 + \dots + W_{j-1})$$

(ii) $\Rightarrow$ (i)

suppose $\alpha_1 + \dots + \alpha_n = \beta_1 + \dots + \beta_n$ where

$$\alpha_i, \beta_i \in W_i, \forall i=1,2,\dots,n$$

$$\alpha_n - \beta_n = (\beta_1 - \alpha_1) + (\beta_2 - \alpha_2) + \dots + (\beta_{n-1} - \alpha_{n-1})$$

now as

$$W_n \cap (W_1 + W_2 + \dots + W_{n-1}) = \{0\}$$

$$\text{we have } \alpha_n = \beta_n$$

$$\text{and } \alpha_1 + \alpha_2 + \dots + \alpha_{n-1} = \beta_1 + \beta_2 + \dots + \beta_{n-1}$$

inserting this to get

$$\alpha_{n-1} = \beta_{n-1}$$

$$\vdots$$

$$\alpha_1 = \beta_1$$

$$\text{or } \alpha_i = \beta_i \forall i$$

$\therefore \{W_i\}$ is independent

$$\Rightarrow W = W_1 \oplus W_2 \oplus \dots \oplus W_n$$

(iii) $\Rightarrow$ (i):

As $B_1, B_2, \dots, B_n$ are basis and

as UB_i is a base of W

or $\forall B_i$ is independent

and $\forall B_i$ spans W

now, as UB_i is independent

all $x_i \in W_i$ can be

rep as $x_i \in B_i$

then all x_i are lin ind

$$\therefore \{W_i\} \text{ is ind } \Rightarrow W = W_1 \oplus W_2 \oplus \dots \oplus W_n$$

(i) $\Rightarrow$ (iii): $B = \bigcup_{i=1}^n B_i$ spans W (trivial)

so if $\bigcup_{i=1}^n B_i$ is independent, then we are done.

To show: $\bigcup_{i=1}^n B_i$ is linearly ind.

let $B_i = \{b_{i1}, b_{i2}, \dots, b_{i r_i}\}$

$\forall i = 1, 2, \dots, n$

now if $\sum_{i=1}^n \sum_{j=1}^{r_i} b_{ji} \alpha_{ji} = 0$

$$= \left(\sum_{j=1}^{r_1} \alpha_{j1} b_{j1} \right) + \left(\sum_{j=1}^{r_2} \alpha_{j2} b_{j2} \right) + \dots + \left(\sum_{j=1}^{r_n} \alpha_{jn} b_{jn} \right)$$

$$0 = x_1 + x_2 + \dots + x_n, \quad x_i \in W$$

as $W = W_1 \oplus W_2 \oplus \dots \oplus W_n$ (as $\{W_i\}$ is ind.)
 $\Rightarrow$ all $x_i = 0$

now as all $x_i = 0$

$$\sum \alpha_{ji} b_{ji} = 0$$

$\Rightarrow \alpha_{ji} = 0 \quad \forall i, j$
 as b_{ji} are lin. ind. w.r.t i

(iii) $\Leftrightarrow$ (iv) is trivial

Defn: A linear map E on a vector space V is a projection if $E^2 = E$

Note: $x \in \text{Ran } E$ (Range of E)

$$\Leftrightarrow E(x) = x$$

proof: ($\Rightarrow$) $x \in \text{Ran } E$
 then $\exists x' \in \text{dom}(E)$ s.t. $E(x') = x$
 also as $E^2 = E$
 $E(E(x')) = E(x')$
 $\Rightarrow E(x) = x$

($\Leftarrow$) If $E(x) = x$ then
 as $x \in \text{dom}(E)$
 and
 $x = E(x)$
 $\Rightarrow x \in \text{Ran}(E)$

$$\therefore x \in \text{Ran}(E) \Leftrightarrow E(x) = x$$

Note: As orthogonal complement of $x \in \text{Ran}(E)$ is

$\perp_E$
 we have other than $E(x) = x$, many other x s.t. $E(x) \neq x$

then $E(x) = 0$.

so either $E(x) = x$ $x \in \text{Ran } E$
or
 $E(x) = 0$ $x \in \text{Nul } E$

$$\therefore \text{Ran } E \oplus \text{Nul } E = V$$

Note: $\text{Ran } E \oplus \text{Nul } E = V$ $\left(\begin{array}{l} \text{Ran } E \oplus V_1 = V \\ \dim V_1 = \dim(\text{Nul } E) \end{array} \right)$ $\left(\begin{array}{l} \text{Nul } E \cap \text{Ran } E = \{0\} \\ \text{Nul } E \oplus \text{Ran } E = V \end{array} \right)$

let W be subspace of V , then what is the projection whose range is W is:

idea: we define map F from vector space V and let $\{w_1, \dots, w_m\}$ basis for W
 $\{w_1, w_2, \dots, w_m, r_1, r_2, \dots, r_n\}$ basis for V

$$\text{then } F \text{ s.t. } F(w_i) = w_i \quad \forall i \\ F(r_j) = 0 \quad \forall j$$

$$v \in V \Rightarrow v = \sum \alpha_i w_i + \sum \beta_j r_j$$

$$F(v) = F(\sum \alpha_i w_i) + F(\sum \beta_j r_j)$$

$$F(v) = F(\sum \alpha_i w_i) = \sum \alpha_i w_i$$

$$\text{now } w \in W \\ F(w) = w$$

$$\text{and } v \in V \setminus W \\ F(v) = 0$$

so we can find a projection (F , which is one-one)

Note: The map $E \rightarrow \text{Ran } E$ is a bijective map is a bijective map between collections of all projections on V and subspaces of V .

lemma: let V be a finite dimensional vector space and W_i 's be subspaces of V . Suppose

$$V = W_1 + W_2 + \dots + W_n$$

IFAE:

$$(i) V = W_1 \oplus W_2 \oplus \dots \oplus W_n$$

$$(ii) \exists \text{ projections } E_1, \dots, E_n \text{ with } \text{Ran } E_i = W_i \text{ s.t.}$$

$$(a) E_i E_j = 0, \forall i \neq j$$

$$(b) I = E_1 + E_2 + \dots + E_n$$

$$(\text{NOK: } E_i(I) = E_i E_1 + E_i E_2 + \dots + E_i E_i + \dots \rightarrow 0 \quad \rightarrow 0 \quad \rightarrow 0) \\ \text{or } E_i = E_i^2$$

proof: $(i) \Rightarrow (ii)$:

$$V = W_1 \oplus W_2 \oplus \dots \oplus W_n$$

as V is direct sum

7th Oct:

Recall: $E: V \rightarrow V$ s.t.
 $E^2 = E \leftarrow \text{projection}$

- (i) $E(x) = x \Leftrightarrow x \in \text{Rom}(E)$
(ii) $V = \text{Rom } E \oplus \text{Nul } E$

Note: The previous lemma was not correct and also the fact $E \leftrightarrow \text{Rom } E$ is false

Note: $E \mapsto \text{Rom } E$ is surjective (not one-one)

Lemma: Let V be a vector space and $w_1, w_2, \dots, w_n$ be subspaces of V . TFAE:

- (i) $V = w_1 \oplus \dots \oplus w_n$
(ii) $\exists$ linear maps E_i 's $i=1, 2, \dots, n$ s.t.
(a) $I = E_1 + E_2 + \dots + E_n$
(b) $E_i E_j = 0 \forall i \neq j$
(c) $E_i^2 = E_i \forall i$
(d) $\text{Rom } E_i = w_i, \forall i=1, 2, \dots, n$

Proof: (2) $\Rightarrow$ (1) since $I = E_1 + E_2 + \dots + E_n$
 $\varphi = E_1(\varphi) + E_2(\varphi) + \dots + E_n(\varphi) \quad \forall \varphi \in V$
 $\Rightarrow \varphi \in w_1 + w_2 + \dots + w_n$
for $\varphi \in V$, suppose it has 2 diff exprs
i.e. $\varphi = \sum \alpha_i = \sum \beta_i$
for $\alpha_i, \beta_i \in w_i \forall i=1, 2, \dots, n$

$$\sum \alpha_i \in w_1 + w_2 + \dots + w_n \\ = \sum \beta_i \in w_1 + w_2 + \dots + w_n$$

$$E_i(\varphi) = E_i(\alpha_1) + \dots + E_i(\alpha_i) + \dots + E_i(\alpha_n) \\ = E_i(\beta_1) + \dots + E_i(\beta_i) + \dots + E_i(\beta_n)$$

or $E_i(\alpha_i) = E_i(\beta_i)$
and $E_i(\varphi) = E_i(\alpha_i) = E_i(\beta_i)$
 $= \alpha_i = \beta_i$

$$\left(\because E_i(\alpha_i) = \alpha_i \Leftrightarrow \alpha_i \in \text{Rom } E_i \right) \\ \therefore \alpha_i = \beta_i \quad \forall i$$

now as $\text{Rom } E_i = w_i$

$$V = w_1 \oplus w_2 \oplus \dots \oplus w_n$$

(1) $\Rightarrow$ (2) Here if $V = w_1 \oplus w_2 \oplus \dots \oplus w_n$

$\left(E \mapsto \text{Rom } E \text{ is surjective as } w \subseteq V, \text{ basis } w = \{\alpha_1, \alpha_2, \dots, \alpha_d\} \right.$
 $\left. E \text{ is s.t. } E(\alpha_i) = \alpha_i, E(\beta_j) = 0 \text{ then } E^2 = E \right)$
 $V = w \oplus w', \text{ basis } w' = \{\beta_1, \beta_2, \dots, \beta_r\}$

(Here $\exists E$ s.t. $E^2 = E$ for given $\text{Rom } E$)

now $V = W_1 \oplus W_2 \oplus \dots \oplus W_n$

then $W'_1 = W_2 \oplus \dots \oplus W_n$

for $1 \leq i \leq n$,
 since $V = W_i \oplus (W_1 \oplus \dots \oplus W_{i-1} \oplus W_{i+1} \oplus \dots \oplus W_n)$

define $E_i : V \rightarrow V$ by
 $E_i(f) = f, \forall f \in W_i$
 $E_i(g) = 0, \forall g \in (W_1 \oplus \dots \oplus W_{i-1} \oplus W_{i+1} \oplus \dots \oplus W_n)$

we can extend E_i linearly to get:
 $E_i(f+g) = E_i(f) + E_i(g)$
 or E_i is a linear map

now Range of $E_i = W_i$ (d)
 and $E_i^2 = E_i$ (c)

also, $E_i E_j = 0$ as
 $\text{Rom } E_j = W_j$
 and $W_j \subseteq \ker E_i$ (b)

now to show $I = E_1 + E_2 + \dots + E_n$

$\varphi \in V$
 $(E_1 + E_2 + \dots + E_n)(\varphi) = E_1(\varphi) + \dots + E_n(\varphi)$

as $V = W_1 \oplus \dots \oplus W_n$

$\varphi = w_1 + w_2 + \dots + w_n$ uniquely for $w_i \in W_i$

$E_i(\varphi) = E_i(w_1 + \dots + w_n)$
 $= E_i(w_i)$
 $= w_i$

so $(E_1 + \dots + E_n)(\varphi) = w_1 + \dots + w_n$
 $= \varphi$
 $\forall \varphi \in V$

$\therefore E_1 + \dots + E_n = I$

Note: $E^2 = E$ and $V = \text{Rom } E \oplus \text{Null } E$

Basis for $\text{Rom}(E)$ $\{ \alpha_1, \dots, \alpha_d \}$ $\rightarrow$ Basis of V
 Basis of $\text{Null}(E)$ $\{ \beta_1, \dots, \beta_r \}$

$E : V \rightarrow V$

$E(\alpha_1) = 1\alpha_1 + 0\alpha_2 + 0\alpha_3 + \dots + 0$

$E(\beta_1) = 0 = 0\alpha_1 + 0\alpha_2 + \dots + 0$

$$\text{or } E = \left[\begin{array}{c|c} \begin{matrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 \end{matrix} & \begin{matrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 \end{matrix} \end{array} \right]_{d+r \times d+r} = \left[\begin{array}{c|c} I_{d \times d} & 0 \\ \hline 0 & 0 \end{array} \right]_{d+r \times d+r}$$

$\underbrace{\quad}_d \quad \underbrace{\quad}_r \quad \rightarrow \text{all zero}$
 $e_1, e_2, \dots, e_d$

Note: $V = W_1 \oplus W_2$, $T: V \rightarrow V$

$$T = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

$$\left. \begin{array}{l} A \in \alpha(W_1, W_1) \\ B \in \alpha(W_2, W_1) \\ C \in \alpha(W_1, W_2) \\ D \in \alpha(W_2, W_2) \end{array} \right\} \text{linear maps}$$

Defn: let $T: V \rightarrow V$ be a linear map and W a subspace of V is called invariant subspace for T if

$$T(W) \subseteq W$$

Note: if W is invariant for T then $T = \begin{bmatrix} * & * \\ 0 & * \end{bmatrix}$ $V = W \oplus W'$

$$\downarrow$$

$$C \in \alpha(W_1, W_2)$$

$$\text{as } W_1 = W$$

$$W_2 = W'$$

$$\text{as } T(W) \subseteq W$$

$$C \text{ has to be zero}$$

$$\text{as if basis } W = \{\alpha_1, \dots, \alpha_d\} \quad W' = \{\beta_1, \dots, \beta_s\}$$

$$T(\alpha_i) \in W \text{ so}$$

$$T(\alpha_i) = * \alpha_1 + * \alpha_2 + \dots + * \alpha_d + (0) \beta_1 + 0 + \dots$$

$$\underbrace{\quad}_{C=0}$$

$$T = \begin{bmatrix} * & * \\ 0 & * \end{bmatrix}$$

$$\text{if } W' \text{ is also invariant then } B \in \alpha(W_2, W_1) = 0$$

$$\text{or } T = \left[\begin{array}{c|c} * & 0 \\ \hline 0 & * \end{array} \right]$$

$$\text{as } T(\beta_i) = 0 \alpha_1 + \dots + 0 \alpha_d + * \beta_1 + \dots + * \beta_s$$

Theorem: let T be a linear map on V , and let $V = W_1 \oplus W_2 \oplus \dots \oplus W_n$ and let E_i 's be projections s.t

- (a) $I = E_1 + \dots + E_n$
- (b) $E_i E_j = 0, \forall i \neq j$
- (c) $W_i = \text{Ran } E_i, \forall i = 1, 2, \dots, n$

TFAE:

(i) Each W_i is an invariant subspace of T

(ii) $TE_i = E_i T, \forall i = 1, 2, \dots, n$

proof: (ii) $\Rightarrow$ (i) $TE_i = E_i T \forall i = 1, 2, \dots, n$

for $\alpha_i \in W_i$

$$T(\alpha_i) = T(E_i(\alpha_i)) = E_i(T(\alpha_i))$$

$$T(\alpha_i) = E_i(T(\alpha_i))$$

$$\Leftrightarrow T(\alpha_i) \in \text{Ran } E_i \\ \Rightarrow T(\alpha_i) \in W_i$$

so $\forall \alpha_i \in W_i$

$$T(\alpha_i) \in W_i$$

or W_i is invariant

(i) $\Rightarrow$ (ii) If all W_i are invariant then
for $v \in V$
s.t $v = w_1 + \dots + w_n$

$$TE_i(v) = T(w_i) \in W_i$$

as W_i is invariant

$$= E_i(T(w_i)) \text{ as } T(w_i) \in W_i = \text{Ran } E_i$$

now
as $E_i(T(w_1 + w_2 + \dots + w_n))$

$$= E_i(T(w_1) + \dots + T(w_n))$$

$$= E_i(T(w_i))$$

$$\Leftrightarrow TE_i(v) = E_i(T(w_i)) = E_i(T(v))$$

Note: $T = \begin{bmatrix} A_1 & & 0 \\ & \ddots & \\ 0 & & A_n \end{bmatrix}, A_j \in \mathcal{L}(W_j, W_j)$
 $A_j = T|_{W_j}$

10th Oct :

Theorem: let $A \in \mathcal{A}(V, V)$ finite d vector space, and let $\alpha_1, \dots, \alpha_d$ be distinct eigenvalues of A. let W_i be the eigenspace corresponding to α_i $i=1, 2, \dots, n$

TFAE

$$(K\mathcal{A}(A - \alpha_i I) = W_i)$$

(i) A is diagonalisable

(ii) the char. polynomial of A has form

$$\chi_A(t) = (t - \alpha_1)^{n_1} \dots (t - \alpha_d)^{n_d}$$

$$\text{and } \dim(W_i) = n_i \quad \forall i=1, 2, \dots, d$$

$$(iii) \dim(V) = \dim(W_1) + \dots + \dim(W_d)$$

$$\Leftrightarrow V = W_1 \oplus W_2 \oplus \dots \oplus W_d$$

(iv) $\exists E_i \in \mathcal{A}(V, V)$, ($i=1, 2, \dots, d$) s.t

$$(a) I = E_1 + \dots + E_d$$

$$(b) A = \alpha_1 E_1 + \dots + \alpha_d E_d$$

$$(c) E_i E_j = 0 \quad \forall i \neq j$$

$$(d) E_j^2 = E_j \quad \forall j$$

$$(e) \text{Range } E_j = W_j, \quad \forall j=1, 2, \dots, d$$

(v) The minimal polynomial of A is

$$(t - \alpha_1) \dots (t - \alpha_d)$$

proof: $(i) \Rightarrow (ii)$

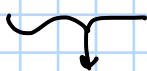
as A is diagonalisable
 $S^{-1} A S = D$

$$\text{and } \chi_A = \chi_D$$

$$= (t - \alpha_1)^{n_1} (t - \alpha_2)^{n_2} \dots (t - \alpha_d)^{n_d}$$

repeated in terms of multiplicity

$$\left[\begin{array}{c} \alpha_1 \\ \alpha_1 \\ \dots \end{array} \right]^{n_1 \text{ times}}$$



Eigenvectors of this matrix are e_i

$\Rightarrow e_1$ to e_{n_1} are eigenvectors corresponding to α_1

$$\Rightarrow \dim(W_1) = n_1$$

$$\text{generally } \dim(W_i) = n_i$$

$\hookrightarrow$ not $\Rightarrow$

$$\chi_D(t) = \prod (t - \alpha_i)^{n_i}$$

$$\dim(W_i) = \dim(\text{eigenspace w.r.t } \alpha_i \text{ in } D) \quad (\because A \sim D)$$

$\hookrightarrow$ w.r.t A

$$\dim(W_i) = n_i$$

$\hookrightarrow \text{wt } A$

$$((ii) \Rightarrow (iii)) \text{ By 2, } n_1 + n_2 + \dots + n_d = \dim(V)$$

$$\dim W_i = n_i$$

$$\text{or } \sum \dim W_i = \dim(V)$$

now as W_i and W_j are ind for $i \neq j$

(eigenvectors corr to diff eigenvalues)

$$\text{so } V = W_1 \oplus W_2 \oplus \dots \oplus W_d$$

$$((iii) \Rightarrow (iv)) \text{ as } V = W_1 \oplus W_2 \oplus \dots \oplus W_d$$

$$\exists \text{ projections } E_i \text{'s s.t.}$$

(a), (c), (d), (e) hold

let $v \in V$ then as $V = W_1 \oplus \dots \oplus W_d$

$$v = \sum_{i=1}^d v_i \text{ for } \forall v_i \in W_i$$

and is unique

$$\text{now, } A(v) = A\left(\sum_{i=1}^d v_i\right) = \sum_{i=1}^d A(v_i)$$

$$= \sum_{i=1}^d \alpha_i(v_i)$$

$$A(v) = \sum_{i=1}^d \alpha_i E_i(v_i)$$

$$= \sum_{i=1}^d \alpha_i E_i\left(\sum_{j=1}^d v_j\right)$$

as E_i kills all other vectors

$$A(v) = \sum_{i=1}^d \alpha_i E_i(v)$$

$$\Rightarrow A = \sum_{i=1}^d \alpha_i E_i$$

(Note: $V = W_1 \oplus W_2 \oplus \dots \oplus W_d$
then

$$A = \begin{bmatrix} \alpha_1 I_{W_1} & & \\ & \alpha_2 I_{W_2} & \\ & & \ddots \end{bmatrix}$$

$$E_1 = \begin{bmatrix} I_{W_1} & 0 \\ 0 & 0 \end{bmatrix} \quad E_2 = \begin{bmatrix} 0 & I_{W_2} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Remarks: (a), (b), (c) $\Rightarrow$ Range $E_j = W_j^\circ$ (e)

If we take $v_j \in \text{Ran } E_j$, then

$$A(v_j) = \sum d_i E_i(v_j) = \alpha_j E_j(v_j)$$

$$A(v_j) = \alpha_j v_j \Rightarrow v_j \in W_j^\circ$$

$$\text{Ran } E_j \subseteq W_j^\circ \quad \forall j$$

and if $v_j^\circ \in W_j^\circ$ i.e. $A(v_j^\circ) = \alpha_j v_j^\circ$

$$\begin{aligned} \Rightarrow \sum_{i=1}^d \alpha_i E_i(v_j^\circ) &= \alpha_j v_j^\circ \\ &\quad \uparrow \\ &\quad \text{from (b)} \end{aligned} \quad = \alpha_j^\circ \left(\sum_{i=1}^d E_i v_j^\circ \right) \quad \uparrow \text{from (a)}$$

$$\Rightarrow \sum d_i E_i(v_j) = \alpha_j^\circ \left(\sum E_i v_j^\circ \right)$$

$$\Rightarrow \sum (\alpha_i - \alpha_j) E_i(v_j) = 0$$

$\Rightarrow$ if we apply E_i on both sides we get

$$(\alpha_i - \alpha_j) E_i^2(v_j) = 0 \Rightarrow E_i(v_j) = 0$$

$$\text{or } \forall i \neq j \quad E_i(v_j^\circ) = 0$$

$$\text{also } v_j^\circ = \sum E_i v_j^\circ = E_j v_j^\circ$$

$$\Rightarrow v_j^\circ = E_j v_j^\circ$$

$$\Rightarrow v_j^\circ \in \text{Ran } E_j$$

$$\Rightarrow W_j^\circ \subseteq \text{Ran } E_j$$

$$\therefore W_j^\circ = \text{Ran } E_j$$

(iv) $\Rightarrow$ (i) As (a), (c), (e) is true it implies

$$V = W_1 \oplus \dots \oplus W_d$$

Therefore A has suff eigenvectors which span V

thus A is diagonalisable

(iv) $\Rightarrow$ (v) by (b) $A = \alpha_1 E_1 + \alpha_2 E_2 + \dots + \alpha_d E_d$ where E_i are projections

$$\Rightarrow A^2 = \sum_{i=1}^d \alpha_i^2 E_i$$

any polynomial $g \in \mathbb{C}[Z]$

$$\left(\begin{array}{l} \text{Note: } g(t) = \sum \alpha_i t^i \\ \Rightarrow g(A) = \sum \alpha_i A^i \end{array} \right) \quad g(A) = \sum_{i=1}^d g(\alpha_i) E_i$$

claim: $g(A) = 0 \Leftrightarrow g(\alpha_i) = 0 \quad \forall i = 1, \dots, d$

($\Leftarrow$) Trivial

($\Rightarrow$) $g(A) = 0$ then $\sum_{i=1}^d g(\alpha_i) E_i = 0$

multiply by E_i

$\Rightarrow g(\alpha_i) = 0 \quad \forall i = 1, \dots, d$
($\because E_i$ are not trivial)

so for $g(A) = 0 \Rightarrow g(\alpha_i) = 0$
or α_i are the roots

$\therefore$ minimal polynomial with α_i roots
for $i = 1, \dots, d$
are:

$$\prod_{i=1}^d (t - \alpha_i)$$

14th set:

Theorem: Let $T \in \alpha(V)$

(V) The minimal polynomial of T is
$$\prod_{i=1}^d (t - \alpha_i)$$

(iv) $\exists E_i \in \alpha(V, V)$ s.t. (a) $I = E_1 + E_2 + \dots + E_n$
(b) $A = \alpha_1 E_1 + \dots + \alpha_d E_d$
(c) $E_i E_j = 0, \forall i \neq j$

proof: (V) $\Rightarrow$ (N)

$$P_1(t) = \prod_{i=2}^d \frac{(t - \alpha_i)}{(\alpha_1 - \alpha_i)}$$

$$P_j(t) = \prod_{\substack{i=1, \\ i \neq j}}^d \frac{(t - \alpha_i)}{(\alpha_j - \alpha_i)} \quad (\text{Lagrange polynomials})$$

(degree $d-1$)

Note: $P_j(t) = \begin{cases} 0 & ; \text{ else} \\ 1 & ; t = \alpha_j \end{cases}$

Claim: $P_1, \dots, P_d$ are linearly independent $\rightarrow$ do

then $I = c_1 P_1 + c_2 P_2 + \dots + c_d P_d$

$t = b_1 P_1 + b_2 P_2 + \dots + b_d P_d$

$I = c_1 P_1 + \dots = P_1 + \dots$

$t = b_1 P_1 + \dots = \alpha_1 P_1 + \dots$

So we are assuming $d > 1$, so there is nothing to prove for the case when $d = 1$

($d=1$, it is a trivial case as only 1 eigenvalue, so that is the minimal poly
 $a = \alpha I$ which is diagonal)

Note: $I = P_1(A) + P_2(A) + \dots + P_d(A)$

$A = \alpha_1 P_1(A) + \dots + \alpha_d P_d(A)$

Let $E_i = P_i(A), \forall i = 1, \dots, d$

then $E_i E_j = P_i(A) P_j(A) \quad i \neq j$
 $= (P_i P_j)(A)$

$P = (t - \alpha_1)(t - \alpha_2) \dots (t - \alpha_d)$

as $P_i P_j = \prod_{\alpha_i - \alpha_i} \frac{(t - \alpha_i)}{(\alpha_i - \alpha_i)} \prod_{\alpha_j - \alpha_i} \frac{(t - \alpha_i)}{(\alpha_j - \alpha_i)}$

we have $P \mid P_i P_j$

$\Rightarrow$ as $P(A) = 0$
 $\Rightarrow P_i P_j(A) = 0$

$\therefore i \neq j \Rightarrow E_i E_j = 0$ also (a), (b), (c) $\Rightarrow$ (e) (done)

proof follows as $E_j = P_j(A) \neq 0$

Generalised eigenvectors:

$$V = W_1 \oplus \dots \oplus W_d$$

Theorem: Let $A \in \mathcal{A}(V, V)$ and let the minimal polynomial of A be of the form

$$p_1 r_1 \dots p_d r_d$$

(different)

where P_i 's are irreducible monic polynomials over $\mathbb{F}$

then

$$(i) V = W_1 \oplus \dots \oplus W_d, \text{ where}$$

$$W_i = \text{Null}(P_i^{r_i}(A)), i=1, \dots, d$$

elements in this are called generalised eigenvectors

$$(ii) W_i \text{ are invariant subspaces of } A \text{ (} T(W_i) \subseteq W_i \text{)}$$

$$(iii) \text{ The minimal polynomial of } T_i = A|_{W_i} : W_i \rightarrow W_i \text{ is } P_i r_i$$

$$\left(A = \begin{bmatrix} T_1 & & 0 \\ & T_2 & \\ 0 & & \ddots \\ & & & T_d \end{bmatrix} \right) \text{ where } T_i \in \mathcal{A}(W_i, W_i) \rightarrow \text{Block diagonal rep.}$$

proof: Let $f_i = \frac{P}{P_i r_i}, \forall i=1, \dots, d$

We want to write 1 like

$$1 = f_1 g_1 + \dots + f_d g_d$$

this

look at ideal generated by $f_1, f_2, \dots, f_d$

ideals are principle so

$$I_1 = (f_1)$$

$$I_2 = (f_2)$$

$$\vdots$$

$$I_d = (f_d)$$

Ideal generated by $(f_1, f_2, \dots, f_d) = I = \langle d \rangle$ as Ring is P.I.D

$$= \{ f_1 g_1 + f_2 g_2 + \dots + f_d g_d \mid \forall g_i \in \text{Polynomials} \}$$

and $d \mid f_i, \forall i=1, 2, \dots, d$

some element in P.I.D

as $\langle d \rangle = I$

and $f_1 \in \langle d \rangle \Rightarrow f_1 = dk$
or $d \mid f_1$

fact: $d \mid f_i, \forall i=1 \dots d \Rightarrow d \equiv 1$

$$\text{so, } 1 = f_1 g_1 + f_2 g_2 + \dots + f_d g_d \\ \Rightarrow I = (f_1 g_1)(A) + \dots + (f_d g_d)(A)$$

Define $E_j = f_j(A) g_j(A)$, $\forall j=1, 2, \dots, d$

$E_i E_j = 0$ to prove they are projections

$$E_i E_j = f_j(A) g_j(A) f_i(A) g_i(A) \\ = \underbrace{(f_i f_j(A))}_{\text{has a factor as minimal poly}} (g_i g_j(A))$$

$$= 0 \quad \text{as } p \mid f_i f_j, i \neq j$$

claim: $\text{Ran } E_i = W_i = \text{Null}(P_i^{r_i}(A))$

$$\text{Ran } E_i \subseteq W_i \text{ as } P_i^{r_i}(A) [f_i(A) g_i(A) u] \\ = P(A) [g_i(A) u] \\ = 0$$

$\forall x \in \text{Null}(P_i^{r_i}(A))$

$$E_i(x_i) = f_i(A) g_i(A)(x_i)$$

$$\text{for } j \neq i \quad E_j(x_i) = f_j(A) g_j(A)(x_i) \\ = \underbrace{f_j(A)(x_i)}_{=0 \text{ as } x_i \in \ker \{f_j(A)\}} g_j(A) \\ = 0$$

$$\text{so } E_j(x_i) = 0$$

$$I = E_1 + \dots + E_d \\ \text{on both sides we get}$$

$$x_i = E_i(x_i) \\ \Rightarrow x_i \in \text{Ran } E_i$$

$$\text{so } \text{Ran } E_i = W_i$$

17th Oct:

Theorem: (Spectral Theorem) Let T be a linear map on a finite dim vector space V . Let

$P = p_1^{r_1} \dots p_d^{r_d}$ be minimal polynomial of T where p_i 's are distinct irreducible monic polynomials over $\mathbb{F}^L$ and r_i 's are positive integers.

Suppose $W_i = \text{Null}(p_i^{r_i}(T))$, $i=1, 2, \dots, d$
then

(i) $V = W_1 \oplus \dots \oplus W_d$

(ii) W_i is an invariant subspace of T , $\forall i=1, 2, \dots, d$

(iii) min polynomial for

$T_i = T|_{W_i} : W_i \rightarrow W_i$ is $p_i^{r_i}$, $\forall i=1, 2, \dots, d$

proof: set $f_i = \frac{P}{p_i^{r_i}}$, $\forall i=1, \dots, d$

$$1 = \sum_{i=1}^d f_i g_i$$

or $1 \in \langle f_1, f_2, \dots, f_d \rangle$
(ideals generated by $f_1, \dots, f_d$)

any ideal here is principle (PID)

$$1 \in \langle f_1, \dots, f_d \rangle = \langle d \rangle$$

$$d \mid f_i \quad \forall i=1, \dots, d$$

so $d \mid \gcd(f_1, f_2, \dots, f_d)$ (as all p_i are irred)

$$\Rightarrow d \mid 1 \Rightarrow d=1$$

now as $\langle f_1, f_2, \dots, f_d \rangle = \langle 1 \rangle$

$$\text{now, } I = \sum_{i=1}^d f_i(T) g_i(T)$$

$$\text{set } E_i = f_i(T) g_i(T)$$

E_i is a projection as $E_i^2 = E_i$

$$\begin{aligned} \text{as: } E_i E_j &= f_i(T) g_i(T) f_j(T) g_j(T) \\ &= f_i(T) f_j(T) g_i(T) g_j(T) \\ &= h(T) P(T) g_i(T) g_j(T) \\ &= 0 \end{aligned}$$

$$\text{as } P(T) = 0$$

↑
minimal polynomial

claim: $\text{Ran } E_i = W_i$

if $x \in \text{Ran } E_i$ then

x can be written as
 $E_i(x) = x$ (as E_i is a projection)

$$\Rightarrow E_i^0(x) = f_i^0(T) g_i(T) x$$

$$\text{now, } p_i^{r_i}(T) x = p_i^{r_i}(T) E_i^0(x) = p_i^{r_i}(T) f_i(T) g_i(T) x \\ = 0 \quad p_i^{r_i}(T) g_i(T) x$$

$$\Rightarrow \text{Ran } E_i^0 \subseteq W_i^0 \quad \left(\because p_i^{r_i}(T) x = 0 \Rightarrow x \in W_i^0 \right)$$

$$\text{now, } E_i^0(W_j^0) = 0 \Rightarrow W_i^0 \subseteq \text{Ran } E_i^0 \text{ for } i \neq j$$

$$I = E_1 + \dots + E_d \\ x \in W_i^0 \Rightarrow x = E_1(x) + \dots + E_d(x) \\ \Rightarrow x = E_i^0(x) \\ \Rightarrow x \in \text{Ran } E_i^0 \\ \Rightarrow W_i^0 \subseteq \text{Ran } E_i^0$$

$$\text{to show } E_j^0(x) = 0$$

$$\text{as } x \in W_i^0 = \text{Null}(p_i^{r_i}(T))$$

$$E_j^0(x) = g_j^0(T) f_j(T) (x) \\ = 0 \quad \text{But } p_i^{r_i}(T) \text{ is in } \text{Inf}_j(T)$$

$$\text{so } V = W_1 \oplus \dots \oplus W_d \quad (\text{from previous theorems})$$

$$\text{for } x \in W_i^0 = \text{Null}(p_i^{r_i}(T)) \\ p_i^{r_i}(T)(Tx) = T(p_i^{r_i}(T)x) = 0$$

$$\Rightarrow T(W_i^0) \subseteq W_i^0 \quad \forall i=1,2,\dots,d \quad (\text{ii})$$

for (iii) The minimal polynomial for $T_i = T|_{W_i^0}$
 Restricting it to just act on W_i^0 and not whole of V

$$\text{for } x \in W_i^0 \quad p_i^{r_i}(T_i) x = p_i^{r_i}(T) x$$

$$= 0 \quad \text{as } \forall j=1,2,\dots,d \quad p_i^{r_i}(T_j) = 0$$

(shown that min x some $= p_i^{r_i}(T)$)

so $p_i^{r_i}$ can be a minimal polynomial

Proof of $p_i^{r_i}$ is minimal:

$$\text{let } g(T_i) = 0 \quad \text{then } g(T) f_i(T) = 0$$

$$x \in W_i \quad f_i(T) g(T) x = f_i(T) g(T_i) x = 0$$

$$W_j = \text{null}(p_j^{r_j}(T))$$

$$\text{for } x \in W_j \quad g(T) f_i(T) x = 0 \quad j \neq i$$

$$\leadsto g(T) f_i(T) = 0$$

$$\Rightarrow \uparrow \mid g f_i \leftarrow \text{as } g(T) f_i(T) = 0$$

minimal polynomial

$$\Rightarrow p_i^{r_i} f_i \mid g f_i$$

$$\Rightarrow p_i^{r_i} \mid g$$

$\Rightarrow p_i^{r_i}$ is minimal polynomial

note: when $F = \mathbb{C}$

$$P = (t - \lambda_1)^{r_1} \cdots (t - \lambda_d)^{r_d}$$

note: case when T is diagonalisable, all $r_i = 1$

$$\therefore P = \prod (t - \lambda_i)$$

here

$$V = W_1 \oplus \cdots \oplus W_d$$

$\searrow$ eigenspaces & invariant space

$$\text{then } T = \begin{bmatrix} A_1 & & 0 \\ & A_2 & \\ 0 & & \ddots \\ & & & A_n \end{bmatrix}$$

$$A_i \in \mathcal{A}(W_i, W_i)$$

Block representation of matrix:

$$V = W_1 \oplus W_2$$

s.t. W_1 & W_2 are invariant

$$\text{basis } W_1 = \{a_1, \dots, a_r\}$$

$$\text{basis } W_2 = \{b_1, \dots, b_m\}$$

$$\text{basis } V = \{a_1, \dots, a_r, b_1, \dots, b_m\}$$

$$T(a_1) = \alpha_{11} a_1 + \alpha_{21} a_2 + \cdots + \alpha_{r1} a_r + 0b_1 + \cdots + 0b_m \quad \text{as invariant}$$

$$T(a_i) = \alpha_{i1}a_1 + \dots + \alpha_{ir}a_r + 0 \cdot b_i$$

similarly $T(b_i) = 0 + \sum_{j=1}^d \beta_{ji} b_j$

then

$$T = \begin{bmatrix} \alpha_{11} & \alpha_{12} & \dots & \alpha_{1r} & 0 & \dots \\ \vdots & \vdots & & \vdots & \vdots & \\ \alpha_{r1} & \alpha_{r2} & \dots & \alpha_{rr} & 0 & \dots \\ 0 & 0 & \dots & 0 & \beta_{11} & \dots \\ 0 & 0 & \dots & 0 & \vdots & \\ 0 & 0 & \dots & 0 & 0 & \ddots \end{bmatrix} \rightarrow \text{not zero}$$

$$T = \begin{bmatrix} A_{r \times r} & 0 \\ 0 & B_{m \times m} \end{bmatrix}$$

$$T_A = T|_A = \begin{bmatrix} A_{r \times r} & 0 \\ 0 & 0 \end{bmatrix}$$

Note: the spectral theorem divides T like:

$$T = \begin{bmatrix} T_1 & & 0 \\ & T_2 & \\ 0 & \dots & T_d \end{bmatrix}$$

$$T_i = T|_{W_i} : W_i \rightarrow W_i$$

in case of $\mathbb{F} = \mathbb{C}$ and minimal polynomial

$$\text{min of } T_i = (t - \lambda_i)^{r_i}$$

note: $(T_i - \lambda_i I)^{r_i} = 0$

$$N_i^{r_i} = 0 \quad (\text{important operator})$$

$$\text{when } N_i = T_i - \lambda_i I$$

$\forall i = 1, 2, \dots, d$

so this theorem also tells us to understand this important operator

$$N_i^{r_i} = 0 = (T_i - \lambda_i I)^{r_i}$$

$$\text{if } \mathbb{F} = \mathbb{C}, P = (t - \lambda_1)^{r_1} \dots (t - \lambda_d)^{r_d}$$

$$W_i = \text{Null}(T - \lambda_i I)^{r_i}$$

$$N_m = \text{Null}(T - \lambda_i I)^m \text{ for } m \in \mathbb{N}$$

Note: $N_1 \subseteq N_2 \subseteq N_3 \subseteq \dots \subseteq N_n = N_{n+1}$
 as whatever vector A kills, is killed by A^2 property of P.I.D

n = index of eigenvalue λ_i

Defn: index of eigenvalue $\lambda_i = n$

$$N_m = \text{Null}(T - \lambda_i I)^m$$

$$N_1 \subseteq N_2 \subseteq \dots \subseteq N_n = N_{n+1} = \dots \quad \& \quad N_n \neq N_{n-1}$$

Lemma: If λ_i is a eigenvalue of T & n is the index of λ_i , then

then $p = \pi(t - \lambda_i)^{r_i}$ is the

minimal poly

then $n = r_i$

proof: we have to show

$$\text{Null}(T - \lambda_i I)^{r_i-1} \neq \text{Null}(T - \lambda_i I)^{r_i}$$

$$\& \text{Null}(T - \lambda_i I)^{r_i} = \text{Null}(T - \lambda_i I)^{r_i+1}$$

(By definition, this r_i = index)

$$\& \text{Null}(T - \lambda_i I)^{r_i-1} = W_i$$

minimal polynomial for T_i divides

which is not possible as

minimal poly for T_i is $(T - \lambda_i I)^{r_i}$

$$\text{so } \text{Null}(T - \lambda_i I)^{r_i-1} \neq W_i$$

$$\text{now } W_i = \text{Null}(T - \lambda_i I)^{r_i}$$

if

$$0 \neq y \in W_j$$

then

$$(T - \lambda_i I)^{r_i+1} y = 0$$

$$\text{then } (T - \lambda_i I)^{r_i} (T - \lambda_i I) y = 0$$

$$\Rightarrow v \in W_i$$

$$v = Ty - \lambda_i y$$

$$\uparrow \quad \uparrow$$
$$\in W_j \quad \in W_j$$

$$\Rightarrow v \in W_i \cap W_j = \{0\}$$

($\because$ direct sum)

$$\Rightarrow v = 0$$

$$(T - \lambda_i I) y = 0$$

$$\therefore \text{Null}(T - \lambda_i I)^{r_i+1} = W_i \quad \neq$$

21st Oct:

Lemma: (key lemma)

Let $T \in \mathcal{L}(V)$ be a linear map on a finite dim vector space. Suppose that $T^{m-1}(x) \neq 0$ and $T^m(x) = 0$ for some $x \in V$ & $m \geq 1$. Then

proof: If $(x, Tx, \dots, T^{m-1}x)$ is lin ind

$$\sum_{i=0}^{m-1} \alpha_i T^i x = 0$$

for some $\alpha_i \in F$ not all zero

now,

$$\begin{aligned} & (\alpha_0 x + \alpha_1 Tx + \dots + \alpha_{m-1} T^{m-1}x) = 0 \\ \Rightarrow & T^{m-1}(\alpha_0 x + \dots + \alpha_{m-1} T^{m-1}x) = 0 \end{aligned}$$

$$\Rightarrow \alpha_0 T^{m-1}(x) = 0$$

$$\Rightarrow \alpha_0 = 0$$

if we repeat the process, we get $\alpha_i = 0 \forall i$
 $\therefore$ lin independent

Defn: Let $T \in \mathcal{L}(V)$, where V is a finite dimensional vector space. We say T is cyclic if $\exists x (\neq 0) \in V$ and a positive integer m s.t.

$\text{span}\{x, Tx, \dots, T^{m-1}x\} = V$
In such a case, x is called a cyclic vector for T .

Defn: A linear map $T \in \mathcal{L}(V)$ is nilpotent if $T^m = 0$ for some positive integer m . The index of nilpotency is the smallest integer r s.t. $T^r = 0$.

denote it by $\eta(T)$

prop: Let T be a nilpotent map on V and $\dim(V) = n$. Then $\dim(V) = \text{index of nilpotent of } T \Leftrightarrow T \text{ is cyclic}$

proof: $(\Rightarrow)$ as $\dim(V) = \text{index of nilpotent of } T = n$

then
as $T^n = 0$, $T^{n-1} \neq 0$, $\exists x \in V$ s.t.
 $T^{n-1}(x) \neq 0$
& $T^n(x) = 0$

then by key lemma

$$\{x, Tx, T^2x, \dots, T^{n-1}x\} \\ = \text{Basis of } V$$

($\because$ lin ind and n in size)

$$\text{span}\{x, Tx, \dots, T^{n-1}x\} = V$$

& $\{x, Tx, \dots, T^{n-1}x\}$ is lin ind

$$\Rightarrow T \text{ is cyclic}$$

$(\Leftarrow)$ Trivial

Note: cyclic-nilpotent maps are special

If T is a cyclic nil map, then $\exists x \in V$ s.t. $\{x, Tx, \dots, T^{n-1}x\}$ is a basis for V .

$$Tx = 0 \cdot x + 1(Tx) + 0(T^2x) + 0(T^3x) + \dots + 0(T^{n-1}x)$$

$$T^2x = 0 + 0 + 1 + 0 + \dots + 0$$

$$T \sim \begin{bmatrix} 0 & 0 & \dots & 0 & 0 \\ 1 & 0 & & & \\ 0 & 1 & & & \\ \vdots & \vdots & \ddots & \vdots & \\ 0 & 0 & \dots & 0 & 0 \end{bmatrix}$$

(last column)

$$T(T^{n-1}x) = 0 + 0 + \dots + 0$$

Also called
Jordan block

This is how T looks like (similar)

$$T \sim \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \\ \vdots & \vdots \\ 0 & 1 \end{bmatrix}$$

If 2×2 then

$$T \sim \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

$$T^2 \sim \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \Rightarrow T^2 = 0$$

Theorem: (Nilpotent splitting theorem) let $T \in \alpha(V)$ be a nilpotent map and $r = \eta(T) < \dim(V)$

suppose $x \in V$ s.t. $T^{r-1}(x) \neq 0$ and

$$V_1 = \text{span}\{x, Tx, \dots, T^{r-1}x\}$$

then V_1 is

① An invariant subspace of T ; $T(V_1) \subseteq V_1$

② V_1 has a T -invariant complementary subspace

$\exists W_1$ s.t.

$$V = W_1 \oplus V_1$$

$$T(W_1) \subseteq W_1$$

we will prove this later

Ques: what happens if index of nilpotency $r < \dim(V)$ ($\eta(T) < \dim(V)$)

$$\text{as } T \in \alpha(V), \dim(V) = n > \eta(T) = r$$

$$V = V_1 \oplus W_1 \quad \text{where } V_1 = \text{span}\{x, Tx, \dots, T^{r-1}x\}$$

$$V_1 = \text{span}\{x, Tx, \dots, T^{r-1}x\} \quad \text{where } T = \begin{bmatrix} T_1 & 0 \\ 0 & T_2 \end{bmatrix} \quad T_1 = T|_{V_1}: V_1 \rightarrow V_1$$

$$\eta(T_1) = \dim(V_1) \quad T_2 = T|_{W_1}: W_1 \rightarrow W_1$$

now $T_1 = T|_{V_1}$ is a cyclic-nilpotent operator

now $T_2 = T|_{W_1}$ is also a nilpotent as it is a restriction of nilpotent map

$$\text{note: } \eta(T_2) \leq \eta(T_1) = \eta(T)$$

$$\text{as } \eta(T_2) \leq \eta(T)$$

$$\text{as } T_2 = T|_{W_1}$$

$$\text{and as } \eta(T_1) = \eta(T)$$

$$\text{we have } \eta(T_2) \leq \eta(T_1)$$

as for any $x \in W$, $T_2^r(x) = T^r(x) = 0$

$$\therefore \eta(T_2) \leq \eta(T)$$

Note: If T_2 is cyclic we are done, otherwise we can keep on using Nilpotent splitting theorem to get cyclic-nilpotents

i.e. $\eta(T_2) = r_2 < \dim(W_1)$

then

$$W_1 = V_2 \oplus W_2$$

$$V_2 = \text{span}\{x_2, T_2 x_2, \dots, T_2^{r_2-1} x_2\}$$

and W_2 is a T_2 -invariant subspace

$$V = V_1 \oplus V_2 \oplus W_2$$

$$T = \begin{bmatrix} T_1 & 0 & 0 \\ 0 & T_2' & 0 \\ 0 & 0 & T_3' \end{bmatrix}$$

cyclic nilpotent

$$T_2' = T_2|_{V_2} : V_2 \rightarrow V_2$$

$$T_3' = T_2|_{W_2} : W_2 \rightarrow W_2$$

cyclic nilpotent

cyclic nilpotent

we repeat this process, since V is finite dimensional this process will end after finite number of steps.

Theorem: Every nilpotent map can be written as a direct sum of a cyclic nilpotent maps.

$$J_r = \begin{bmatrix} p & 0 \\ 0 & p \\ \vdots & \vdots \\ 0 & 0 \end{bmatrix}_{r \times r} \rightarrow \text{Jordan Block of } \eta(J_r) = r$$

proof: from the previous problem we get

$$T \cong \begin{bmatrix} J_{r_1} & & 0 \\ & J_{r_2} & \\ 0 & & \dots & J_{r_k} \end{bmatrix} \leftarrow J\text{-matrix}$$

$$r_1 \geq r_2 \geq \dots \geq r_k$$

Lemma: let W be a subspace of V , and let $T \in \mathcal{L}(V)$. If W is T -invariant then

$T^{-1}(W)$ is also T -invariant

$$T^{-1}(W) = \{x \in V \mid T(x) \in W\}$$

proof: To show

$$T(T^{-1}(W)) \subseteq T^{-1}(W)$$

well

$$T(T^{-1}(W)) \subseteq W$$

and as W is invariant

$$T(W) \subseteq W$$

$$\Rightarrow W \subseteq T^{-1}(W)$$

$$\therefore T(T^{-1}(W)) \subseteq W \subseteq T^{-1}(W)$$

$$\Rightarrow T(T^{-1}(W)) \subseteq T^{-1}(W)$$

or $T^{-1}(W)$ is invariant

24th Oct:

Theorem: (Nilpotent splitting theorem) Let $T \in \mathcal{L}(V)$ be a nilpotent operator with $\eta(T) < \dim(V)$, and let $V_1 = \text{span}\{x, Tx, \dots, T^{m-1}x\}$ where $T^m x \neq 0$. Then $\exists$ a T -invariant subspace W_1 s.t. $V = V_1 \oplus W_1$

Lemma: If W is a T -invariant subspace then $T^{-1}(W)$ is also T -invariant
(i) $(T(W) \subseteq W \Rightarrow W \subseteq T^{-1}(W) \Rightarrow T(T^{-1}(W)) \subseteq W \subseteq T^{-1}(W)) \rightarrow \textcircled{1}$

Lemma: $T^{-1}(T(W)) = W + \text{Null } T$ for every subspace W
(ii) $(W \subseteq T^{-1}(T(W)) \text{ can be seen})$

proof: $W + \text{Null}(T) \subseteq T^{-1}(T(W))$ is trivial to see ($\because \forall x \in \text{Null } T, T(\text{Null } T) = 0 \subseteq T(W) \Rightarrow \text{Null } T \subseteq T^{-1}(T(W))$)
now $\forall x \in T^{-1}(T(W))$
 $\Rightarrow T(x) \in T(W)$
 $\Rightarrow T(x) = T(u)$ for some $u \in W$
 $\Rightarrow T(x - u) = 0$
 $\Rightarrow x - u \in \text{Null } T$
 $\Rightarrow x \in W + \text{Null } T$
 $\therefore T^{-1}(T(W)) \subseteq W + \text{Null } T$
or
 $T^{-1}(T(W)) = W + \text{Null } T \rightarrow \textcircled{2}$

proof: The proof is by induction on m .

Step 1: Suppose T is a nilpotent operator with $\eta(T) = 1$. Then $V_1 = \text{span}\{x\}$. s.t. $x \neq 0$
As this is a zero operator
any subspace is T -invariant. $\circ$ operator

$\therefore$ Any complementary subspace of V_1 , then W_1 is invariant under T
and $V = V_1 \oplus W_1$

suppose the theorem is true for any nilpotent operator if index is $m-1$

Step 2: let T be a nilpotent operator with $\eta(T) = m$.
 $V_1 = \text{span}\{x, Tx, \dots, T^{m-1}x\}$
where $T^m(x) \neq 0$

look at $T_1 = T|_{\text{Ran } T} : \text{Ran } T \rightarrow \text{Ran } T$

as $T_1^{m-1}(Ty) = T^{m-1}(Ty) = 0$ (here $Tx = y \in \text{Ran } T$
 $T_1 : \text{Ran } T \rightarrow \text{Ran } T$)

Note: $T_1^{m-2}(Tx) = T^{m-1}(x) \neq 0$

or $\eta(T_1) = m-1$

$T_1 = T|_{\text{Ran } T}$. Here index of nilpotency is $m-1$,

$\exists$ a T -invariant subspace $Y_1 \subseteq \text{Ran } T \subseteq V$ (using induction)
s.t. $\text{Ran } T = Y_1 \oplus Y_2$

$Y_1 = \text{span}\{Tx, T^2x, \dots, T^{m-1}x\}$
 $= \text{span}\{y, Ty, \dots, T^{m-2}y\}$

Claim: $V = V_1 + T^{-1}(Y_2)$ (here $T(V_1) = Y_1$
 $T(V) = T(V_1) \oplus Y_2$)

$V = T^{-1}(\text{Ran } T) = T^{-1}(Y_1 \oplus Y_2) = T^{-1}(Y_1) + T^{-1}(Y_2)$
 $= T^{-1}(T(V_1)) + T^{-1}(Y_2)$

$\textcircled{3} \rightarrow = V_1 + \text{Null } T + T^{-1}(Y_2) = V_1 + T^{-1}(Y_2)$
(from $\textcircled{2}$) (Note: $\text{Null } T \subseteq T^{-1}(Y_2)$)

claim 2: $V_1 \cap Y_2 = \{0\}$

$$\begin{aligned} T(V_1 \cap Y_2) &\subseteq Y_1 \cap Y_2 = \{0\} \\ \Rightarrow V_1 \cap Y_2 &\subseteq V_1 \cap \text{Null } T \\ \Rightarrow V_1 \cap Y_2 &\subseteq V_1 \cap \text{Null } T \\ &= \text{span} \{T^{m-1}x\} \subseteq Y_1 \\ &\quad \& V_1 \cap Y_2 \subseteq Y_2 \\ \Rightarrow V_1 \cap Y_2 &\subseteq Y_1 \cap Y_2 \\ \Rightarrow V_1 \cap Y_2 &= \{0\} \end{aligned}$$

$(T(V_1 \cap Y_2) = T(V_1) \cap T(Y_2) = Y_1 \cap T(Y_2) \subseteq Y_1 \cap Y_2 = \{0\} \Rightarrow T(Y_2) \subseteq Y_2)$

step 3: Now $V = V_1 + T^{-1}(Y_2)$ ($Y_2 \subseteq T^{-1}(Y_2)$, $V_1 \cap T^{-1}(Y_2) \subseteq T^{-1}(Y_2)$ so $\exists Z$)

$$Y_2 \oplus (V_1 \cap T^{-1}(Y_2)) \oplus Z = T^{-1}(Y_2)$$

fact: $v = v_1 \oplus (Y_2 \oplus Z)$ (Note that this is true)

claim 3: $Y_2 \oplus Z$ is T -invariant

$$\begin{aligned} T(Y_2 \oplus Z) &\subseteq T(Y_2) + T(Z) \\ \text{we know } T(Y_2) &\subseteq Y_2 \text{ (already known)} \\ \& T(Z) &\subseteq T(T^{-1}(Y_2)) \subseteq Y_2 \\ \Rightarrow T(Y_2 \oplus Z) &\subseteq Y_2 \subseteq Y_2 \oplus Z \\ \Rightarrow T(Y_2 \oplus Z) &\subseteq Y_2 \oplus Z \end{aligned}$$

$T \cong \begin{bmatrix} J_{m_1} & & 0 \\ & \ddots & \\ 0 & & J_{m_n} \end{bmatrix}$

$\nwarrow$ cyclic $\nearrow$ cyclic
 $m_1 \geq m_2 \geq \dots \geq m_k$

$$\begin{aligned} \therefore v &= v_1 \oplus (Y_2 \oplus Z) \\ &= v_1 \oplus W_1 \\ \text{s.t. } W_1 &\text{ is } T\text{-invariant} \end{aligned}$$

now, $\dim(\text{Null } T) = k$
 $A \in \mathcal{A}(V, V)$

$$\chi_A(t) = (t - \lambda_1)^{d_1} \dots (t - \lambda_r)^{d_r} \quad (\text{characteristic polynomial})$$

$$\rho(t) = (t - \lambda_1)^{s_1} \dots (t - \lambda_r)^{s_r} \quad (\text{minimal polynomial})$$

$$A \cong \begin{bmatrix} A_1 & 0 \\ 0 & A_r \end{bmatrix} \quad \begin{aligned} A_i &= A|_{W_i} \\ W_i &= \text{Null}(A_i - \lambda_i I) \end{aligned}$$

Since $(A_i - \lambda_i I)$ is a nilpotent operator of index s_i

$$\psi \quad A_i - \lambda_i I = \begin{bmatrix} J_{i1} & & 0 \\ & \ddots & \\ 0 & & J_{ik} \end{bmatrix}$$

$$\Rightarrow A_i = \begin{bmatrix} J_{i1} + \lambda_i I & & 0 \\ & \ddots & \\ 0 & & J_{ik} + \lambda_i I \end{bmatrix}$$

$$= \begin{bmatrix} 1 & \lambda_i & & 0 \\ & \ddots & & \\ 0 & & 1 & \lambda_i \end{bmatrix} \leftarrow \text{Jordan blocks corresp. to } \lambda_i$$

28th Oct:

Defⁿ: Let V be a vector space over $\mathbb{R}/\mathbb{C}$. Then an inner product on V is a map

$$\langle \cdot, \cdot \rangle: V \times V \rightarrow \mathbb{R}/\mathbb{C}$$

$$(x, y) \rightarrow \langle x, y \rangle \text{ s.t.}$$

$$(i) \langle \alpha x + \beta y, z \rangle = \alpha \langle x, z \rangle + \beta \langle y, z \rangle, \forall \alpha, \beta \in \mathbb{R}/\mathbb{C}, x, y, z \in V$$

$$(ii) \langle x, y \rangle = \overline{\langle y, x \rangle}$$

$$(iii) \langle x, x \rangle \geq 0, \forall x \neq 0$$

Remark: $\langle x, \alpha y + \beta z \rangle = \overline{\langle \alpha y + \beta z, x \rangle}$
 $= \overline{\alpha \langle y, x \rangle + \beta \langle z, x \rangle}$
 $= \overline{\alpha} \overline{\langle y, x \rangle} + \overline{\beta} \overline{\langle z, x \rangle}$
 $= \overline{\alpha} \langle x, y \rangle + \overline{\beta} \langle x, z \rangle$

Example: (i) $V = \mathbb{R}^n$, $\langle x, y \rangle = \sum_{i=1}^n x_i y_i$ ① trivial
 (dot-product) ② trivial
 ③ $\langle x, x \rangle \geq 0$ (as sum squares)

$$\therefore \langle x, y \rangle = \sum_{i=1}^n x_i y_i \text{ is an inner product}$$

(ii) $V = \mathbb{C}^n$
 $\langle x, y \rangle = \sum_{i=1}^n x_i \overline{y_i}$ ① trivial
 ② $\sum x_i \overline{y_i} = \sum \overline{y_i x_i} = \sum \overline{y_i} \overline{x_i} = \sum \overline{x_i y_i}$
 ③ $\sum x_i \overline{x_i} \geq 0$ as $\Rightarrow \sum (x_i)^2 \geq 0$

$$\therefore \sum x_i \overline{y_i} \text{ is an inner product}$$

(iii) $V = C([0, 1])$

$$\langle f, g \rangle = \int_0^1 f(t) \overline{g(t)} dt$$

① trivial
 ② $\int_0^1 f(t) \overline{g(t)} dt = \int_0^1 \overline{f(t) g(t)} dt$

$$\langle x, y \rangle = \overline{\langle y, x \rangle}$$

$$\textcircled{3} \int_0^1 |f(t)|^2 dt \geq 0$$

$$\therefore \langle f, g \rangle = \int_0^1 f(x) \overline{g(x)} dx \text{ is a inner product}$$

Defⁿ: (i) A vector space V with an inner product is called an inner product space

(ii) Two vectors x and y in an inner product space are orthogonal if $\langle x, y \rangle = 0$

(iii) A set of vectors $\{x_1, \dots, x_n\}$ in V is orthonormal set of vectors if
 Norm $\leftarrow$ ① $\|x_i\| = \langle x_i, x_i \rangle^{1/2} = 1$
 ② $\langle x_i, x_j \rangle = 0 \forall i \neq j$

Lemma: (Cauchy-Schwarz inequality)

in an inner product space V , $|\langle x, y \rangle| \leq \|x\| \|y\|$
 where $\|x\| = \langle x, x \rangle^{1/2}$
 Norm

proof: $\langle x + t\alpha y, x + t\alpha y \rangle \quad t \in \mathbb{R}$

$$= \langle x, x + t\alpha y \rangle + t\alpha \langle y, x + t\alpha y \rangle$$

$$= \langle x, x \rangle + \overline{\alpha} t \langle x, y \rangle + t\alpha \langle y, x \rangle + t^2 \alpha \overline{\alpha} \langle y, y \rangle$$

(assuming x is not a scalar multiple of y)

$$= \|x\|^2 + \overline{\alpha} t \langle x, y \rangle + t\alpha \langle y, x \rangle + t^2 |\alpha|^2 \|y\|^2$$

$$= \|x\|^2 + t [\overline{\alpha} \langle y, x \rangle + \alpha \langle y, x \rangle] + t^2 |\alpha|^2 \|y\|^2$$

$$= \|x\|^2 + t [2 \operatorname{Re}(\alpha \langle y, x \rangle)] + t^2 |\alpha|^2 \|y\|^2$$

$$= \|x\|^2 + 2t \operatorname{Re}(\alpha \langle y, x \rangle) + t^2 |\alpha|^2 \|y\|^2$$

choose α with $|\alpha| = 1$ s.t. $\alpha \langle y, x \rangle = |\langle y, x \rangle|$

then $\langle x + t\alpha y, x + t\alpha y \rangle = \|x\|^2 + 2t |\langle y, x \rangle| + t^2 \|y\|^2 \geq 0 \quad \forall t \in \mathbb{R}$

$$\Rightarrow \Delta \leq 0$$

$$\Rightarrow \cancel{4t^2} |\langle x, y \rangle|^2 \leq \cancel{4t^2} \|x\|^2 \|y\|^2$$

$$\Rightarrow |\langle x, y \rangle| \leq \|x\| \|y\|$$

Lemma: (Triangle inequality) $\|x + y\| \leq \|x\| + \|y\|, \forall x, y \in V$

proof:

$$\|x + y\|^2 = \|x\|^2 + 2 \operatorname{Re} \langle y, x \rangle + \|y\|^2$$

(putting $t\alpha = 1$)

$$\leq \|x\|^2 + \|y\|^2 + 2 |\langle y, x \rangle|$$

$$\leq \|x\|^2 + \|y\|^2 + 2 \|x\| \|y\|$$

$$= (\|x\| + \|y\|)^2$$

Theorem: Let V be a finite dimensional inner product space. If $\{y_1, \dots, y_k\}$ is a linearly independent set of vectors in V , then $\exists$ an orthonormal set of vectors $\{x_1, \dots, x_k\}$ s.t.

(Gram-Schmidt decomposition) $x_i \in \operatorname{span}\{y_1, \dots, y_k\}$
 (or $\exists$ a lin ind orthonormal set spanning $\{y_1, \dots, y_k\}$. If $\operatorname{span}\{y_1, \dots, y_k\}$ is V then the new set is also a basis)

Proof: $\{y_1, \dots, y_k\}$ is a linearly ind set of vectors in V

wlog pick y_1 then

$$x_1 = \frac{y_1}{\|y_1\|} \quad (\text{s.t. } \|x_1\| = 1)$$

now, x_2 s.t. it is unit vector and $\langle x_1, x_2 \rangle = 0$

$$\text{now, } x_2 = \frac{y_2 - \langle y_2, x_1 \rangle x_1}{\|y_2 - \langle y_2, x_1 \rangle x_1\|}$$

as scalar

$$\langle x_2, x_1 \rangle = \langle y_2 - \langle y_2, x_1 \rangle x_1, x_1 \rangle$$

$$= \langle y_2, x_1 \rangle - \langle y_2, x_1 \rangle \langle x_1, x_1 \rangle$$

$$= \langle y_2, x_1 \rangle - \langle y_2, x_1 \rangle$$

$$= 0$$

$\rightarrow \|x_1\|^2$

$$\text{now } x_2 = c \left[y_2 - \langle y_2, x_1 \rangle x_1 \right]$$

now c for which $\langle x_2, x_2 \rangle = 1$
we can find c s.t.
 $\|x_2\| = 1$

suppose that we have chosen $\{x_1, \dots, x_{n-1}\}$ s.t this set is orthonormal

$$\text{then } x_n = \beta \left(y_n - \sum_{i=1}^{n-1} \langle y_n, x_i \rangle x_i \right)$$

$$\begin{aligned} \text{now } \langle x_n, x_j \rangle &= \beta \left\langle y_n - \sum_{i=1}^{n-1} \langle y_n, x_i \rangle x_i, x_j \right\rangle \\ &= \beta \left[\langle y_n, x_j \rangle - \langle y_n, x_j \rangle \right] \\ &= 0 \end{aligned}$$

Choose β accordingly

Lemma: An orthonormal set of vectors is linearly independent

proof: ($\langle x_i, x_i \rangle = 0, \langle x_i, x_i \rangle = 1, \forall i \neq j$)
If $\{x_1, \dots, x_n\}$ is an orthonormal set of vectors and if
 $c_1 x_1 + \dots + c_n x_n = 0$

then taking inner product with x_i

$$\begin{aligned} \langle c_1 x_1 + \dots + c_n x_n, x_i \rangle &= \langle 0, x_i \rangle = 0 \\ &\quad \left(\text{as } \langle 20, x_i \rangle = \langle 0, x_i \rangle + \langle 0, x_i \rangle \right) \\ &\quad \langle 0, x_i \rangle \end{aligned}$$

$$\Rightarrow c_1 \langle x_1, x_i \rangle + \dots + c_n \langle x_n, x_i \rangle = 0$$

$$\Rightarrow c_i \langle x_i, x_i \rangle = 0$$

$$\Rightarrow c_i (1) = 0$$

$$\Rightarrow c_i = 0 \quad \forall i = 1, 2, \dots, n$$

Note: any basis $\rightarrow$ orthonormal basis converse

$$\begin{aligned} y \in V, \langle \cdot, y \rangle: V \times V &\rightarrow \mathbb{C} \\ x &\mapsto \langle x, y \rangle \in \mathbb{C} \\ \therefore \text{linear functional} \end{aligned}$$

Theorem: let V be an inner product space. If f is a linear functional on V then
 $\exists$ a unique vector $y \in V$ s.t.

$$f(x) = \langle x, y \rangle, \forall x \in V$$

proof: let $\{x_1, \dots, x_n\}$ be an orthonormal basis of inner product space V (so it is also a basis of V)

$$\begin{aligned} \text{Suppose } f(x_i) &= \alpha_i, \forall i = 1, 2, \dots, n \\ \text{set } y &= \sum_{i=1}^n \overline{\alpha_i} x_i \end{aligned}$$

$$\begin{aligned} \text{then } \langle x_i, y \rangle &= \langle x_i, \sum_{j=1}^n \overline{\alpha_j} x_j \rangle \\ &= \overline{\alpha_i} \langle x_i, x_i \rangle \\ \langle x_i, y \rangle &= \alpha_i = f(x_i), \forall i = 1, \dots, n \\ \Rightarrow f(x) &= \langle x, y \rangle, \forall x \in V \end{aligned}$$

uniqueness of y : if $\exists y_2$ s.t.
 $f(x) = \langle x, y_2 \rangle$
 $\neq f(x) = \langle x, y \rangle$

$$\begin{aligned}
 \text{then } & \langle x, y \rangle = \langle x, y_2 \rangle \quad \forall x \in V \\
 \Rightarrow & \langle x, y - y_2 \rangle = 0 \quad \forall x \in V \\
 \Rightarrow & \langle y - y_2, y - y_2 \rangle = 0 \\
 \Rightarrow & y - y_2 = 0 \\
 \Rightarrow & y = y_2
 \end{aligned}$$

let U be a subspace of an inner product space V .

$$\begin{aligned}
 U^\perp &= \{ f \in V \mid \langle f, y \rangle = 0 \quad \forall y \in U \} \\
 &= \langle z \in V \mid \langle y, z \rangle = 0 \quad \forall y \in U \rangle
 \end{aligned}$$

$\therefore U^\perp = \text{orthogonal complement of } U$

30th Oct :

Recap:

$$J_n(\lambda) = \begin{bmatrix} \lambda & & 0 \\ & \ddots & \\ 0 & & \lambda \end{bmatrix}_{n \times n} \quad \text{nilpotency index}$$

$$J_n(\lambda) = \begin{bmatrix} \lambda & & 0 \\ & \ddots & \\ 0 & & \lambda \end{bmatrix}_{n \times n}$$

$$T = \begin{bmatrix} 0 & & 0 \\ 1 & \ddots & \\ 0 & & 0 \end{bmatrix}_{n \times n}$$

$$T^n = 0, \quad T^{n-1} \neq 0$$

$$T^{n-1}x \neq 0 \\ T^n x = 0$$

$$\{x, Tx, \dots, T^{n-1}x\}$$

ordered basis then matrix we get is:

$$\text{Jordan form} \leftarrow \begin{bmatrix} \lambda & & 0 \\ & \ddots & \\ 0 & & \lambda \end{bmatrix}$$

Note: $\{T^{n-1}x, \dots, x\}$ ordered basis then

$$\begin{bmatrix} \lambda & & 0 \\ & \ddots & \\ 0 & & \lambda \end{bmatrix} \leftarrow \text{Transpose of Jordan matrix}$$

$V = \{x_1, \dots, x_n\} \leftarrow$ orthonormal basis (ONB) for V
for any $x \in V$,

$$x = \sum_{i=1}^n c_i x_i$$

$$(x = \sum \alpha_i x_i, \text{ but } x_i \perp x_j \forall i \neq j) \\ \text{i.e. } \langle x_i, x_j \rangle = 0$$

$$\text{to find } c_i: \langle x, x_i \rangle = c_i \\ \text{as } \langle x_j, x_i \rangle = 0 \text{ for } i \neq j \\ \text{for } i = j$$

$$\Rightarrow x = \sum_{i=1}^n \langle x, x_i \rangle x_i \quad (\langle x, x_i \rangle = c_i \forall i)$$

$$\text{Note: } x = \sum_{i=1}^n \langle x, x_i \rangle x_i$$

$$\text{now, } \|x\|^2 = \langle x, x \rangle = \left\langle \sum_{i=1}^n \langle x, x_i \rangle x_i, \sum_{i=1}^n \langle x, x_i \rangle x_i \right\rangle$$

$$(\|x\|^2 = \langle x, x \rangle)$$

$$= \sum_{j=1}^n \sum_{i=1}^n \langle x, x_i \rangle \overline{\langle x, x_j \rangle} \langle x_i, x_j \rangle$$

$$= \sum_{i=1}^n \sum_{j=1}^n \langle x, x_i \rangle \overline{\langle x, x_j \rangle} \langle x_i, x_j \rangle$$

$$\|x\|^2 = \sum_{i=1}^n |c_i|^2$$

$$\|x\| = \sqrt{\sum_{i=1}^n |\langle x, x_i \rangle|^2} = \sqrt{\sum_{i=1}^n |c_i|^2}$$

Note: There is a bijection b/w n dimensional (inner space V) and $\mathbb{C}^n$

$$\Psi: V \longrightarrow \mathbb{C}^n \text{ as } \langle x, x_i \rangle \in \mathbb{C}$$

$$x \longmapsto (\langle x, x_1 \rangle, \langle x, x_2 \rangle, \dots, \langle x, x_n \rangle)$$

This is well defined

$$\text{as } x = \sum \langle x, x_i \rangle x_i$$

- ① one-one
- ② onto
- ③ linear

$$\longrightarrow V \cong \mathbb{C}^n$$

$$\left(\begin{array}{l} x = \sum c_i x_i \\ \Psi(x) = (c_0, c_1, \dots, c_n) \end{array} \right)$$

Note: This Ψ preserves the inner product:

$$\text{then } \langle x, x \rangle = \sum |c_i|^2$$

$$= \langle (c_0, c_1, \dots, c_n), (c_0, c_1, \dots, c_n) \rangle$$

$$= \langle \Psi(x), \Psi(x) \rangle$$

$$\text{See down } \leftarrow \begin{array}{l} \langle x, x \rangle = \langle \Psi(x), \Psi(x) \rangle \quad \forall x \in V \\ \langle x, y \rangle = \langle \Psi(x), \Psi(y) \rangle \quad \forall x, y \in V \end{array}$$

Polonising identity:

$$\langle x, y \rangle = \frac{1}{4} \left(\|x+y\|^2 - \|x-y\|^2 + i \|x+iy\|^2 - i \|x-iy\|^2 \right)$$

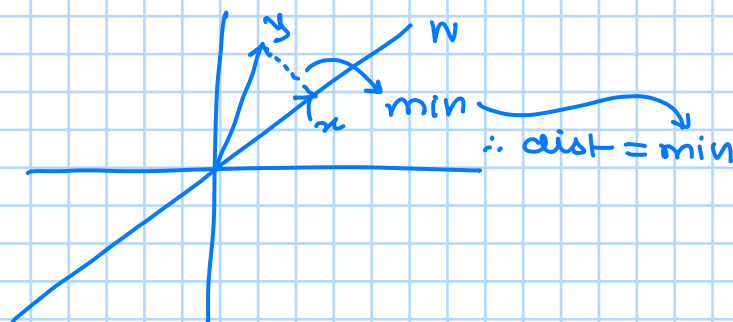
(using this we show $\langle x, y \rangle = \langle \Psi(x), \Psi(y) \rangle$)

Note: upto isomorphism both V & $\mathbb{C}^n$ are same.

Defn: let w be a subspace of an inner product space V . A vector $x \in w$ is a best approximate of $y \in V$ if

$$\|y-z\| \geq \|y-x\| \quad \forall z \in w$$

$$\text{dist}(w, y) = \inf \{ \|z-y\| : \forall z \in w \}$$



note here $y-x \perp w$

Theorem: let w be a subspace of an inner product space V .

(a) Then $x \in w$ is the best approximation of vector y

$$\text{iff } y-x \in w^\perp$$

$$(w^\perp = \{ v \in V \mid \langle v, w \rangle = 0, \forall w \in w \})$$

also called orthocomplement

(b) Best approximation point is unique

(c) if $\{w_1, \dots, w_r\}$ is an ONB for w then the best approximation of w of $y \in V$ is $\sum \langle y, w_i \rangle w_i$

Ex: $w^\perp$ is subspace of V .

$$\text{as } w^\perp = \{ v \in V \mid \langle v, w \rangle = 0, \forall w \in w \} \quad \text{for } v_1, v_2 \in w^\perp$$

$$\langle \alpha v_1 + v_2, w \rangle = \alpha \langle v_1, w \rangle + \langle v_2, w \rangle = \alpha \cdot 0 + 0 = 0 \quad \therefore \alpha v_1 + v_2 \in w^\perp$$

proof : (b) supposing (a)

suppose $x_1, x_2 \in W$
 $\&$ Both are best approx of y
 then $y - x_1 \in W^\perp$
 $\&$ $y - x_2 \in W^\perp$

$$\Rightarrow x_1 - x_2 \in W^\perp$$

also
 $x_1 - x_2 \in W$

(Here this means
 that
 $\langle y - \sum \langle y, w_i \rangle w_i, w_j \rangle = 0$
 $\forall j; \forall w \in W$
 $\therefore \langle y - \sum \langle y, w_i \rangle w_i, w \rangle = 0$
 $\Rightarrow y - \sum \langle y, w_i \rangle w_i \in W^\perp$
 $\Rightarrow \sum \langle y, w_i \rangle w_i$
 is the
 best app. of y)

$$\text{i.e. } \langle x_1 - x_2, x_1 - x_2 \rangle = 0$$

$$\Rightarrow x_1 - x_2 = 0$$

$$\Rightarrow x_1 = x_2$$

(c) $y - \sum_{i=1}^r \langle y, w_i \rangle w_i \in W^\perp$
 then we
 are done

$$\langle y - \sum \langle y, w_i \rangle w_i, w_j \rangle$$

$$= \langle y, w_j \rangle - \langle y, w_j \rangle$$

$$= 0$$

$$\forall j = 1, 2, \dots, r$$

$\therefore y - \sum \langle y, w_i \rangle w_i$ is orthogonal
 to all w_j
 $\Rightarrow$ orthogonal
 to linear combination
 of w_j
 $\Rightarrow$ orthogonal to $x, \forall x \in W$

$$\forall x \in W$$

$$\therefore \langle y - \sum \langle y, w_i \rangle w_i, x \rangle = 0$$

$$\Rightarrow y - \sum \langle y, w_i \rangle w_i \in W^\perp$$

$\Rightarrow \sum \langle y, w_i \rangle w_i$ is best approximation by
 part (a)

$$(a) \|y - z\| \geq \|y - x\| \quad \forall z \in W$$

$$\|y - z\|^2 = \|(y - x) + (x - z)\|^2$$

$$= \langle (y - x) + (x - z), (y - x) + (x - z) \rangle$$

$$= \|y - x\|^2 + \|x - z\|^2 + 2\operatorname{Re} \langle x - z, y - x \rangle$$

$$\geq \|y - x\|^2$$

$\Leftrightarrow$

$$\|x - z\|^2 + 2\operatorname{Re} \langle y - x, x - z \rangle \geq 0$$

$$\forall z \in W$$

$x - z \in W \leftarrow$ gives an vector
 $\forall w \in W,$
 $\langle y - x, x - z \rangle = \langle y - x, w \rangle$
 for $x - z = w$
 as $\forall z \in W$
 w also spans W

$$\Leftrightarrow \| \alpha \|^2 + 2 \operatorname{Re} \langle y - x, \alpha \rangle \geq 0 \quad \forall \alpha \in W$$

this is only possible for $\forall \alpha \in W$

$$\begin{aligned} \langle y - x, \alpha \rangle &= 0 \\ \Rightarrow y - x &\in W^\perp \end{aligned}$$

(x is best app
iff
 $\| \alpha \|^2 + 2 \operatorname{Re} \langle y - x, \alpha \rangle \geq 0$
 $\forall \alpha \in W$)

so if $2 \operatorname{Re} \langle y - x, \alpha \rangle$ is non-zero

then can
we come up
with α s.t

$$\left(\begin{aligned} &\| \alpha \|^2 + 2 \operatorname{Re} \langle y - x, \alpha \rangle \geq 0 \\ &\text{iff} \\ &\langle y - x, \alpha \rangle = 0 \end{aligned} \right)$$

$$\begin{aligned} \| \alpha \|^2 + 2 \operatorname{Re} \langle y - x, \alpha \rangle &\text{ is } \\ &\text{less than zero} \\ 2 \operatorname{Re} \langle y - x, \alpha \rangle &= -\| \alpha \|^2 \end{aligned}$$

$$\alpha = - \frac{\langle y - x, \alpha \rangle}{\| \alpha \|^2} \alpha$$

($\alpha = - \frac{\langle y - x, \alpha \rangle}{\| \alpha \|^2} \alpha$
is counter example)

$$\text{so } \frac{\| \alpha \|^2}{-2 \operatorname{Re} \langle y - x, \alpha \rangle} = \frac{|\langle y - x, \alpha \rangle|^2 \| \alpha \|^2}{\| \alpha \|^4}$$

$$-2 \operatorname{Re} \left\langle y - x, \frac{\langle y - x, \alpha \rangle}{\| \alpha \|^2} \alpha \right\rangle$$

$$= \frac{|\langle y - x, \alpha \rangle|^2}{\| \alpha \|^2} - 2 \operatorname{Re} \frac{\langle y - x, \alpha \rangle \langle y - x, \alpha \rangle}{\| \alpha \|^2}$$

$$= \frac{|\langle y - x, \alpha \rangle|^2}{\| \alpha \|^2} - \frac{2 |\langle y - x, \alpha \rangle|^2}{\| \alpha \|^2}$$

$$< 0$$

$$\therefore y - x \in W$$

ex: polarising identity

$$\| x + y \|^2 = \langle x + y, x + y \rangle$$

$$= \langle x, x + y \rangle + \langle y, x + y \rangle$$

$$= \langle x + y, x \rangle + \langle x + y, y \rangle$$

$$= \langle y, x \rangle + \langle x, y \rangle + \langle x, y \rangle + \langle y, y \rangle$$

$$\| x + y \|^2 = \| x \|^2 + \| y \|^2 + 2 \operatorname{Re} \langle x, y \rangle$$

sim

$$\| x - y \|^2 = \| x \|^2 + \| y \|^2 - 2 \operatorname{Re} \langle x, y \rangle$$

$$4 \operatorname{Re}(\langle x, y \rangle) = \| x + y \|^2 - \| x - y \|^2$$

and

$$\operatorname{Re} \langle x, y \rangle + i \operatorname{Im} \langle x, y \rangle = \langle x, y \rangle$$

$$\text{where } \operatorname{Im} \langle x, y \rangle = \operatorname{Re}(-i \langle x, y \rangle)$$

$$\text{note } 4 \operatorname{Re} \langle x, iy \rangle = \| x + iy \|^2 - \| x - iy \|^2$$

$$\text{then } \operatorname{Re} \langle x, iy \rangle = \frac{1}{4} [\|x + iy\|^2 - \|x - iy\|^2] = \operatorname{Im} \langle x, y \rangle$$

$$\operatorname{Re} \langle x, y \rangle = \frac{1}{4} [\|x + y\|^2 - \|x - y\|^2]$$

$$\Rightarrow \langle x, y \rangle = \frac{1}{4} \left[i^0 \|x + i^0 y\|^2 + i^1 \|x + i^1 y\|^2 + i^2 \|x + i^2 y\|^2 + i^3 \|x + i^3 y\|^2 \right]$$

$$\langle x, y \rangle = \frac{1}{4} \sum_{n=0}^3 i^n \|x + i^n y\|^2$$

Ans: $\langle x, y \rangle = \langle \psi(x), \psi(y) \rangle$ using polarising identity

$$x = \sum a_i \omega_i \quad \text{where } \omega_i \perp \omega_j \quad \forall \quad i \neq j$$

$$y = \sum b_i \omega_i$$

$$\text{now } \psi(x) = (a_0, a_1, \dots, a_n)$$

$$\psi(y) = (b_0, b_1, \dots, b_n)$$

$$\langle x, y \rangle = \frac{1}{4} \sum_{c=0}^3 i^c \|x + i^c y\|^2$$

$$\text{now } \|\psi(x)\|^2 = \sum a_i^2$$

$$\begin{aligned} \|\psi(x) + i^c \psi(y)\|^2 &= \sum (a_i^2 + i^c b_i^2 + 2i^c a_i b_i) \\ &= \sum a_i^2 + (i^c)^2 \sum b_i^2 + 2i^c \sum a_i b_i \\ &= \langle x, x \rangle + (i^c)^2 \langle y, y \rangle + 2i^c \langle x, y \rangle \end{aligned}$$

$$\begin{aligned} \text{now } \frac{1}{4} & \left[\cancel{\langle x, x \rangle} + (1) \cancel{\langle y, y \rangle} + 2 \langle x, y \rangle \right. \\ & + (i) (\cancel{\langle x, x \rangle} + (-1) \cancel{\langle y, y \rangle} - 2 \cancel{\langle x, y \rangle}) \\ & + (-1) (\cancel{\langle x, x \rangle} + (1) \cancel{\langle y, y \rangle} + 2 \langle x, y \rangle) \\ & \left. + (i) (\cancel{\langle x, x \rangle} + (-1) \cancel{\langle y, y \rangle} - 2 \cancel{\langle x, y \rangle}) \right] \\ &= \langle \psi(x), \psi(y) \rangle \\ &= \langle x, y \rangle \quad (\text{after meaning}) \end{aligned}$$

$$\Rightarrow \langle x, y \rangle = \langle \psi(x), \psi(y) \rangle$$

4th Nov:

Recall: $W \subseteq V$ - inner product space

$\beta \in W$ is best app. to $\alpha \in V$ by vector in $W \Leftrightarrow \alpha - \beta \in W^\perp$

Note: $\{\alpha_1, \dots, \alpha_n\}$ is ONB for W , then $\beta = \sum \langle \alpha, \alpha_i \rangle \alpha_i$

β is unique

Best app $\alpha \in V$

now, $W \oplus W^\perp = V$ $\left(\begin{array}{l} \alpha = \beta + (\alpha - \beta) \\ \beta \in W \\ \alpha - \beta \in W^\perp \end{array} \right)$
as β is unique

$(W \oplus W^\perp \text{ is where } \forall \alpha \in V \text{ we have } \beta \text{ (unique) s.t. } \alpha = \beta + (\alpha - \beta) \in W \oplus W^\perp)$

if ONB of $W = \{\alpha_1, \dots, \alpha_n\}$

ONB of $W^\perp = \{\alpha_1, \dots, \alpha_m\}$

then $\text{ONB}_{W \cup W^\perp} = \{\alpha_1, \dots, \alpha_n, \alpha_1, \dots, \alpha_m\} = \text{ONB for } V$

Note: $\forall \alpha \in V \Rightarrow \alpha \in W \oplus W^\perp$

or $\alpha = \sum_{i=1}^n \langle \alpha, \alpha_i \rangle \alpha_i + \sum_{j=1}^m \langle \alpha, \alpha_j \rangle \alpha_j$

let $E_W: V \rightarrow V$

s.t. $E_W(\alpha) = E_W(\sum \langle \alpha, \alpha_i \rangle \alpha_i + \sum \langle \alpha, \alpha_j \rangle \alpha_j)$

$= \sum_{i=1}^n \langle \alpha, \alpha_i \rangle \alpha_i \leftarrow \text{This is also the best approximation to } \alpha \text{ by vectors in } W$

Ex: $E_W^2 = E_W$ or E_W is a projection

$E_W(E_W(\alpha)) = E_W(\alpha)$ as $E_W(\alpha) \in W$ & $E_W(w) = w$

Ex: $\text{Ran } E_W = W$ & $\text{Ker } E_W = W^\perp$

$\text{Ran } E_W = W$ as $\forall w \in W, E_W(w) = w$ & $\text{Ker } E_W = W^\perp$ (trivial)

Note: There is a bijective correspondence b/w subspaces of V and orthogonal projections (This bijection only exist in orthogonal projections)
 $E^2 = E$ (projection)

Defn: orthogonal projection on an inner product space is a projection E with nullspace of E :

$$\text{null } E = (\text{Ran } E)^\perp$$

Example: $E_W: V \rightarrow V$

then $\text{Ran } E_W = W$

(orthogonal proj $\perp$)
 $(\text{null } E_W = (\text{Ran } E_W)^\perp)$

$\text{null } E_W = W^\perp = (\text{Ran } E_W)^\perp$

Note: if $\ell \in V'$ (or $\alpha(V, \mathbb{R})$) ($\ell \in \{T: V \rightarrow \mathbb{R} \mid T \text{ is linear}\}$) or $\ell: V \rightarrow \mathbb{R}$ $\hookrightarrow$ linear
then $\exists y \in V$ s.t. $\ell(x) = \langle x, y \rangle \quad \forall x \in V$

$$T: X \rightarrow Y$$

$$T': Y' \rightarrow X'$$

$$T'(\theta)(x) = \theta(Tx)$$

$$\uparrow \quad \forall \theta \in Y'$$

$$x \in X$$

$$x \xrightarrow{T} Tx \xrightarrow{\theta} \theta(Tx)$$

$$T': \theta \mapsto \theta \circ T$$

$$T': \theta \mapsto \theta \circ T$$

$$(\ell(x) = \langle x, y \rangle \in \mathbb{R})$$

$$T: X \rightarrow Y$$

$$T': Y' \rightarrow X'$$

$$T'(\theta)(x) = \theta(Tx)$$

$$\in Y'$$

$$\text{as } \theta \circ T(x) \text{ is}$$

$$\theta: Y \rightarrow \mathbb{R} \quad T: X \rightarrow Y$$

$$\theta \circ (Tx): X \rightarrow \mathbb{R}$$

Theorem: let V be an inner product space and T be linear map on V then there is a unique linear map (adjoint of T)

$$(\langle Tx, y \rangle = \langle x, T^*y \rangle)^{\text{unique}}$$

$$\text{s.t. } \langle Tx, y \rangle = \langle x, T^*y \rangle \quad \forall x, y \in V$$

$$T^*: V \rightarrow V$$

proof: $x \mapsto \langle Tx, y \rangle$ (This is a linear functional on V for fixed $y \in V$)

Then By Riesz representation theorem

$$f: x \mapsto \langle Tx, y \rangle$$

$\exists$ a unique $z \in V$ s.t.

set $z = T^*y$ then $f(x) = \langle x, z \rangle = \langle Tx, y \rangle \forall x \in V$

we have to check that $\tilde{f}: V \rightarrow V$ is well defined

$y \mapsto z$

T^* is linear map: for $\alpha_1 y_1 + \alpha_2 y_2 \in V$

$$\begin{aligned} \langle x, T^*(\alpha_1 y_1 + \alpha_2 y_2) \rangle &= \langle Tx, \alpha_1 y_1 + \alpha_2 y_2 \rangle = \alpha_1 \langle Tx, y_1 \rangle + \alpha_2 \langle Tx, y_2 \rangle \\ &= \langle x, \alpha_1 T^*(y_1) + \alpha_2 T^*(y_2) \rangle \end{aligned}$$

$$\langle x, T^*(\alpha_1 y_1 + \alpha_2 y_2) \rangle = \langle x, \alpha_1 T^*(y_1) + \alpha_2 T^*(y_2) \rangle$$

$\therefore T^*$ is linear

Also see that $T^* \approx T'$ for the case of

$T'(0)(x) = Q(Tx)$

here $y \in V \leftrightarrow Q_y(x) = \langle x, y \rangle$ (fixed)

$$Q_y(Tx) = \langle Tx, y \rangle$$

$$Q_{T^*y}(x) = \langle x, T^*y \rangle$$

$$\begin{aligned} \text{as } T'(0)(x) &= Q(Tx) \\ Q_{T^*y}(x) &= Q_y(Tx) \end{aligned}$$

$$\text{as } Q_y(Tx) = (Q_y \circ T)(x)$$

$V \xrightarrow{T} V \xrightarrow{Q_y} F$

$$\begin{aligned} 0 &\mapsto 0 \circ T \\ Q_{T^*y}(x) &= (Q_y \circ T)(x) \end{aligned}$$

Note: $T: V \rightarrow V$

$\{x_1, \dots, x_n\} \rightarrow$ ONB for V

$$A = \begin{bmatrix} | & | & | \\ T(x_1) & T(x_2) & \dots & T(x_n) \\ | & | & | \end{bmatrix}_{n \times n}$$

matrix rep

as $\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}_{n \times 1}$

$$T(x_i) = \sum_j \langle T(x_i), x_j \rangle x_j$$

$$A_{ji} = \langle T(x_i), x_j \rangle$$

A looks like:

$$\begin{bmatrix} \langle T(x_1), x_1 \rangle & \dots & \langle T(x_n), x_1 \rangle \\ \langle T(x_1), x_2 \rangle & \dots & \langle T(x_n), x_2 \rangle \\ \vdots & & \vdots \\ \langle T(x_1), x_n \rangle & \dots & \langle T(x_n), x_n \rangle \end{bmatrix}$$

$$\left(\begin{array}{l} \text{as } T: V \rightarrow V \\ x \mapsto T(x) \\ T(x_i) = \sum \langle T(x_i), x_j \rangle x_j \\ A_{ij} = \langle T(x_i), x_j \rangle \end{array} \right)$$

propn: let V be an inner product space $^{n \times n}$ on $T: V \rightarrow V$ be a linear map. let $\{x_1, \dots, x_n\}$ be an ONB for V . Then the matrix rep of T^* corresponding to $\{x_1, \dots, x_n\}$ is conjugate transpose of the matrix rep of T w.r.t $\{x_1, \dots, x_n\}$.

proof:

$$\begin{aligned} T_{ji}^* &= \langle T^*(x_i), x_j \rangle \\ &= \overline{\langle x_j, T^*(x_i) \rangle} \end{aligned}$$

$$\left(\begin{array}{l} J_{ji}^* = \langle T^*(x_i), x_j \rangle \\ = \overline{\langle x_j, T^*(x_i) \rangle} \\ = \overline{\langle T(x_j), x_i \rangle} \end{array} \right)$$

$$T_{ji}^* = \overline{\langle T(x_j), x_i \rangle} = \overline{T_{ij}}$$

$$\text{other transpose: } T_{ij}^* = \langle T^*(x_j), x_i \rangle$$

$$\Rightarrow T_{ij} = \langle T(x_j), x_i \rangle$$

$$\Rightarrow \overline{T_{ij}} = \overline{\langle T(x_j), x_i \rangle}$$

Defn: A linear map $T: V \rightarrow V$ is self-adjoint if $T^* = T$

6th Nov:

Exercise: (i) $(T_1 + T_2)^* = T_1^* + T_2^*$ $\langle (T_1 + T_2)\alpha | \beta \rangle = \langle \alpha | (T_1 + T_2)^* \beta \rangle$
 (ii) $(T^*)^* = T$ $\Rightarrow \langle \alpha | T^* \beta \rangle + \langle \alpha | T^* \beta \rangle = \langle \alpha | (T_1 + T_2)^* \beta \rangle$
 (iii) $(\lambda T)^* = \bar{\lambda} T^*$

defn: A linear map T on an inner operator is normal if $T T^* = T^* T$ (defn for normal)

eg: (i) unitary map on IPS (inner product space)

$T: V \rightarrow V$ is unitary if

$$\|T\alpha\| = \|\alpha\|$$

$$\Leftrightarrow \langle T\alpha, T\beta \rangle = \langle \alpha, \beta \rangle \quad \forall \alpha, \beta \in V$$

$$\Leftrightarrow \langle \alpha, T^* T \beta \rangle = \langle \alpha, \beta \rangle \quad \forall \alpha, \beta \in V$$

$$\Leftrightarrow \langle \alpha, (T^* T - I) \beta \rangle = 0 \quad \forall \alpha, \beta \in V$$

$$\Leftrightarrow T^* T = I$$

$$\text{as } \forall \alpha \quad \langle \alpha, \beta \rangle = 0 \Rightarrow \beta = 0$$

Orthogonal to all α

$$\Leftrightarrow T^* T = I = T T^* \Leftrightarrow T^* = T^{-1}$$

(Note: Normal $\Rightarrow \exists$ Basis s.t. $P^* T P = \Lambda$ $\rightarrow$ diag)

(unitary: $\|T\alpha\| = \|\alpha\|$
 $\langle T\alpha | T\beta \rangle = \langle \alpha | \beta \rangle$
 $T^* T = T T^* = I$)

$$T = \begin{bmatrix} c_1 & \dots & c_n \end{bmatrix}$$

$$T^* = \begin{bmatrix} \bar{c}_1 \\ \bar{c}_2 \\ \vdots \\ \bar{c}_n \end{bmatrix} \leftarrow \text{conjugate transpose (adjoint)}$$

$\therefore$ unitary $\Rightarrow$ Normal

$$\begin{bmatrix} \bar{c}_1 \\ \vdots \\ \bar{c}_n \end{bmatrix} \begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix} = I$$

$$\begin{bmatrix} \bar{c}_1 c_1 & \bar{c}_1 c_2 & \dots & \bar{c}_1 c_n \\ \vdots & \vdots & \ddots & \vdots \end{bmatrix} = I$$

$$A_{ij} = \bar{c}_i c_j$$

$$[\delta_{ij}] = [A_{ij}]$$

δ_{ij} is s.t. $i=j \Rightarrow 1$
 else 0

$U \leftarrow$ unitary, every column $\leftarrow$ ONB

Note: $\bar{c}_i \cdot c_j = \langle c_j, c_i \rangle = \delta_{ij}$

$$\Rightarrow \text{if } i=j \text{ then } \langle c_i, c_j \rangle = 1 \text{ else } \langle c_i, c_j \rangle = 0$$

or $\{c_1, c_2, \dots, c_n\}$ ONB

Note: A matrix is unitary iff the column vectors of the matrix is ONB
 $(U^* U = U U^* = I \Leftrightarrow B = \{c_1, \dots, c_n\}$ is ONB

defn: we say two linear maps T_1 and T_2 on an IPS are unitary equivalent if $\exists$ a unitary map on V s.t.

unitary eq if

$$U^* T_1 U = T_2$$

$$U \text{ is unitary} \Rightarrow U^* = U^{-1} \quad U^* T_1 U = T_2$$

$\rightarrow$ ONB or with

$$U^{-1} T_1 U = T_2 \leftarrow \text{orthonormal basis}$$

orthonormal basis

instead of normal basis transformation

Lemma 1: Let T be a normal map on IPS V . If x is an eigenvector of T with eigenvalue λ then x is an eigenvector of T^* with eigenvalue $\bar{\lambda}$.

Proof:

$$\begin{aligned} \langle T T^* y, y \rangle &= \langle T^* T y, y \rangle \quad \forall y \in V \\ \Leftrightarrow \langle T^* y, T^* y \rangle &= \langle T y, T y \rangle \\ \Leftrightarrow \|T^* y\| &= \|T y\| \end{aligned}$$

$\leftarrow$ eigenvalue of T

$$\begin{aligned} T x &= \lambda x \\ \text{then } \langle T x | x \rangle &= \langle \lambda x | x \rangle \\ &= \langle x | T^* x \rangle \\ &= \langle x | \bar{\lambda} x \rangle \\ \text{or } T^* x &= \bar{\lambda} x \end{aligned}$$

Ex: If T is normal $\Rightarrow T - \lambda I$ is normal $\lambda \in \mathbb{C}$

① $\|T^* y\| = \|T y\|$

$\|T^* y\| = \|T y\|$

② $\|(T - \lambda I)x\| = \|(T - \lambda I)^* x\| = \|(T^* - \bar{\lambda} I)x\|$

$0 = \|(T - \lambda I)x\| = \|(T - \lambda I)^* x\|$

$((T - \lambda I)^* = T^* - \bar{\lambda} I)$

as $T - \lambda I$ is normal

$= \|T^* - (\lambda I)^* x\|$

$(T - \lambda I)(T^* - \bar{\lambda} I) \|T - \lambda I x\| = \|T^* - \bar{\lambda} I x\|$

$= T T^* + \lambda \bar{\lambda} I \Rightarrow (T^* - \bar{\lambda} I)x = 0$

$- \lambda T^* - \bar{\lambda} I$

or $\bar{\lambda}$ is eigenvalue of T^* (eigenvector)

$(T^* - \bar{\lambda} I)(T - \lambda I) = T^* T - \lambda T^* - \bar{\lambda} T + \bar{\lambda} \lambda I$ (then use ①)

Lemma 2: Let T be a linear map on IPS V . If W is an invariant subspace for T then $W^\perp$ is invariant for T^* .

Proof:

$V = W \oplus W^\perp$ $(T: V \rightarrow V)$ $T(W) \subseteq W$

then $T^*(W^\perp) \subseteq W^\perp$

for $x \in W^\perp$,

$e \in W^\perp \in W$

now as $\forall x \in W \Rightarrow T(x) \in W$

$\langle T^* x, y \rangle = \langle x, T y \rangle \quad \forall y \in W$

$= 0$

since $T y \in W$

$\Rightarrow T^* x \in W^\perp$

$\therefore \forall x \in W^\perp \Rightarrow T^* x \in W^\perp$

we have

$\langle T x | y \rangle = 0 \Rightarrow \langle x | T^* y \rangle = 0$

$e \in W \in W^\perp$

$\Rightarrow T^* y \in W^\perp$

Theorem: Let T be a linear map on an IPS V . Then $\exists$ an ONB of V s.t the matrix rep. of T w.r.t ONB is upper triangular.

Application:

Let $T \in M_{n \times n}(\mathbb{C})$ be a normal

$\exists$ unitary matrix U s.t

$T: V \rightarrow V$

$\exists$ ONB of V s.t

$U^* T U = \text{Upper triagle}$

$A = U^* T U$ is upper triangular

$A^* A = (U^* T U)^* (U^* T U)$

$= U^* T^* U U^* T U$

$= U^* T T^* U$

$= (U^* T U) (U^* T^* U)$

$= A A^*$

if T is normal, then $\exists U^* T U = A$

upper triagle

$A A^* = A^* A$

$\Rightarrow A$ is normal

Ex: $(U^* T U)^* = U^* T^* U$ or $(AB)^* = B^* A^*$

as $(AB)^* = B^* A^*$

$\langle AB x | y \rangle = \langle x | (AB)^* y \rangle$

$= \langle B x | A^* y \rangle$

$= \langle x | B^* A^* y \rangle = \langle x | (AB)^* y \rangle$

A

$= [A_{ij}]$

$A_{ij} = 0 \quad \forall i > j$

upper triangular

$$= \begin{bmatrix} A_{11} & & & \\ & \ddots & & \\ 0 & & A_{nn} & \\ & & & \ddots \end{bmatrix}_{n \times n}$$

since $A e_i = A_{ii} e_i$
 $A^* e_i = \bar{A}_{ii} e_i$

$$A^* = \begin{bmatrix} \bar{A}_{11} & 0 & \dots & 0 \\ \bar{A}_{12} & & & \\ \vdots & & & \\ \bar{A}_{ni} & & & \bar{A}_{nn} \end{bmatrix}_{n \times n}$$

A is normal and also upper triangular
 $A A^* = A^* A$

But as $A^* e_1 = \bar{A}_{11} e_1 \Rightarrow A_{1j} = 0 \quad \forall j > 1$
 similar

$$\left. \begin{aligned} A e_2 &= A_{22} e_2 \\ A^* e_2 &= \bar{A}_{22} e_2 \end{aligned} \right\} \Rightarrow A_{2j} = 0 \quad \forall j \neq 2$$

If we repeat this, we get

$$A = \begin{bmatrix} A_{11} & & 0 \\ & A_{22} & \\ 0 & & \ddots \\ & & & A_{nn} \end{bmatrix}_{n \times n}$$

$\therefore A$ is diagonal

$$A = U^* T U$$

Theorem: (Spectral theorem for Normal matrices) If $T \in M_{n \times n}(\mathbb{C})$ is a normal matrix, then $\mathbb{C}^n$ has an ONB consisting of eigenvectors of T .

proof: If $\dim T = 1$ then the theorem holds true. Suppose that the theorem is also true for all inner product spaces with $\dim$ less than $\dim V$.

Suppose that λ is an eigenvalue of T^* with eigenvector x .

$$\text{Set } W = \text{span} \{x\} \subseteq V$$

then W is an invariant subspace for T^*

then from previous lemma

$W^\perp$ is invariant under $(T^*)^* = T$

$$T_1 = T|_{W^\perp} : W^\perp \rightarrow W^\perp$$

since $\dim(W^\perp) < \dim(V)$

then By induction hypothesis,

$W^\perp$ has an orthonormal basis $\{x_1, \dots, x_{n-1}\}$ (say)

s.t.

T_1 is upper triangular wrt $\{x_1, \dots, x_{n-1}\}$

Consider the orthonormal basis

$$\left\{ x_1, \dots, x_{n-1}, \frac{x}{\|x\|} \right\} \text{ for } V$$

$$\downarrow$$

$$x / \|x\| \text{ is unit}$$

$$\text{as } V = W \oplus W^\perp$$

$$\hookrightarrow \text{ONB of } V = \text{ONB } W \cup \text{ONB } W^\perp$$

Claim: T is upper triangular wrt $\left\{ x_1, \dots, x_{n-1}, \frac{x}{\|x\|} \right\}$

$$T_1(x_j) = T(x_j) = *x_1 + \dots + *x_{n-1} + 0 \cdot x$$

$$\forall j = 1, \dots, n-1$$

↑
upper
triangular

$$\text{so } \begin{bmatrix} * & \dots & * \\ 0 & \dots & 0 \\ \vdots & & \vdots \\ 0 & \dots & 0 \end{bmatrix} = \begin{bmatrix} * & \dots & * \\ 0 & \ddots & * \\ & & * \end{bmatrix}_{n \times n}$$

Always upper triangular

Self adjoint matrix:

$$A^* = A$$

Note: Self-adjoint matrices has only real eigenvalues.

Real self-adjoint matrices have real eigenvector.

Ex: All the eigenvalues of a unitary matrix are uni-modular.

$$\text{As } U^*U = I = U^*U$$

also

$$\|U\alpha\| = \|\alpha\|$$

$$\Rightarrow \|\lambda\alpha\| = \|\alpha\|$$

$$\Rightarrow |\lambda| \|\alpha\| = \|\alpha\|$$

$$\Rightarrow |\lambda| = 1$$

$\therefore$ every eigenvalue of U is unimodular

Also T is normal then $\exists P$ s.t

$$P^* T P = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

ONB

eigenvalues of T

now, λ is eigenvalue of T^*

$$(P^* T^* P) = \begin{bmatrix} \lambda_1^* & & 0 \\ & \ddots & \\ 0 & & \lambda_n^* \end{bmatrix}$$

$$\text{if } (P^* T^* P)^* = P^* (P^* T^*)^* = P^* (T P)$$

$$= \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

$$P^* T^* P = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}^* = \begin{bmatrix} \bar{\lambda}_1 & & 0 \\ & \ddots & \\ 0 & & \bar{\lambda}_n \end{bmatrix}$$

$$\text{now } T = T^* \Rightarrow \lambda_1 = \bar{\lambda}_1 \Rightarrow \lambda_i = \bar{\lambda}_i \forall i \Rightarrow \lambda_i \text{ are real}$$

